



---

# ***ISS Design Analysis Cycle 8 Environment Predictions***

**Microgravity Environment Interpretation Tutorial  
NASA Glenn Research Center  
March 6-8, 2001**

**Steve Del Basso**

**Structural Analysis Microgravity Team**

**Boeing**

**502 Gemini Avenue**

**Houston, Texas**

**281-853-1603**



## Presentation Overview

---

---

- **Design Analysis Cycle**
- **Analysis Methods**
- **Active Rack Isolation System**
- **Disturbance Forcing Functions**
- **Quasi-steady Accelerations**
- **Vibratory Accelerations**



## Design Analysis Cycle (DAC) 8

---

DACs may be viewed as PDR/CDR level analyses or “special” case studies.

- DAC8 was completed in winter 1999.
- DAC9 is in process with results expected summer of 2001.
- DACs capture updated models & disturbance forcing functions.

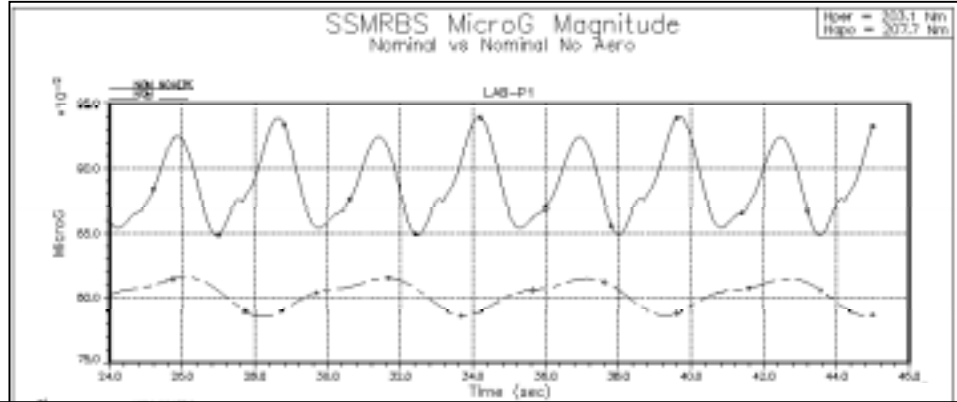
Verification Analysis Cycles (VACs) are in process and are conducted on a flight by flight basis.

- Verify that the hardware launched complies with Assembly Complete microgravity requirements.
- Priority tasks necessary for Certification of Flight Readiness.

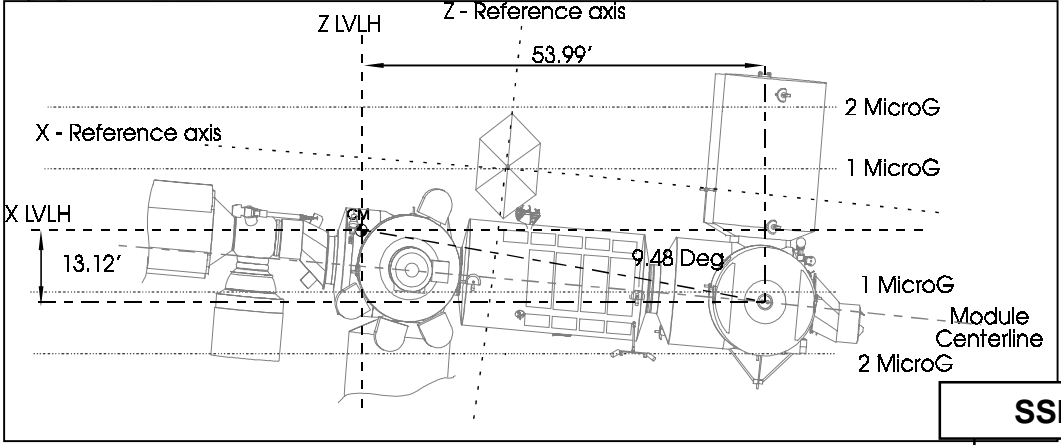
Microgravity sustaining engineering efforts underway.

- Use of on-orbit measurements for issue resolution, uncertainty reduction, analytical model correlation.
- Support anomaly resolution and operations.

# Methods & Tools Quasi-Steady Analysis



- Below 0.01 Hz**
- Orbital Mechanic Multi-Rigid Body Closed Loop Attitude Control Analysis
  - Space Station Multi Rigid Body Simulation (NASA SPARC)
  - SSMRBS used for GN&C Software Verification



$$\vec{a} = -\mu \left( \frac{\vec{r}_p}{r_p^3} - \frac{\vec{r}_g}{r_g^3} \right) - \vec{\omega} \times \left( \vec{\omega} \times \vec{r}_{p/g} \right) - \dot{\vec{\omega}} \times \vec{r}_{p/g} + \vec{a}_D$$

Gravity Gradient
Centripetal
Tangential
Aerodynamic Drag

**SSMRBS Environment Data Validation**

**verify\_gfield  
(gravity)**

ADA Advanced Simulation Development System (ASDS)  
Gravitational Potential (GOTPOT) model

**verify\_bfield  
(magnetic)**

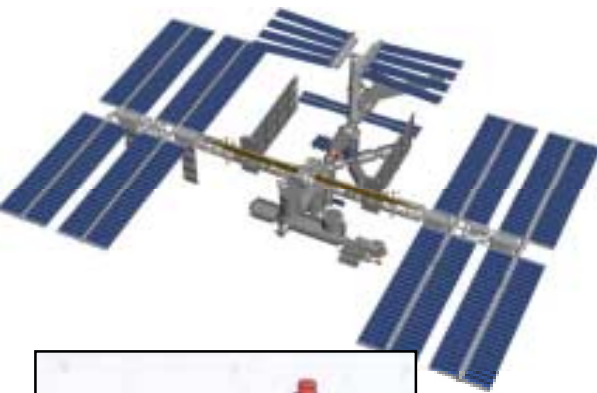
Goddard Space Flight Center International Geophysical Reference Field (IGRF) Earth Magnetic model

**verify\_atm\_density  
(density)**

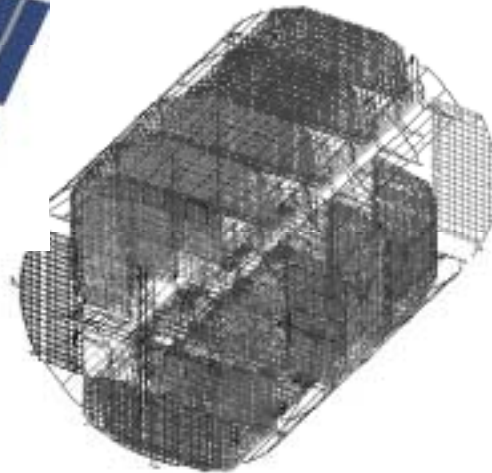
Marshall Engineering Thermosphere (MET) Earth Atmospheric Density model

# Methods & Tools

## Structural Dynamic Analysis



Enhanced COF Model

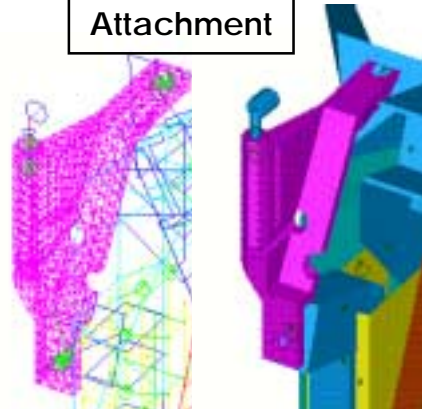


Lower Pivot



Non-isolated Rack I/F

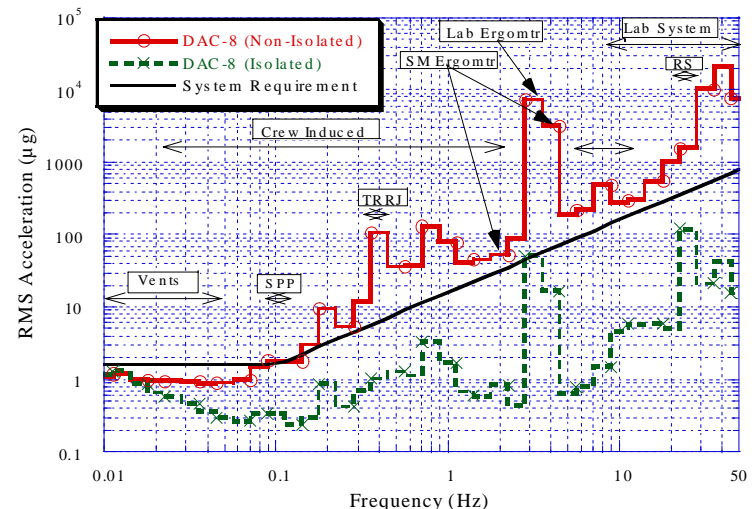
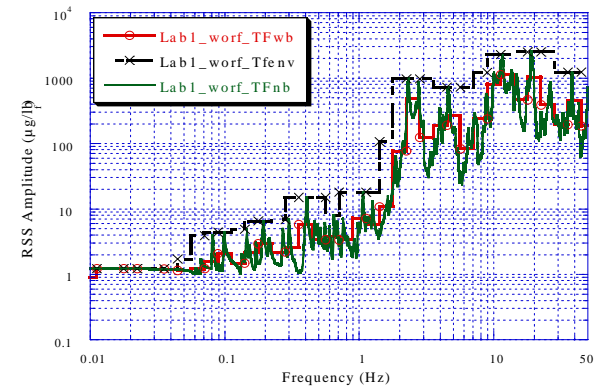
Rack KBAR Attachment



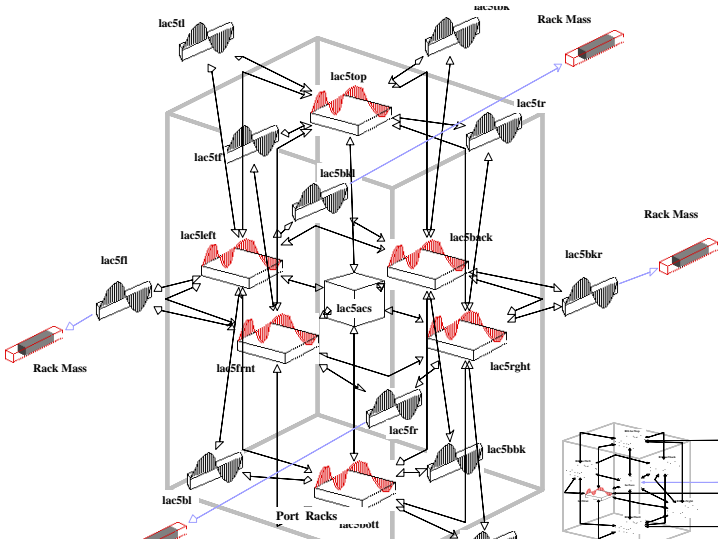
Upper KBAR

March 8, 2001

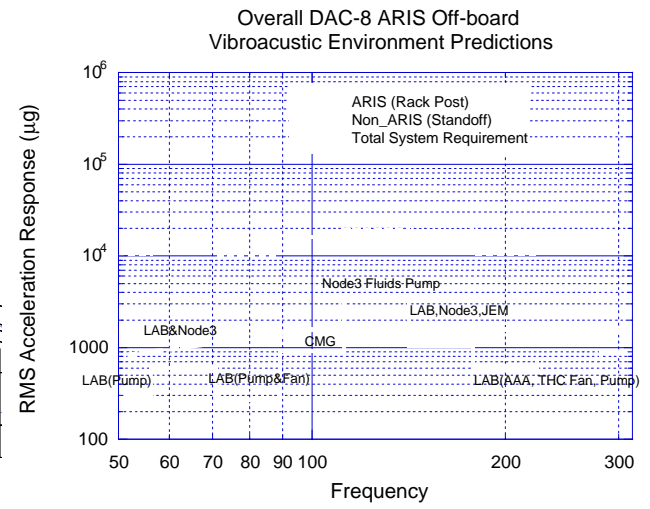
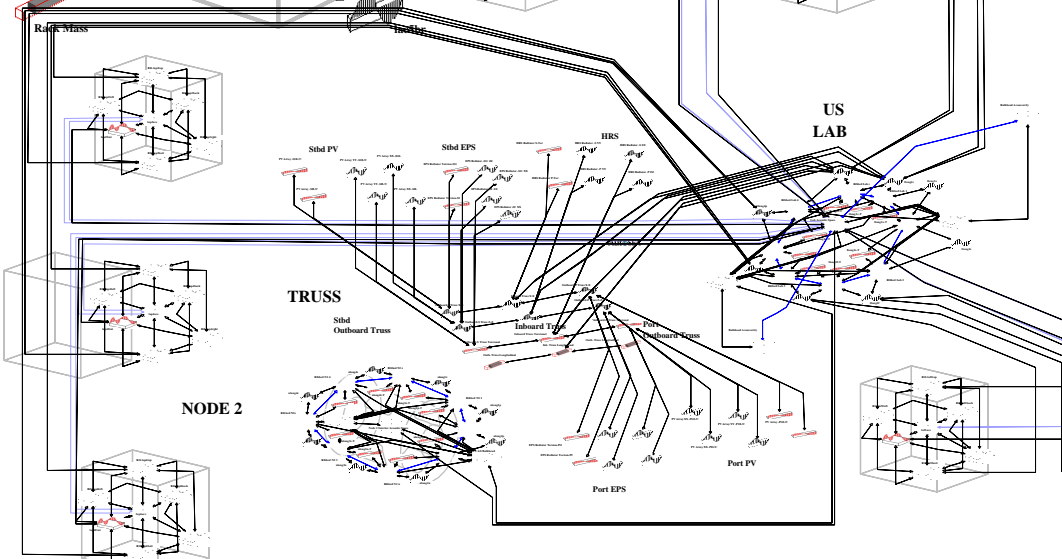
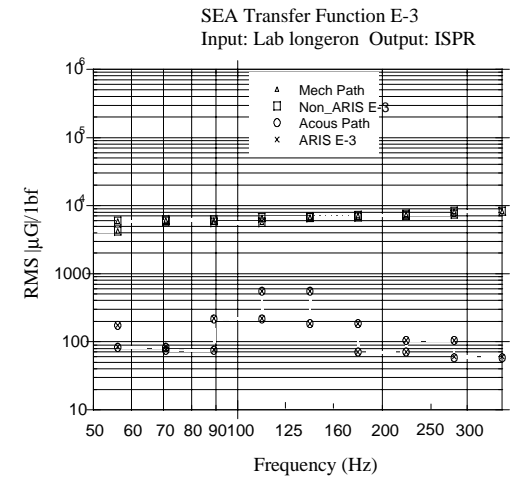
**0.01 to 50 Hz**  
**Structural Dynamic Finite Element Analysis**  
**MSC/NASTRAN (NASA CRAY)**  
**"Enhanced" Loads & Dynamics Models**



# Methods & Tools VibroAcoustic Analysis

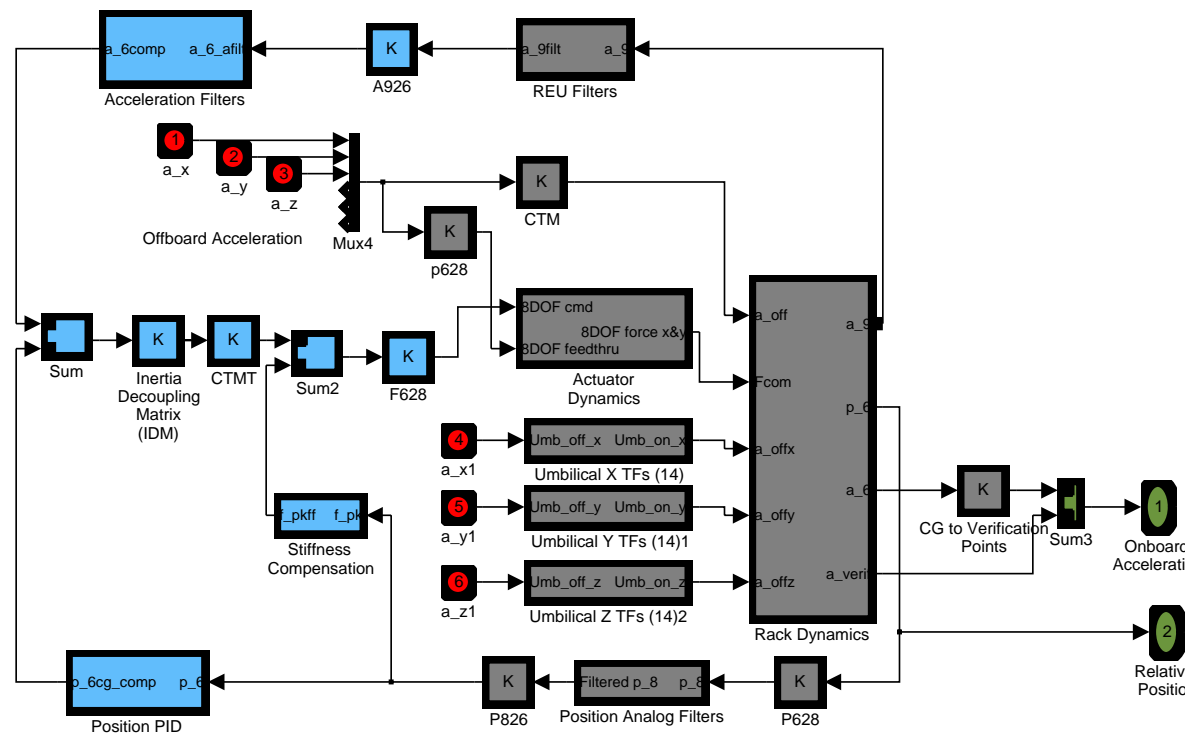
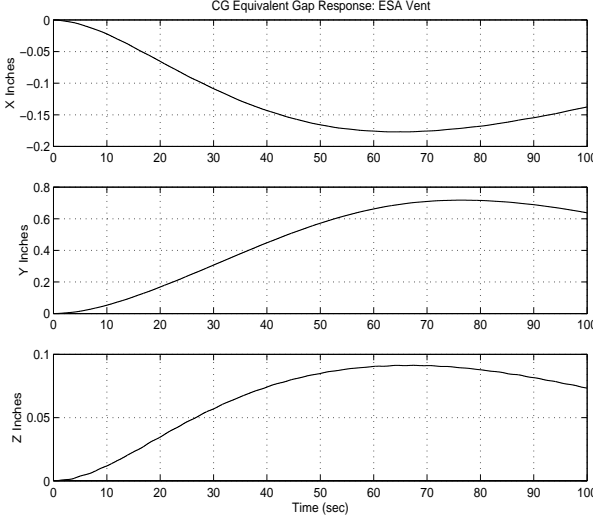
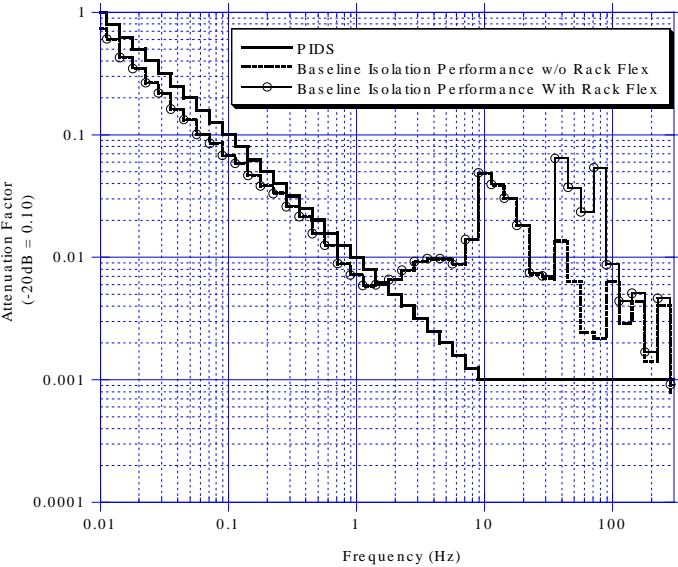


**50 to 300 Hz**  
**Vibroacoustic Statistical Energy Analysis**  
**VSL/AutoSEA (Desktop Dell Workstation)**  
**Acoustics/Launch**  
**Vibroacoustics Heritage**  
**"Original Development"**



March 8, 2001

**Active Rack Isolation System  
Control System Analysis  
Matlab/Simulink (NASASparc)**



# Methods & Tools Disturbance Analysis & Testing

**NODE TEST**

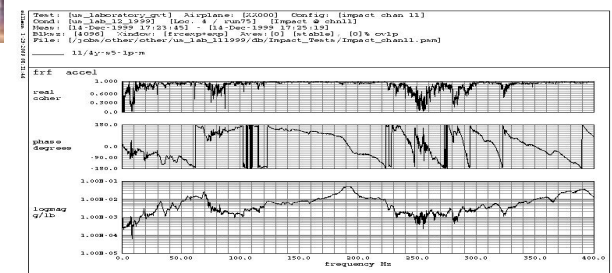


**LAB TEST**



EQUIPMENT		DACS	VMBB	RSA ORU LOGISTICS	KHSC EN-10-01, P.2	PRIME DDB	COMMENTS	ASSESSED
SOLAR ARRAY	DRIVE	1	2	2	2			
FAN	T/C	2	11	8	8	VIB ONLY	X	
	DUST COLLECTOR	2	2	2	2	VIB ONLY	X	
	CONTROL SYSTEM			1	1	NQ	N/A	
	CONTN. FILTER			1	1	NQ	N/A	
	TCS			2	2	1-VIB, 1-NQ	1-X, 1-N/A	
	COMFORT	1	3	3	3	LOW POWER	N/A	
	FIRE HAZARD			10	10	LOW POWER	N/A	
	BANK OF FANS	1						
	LIFE SUPPORT	1	4					
PUMP	TCS	2		2	2	VIB ONLY	X	
HEAT EXCH.	TCS - GAS/LIQUID	2		4	4	KHSC INS.G.		
VALVE	TCS RETURN	1		2	2	KHSC INS.G.		
	TCS REGULATOR	1		1	1	KHSC INS.G.		
	LIFE SUP. - PRESS	1		1	1	KHSC INS.G.		
	LIFE SUP. - PRESS REDUCTION	1		1	1	KHSC INS.G.		
	LIFE SUP. - EQUAL	1		1	1	KHSC INS.G.		
	LIFE SUP. - CNTRL	2		1	1	KHSC INS.G.		
TV	CAMERA	1		1 EXT-NQ	1 EXT-NQ	EXT & NQ	N/A	
PHONE	LOUDSPEAKER	3	4	3	3	CONTINGENCY	N/A	
TOTAL		22	24	45	45			

## Capture & Adequacy

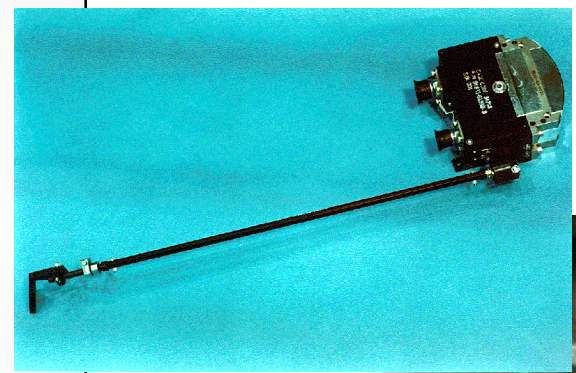
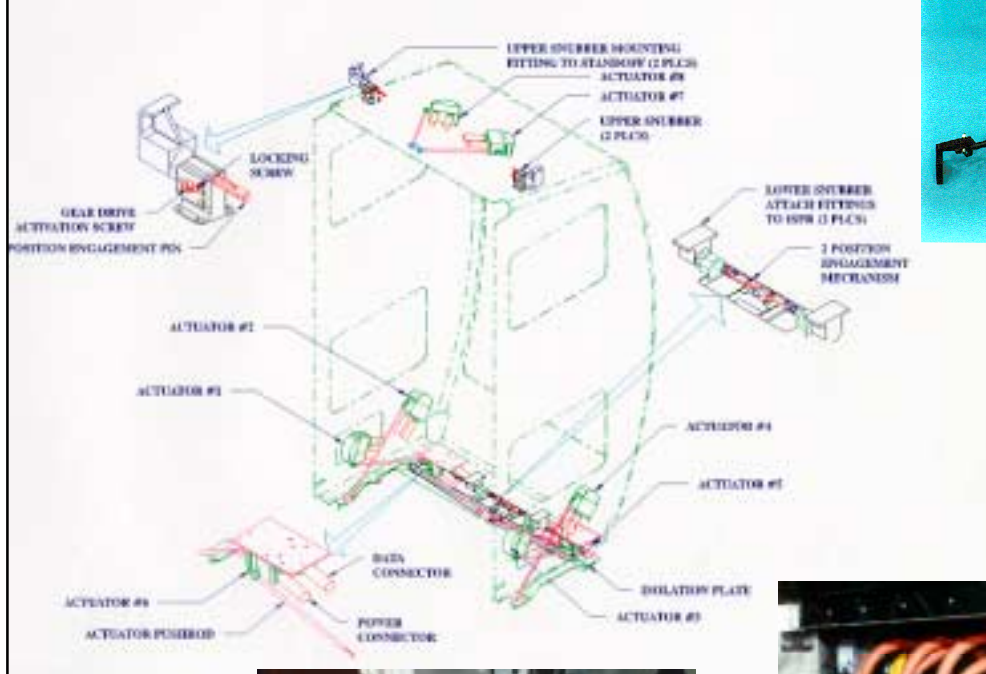


EQUIPMENT		PG/IP	DISTURBANCE COMPONENT ASSURACY (WEIGHTING * RATING)						ACCURACY RATING	
TYPE	ITEM	NUMBER	QUASI-STeady	MECHANICAL			ACOUSTICAL			0 c/= AR c/= 10
				NB	WB	TR	NB	WB	TR	
				Fndmtl.	Harmonics		Fndmtl.	Harmonics		
Flight 1A/R - FGB										
	ECLSS Fans	12	RS	8*8	4*8	2*0			1*0	6.4
	TCS Pumps	2	RS	8*8	4*6	2*0			1*0	4.8

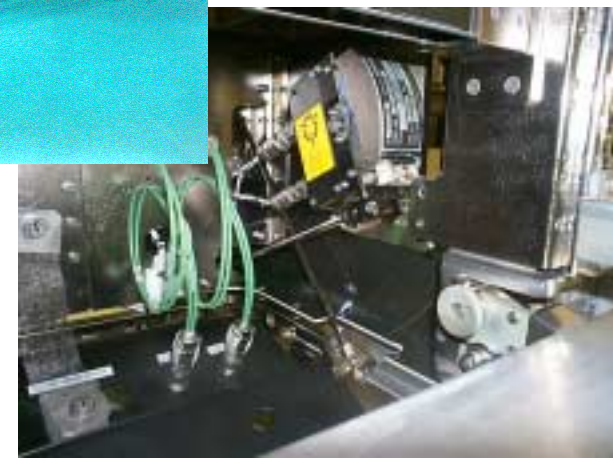


# ARIS

## ACTIVE RACK ISOLATION SYSTEM CONTROL ASSEMBLY



Actuator

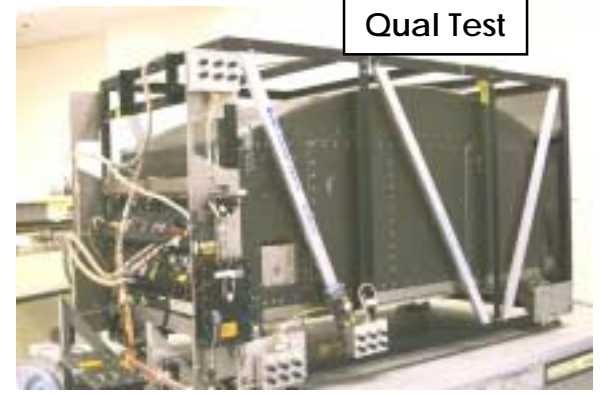


Qual Test

Snubber

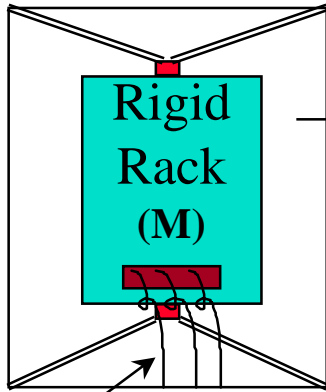


Umbilicals

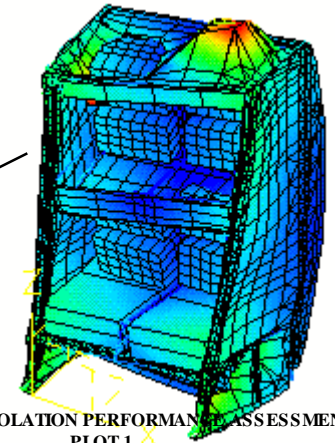
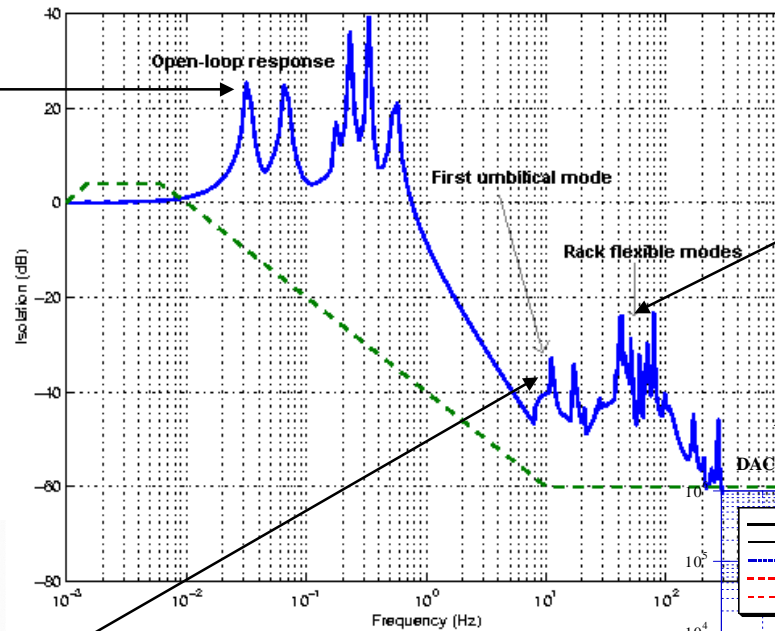
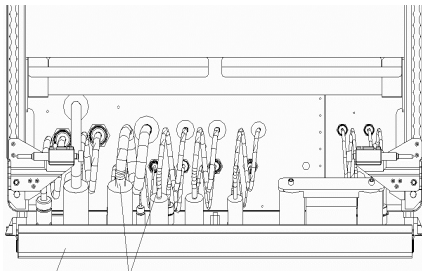


March 8, 2001

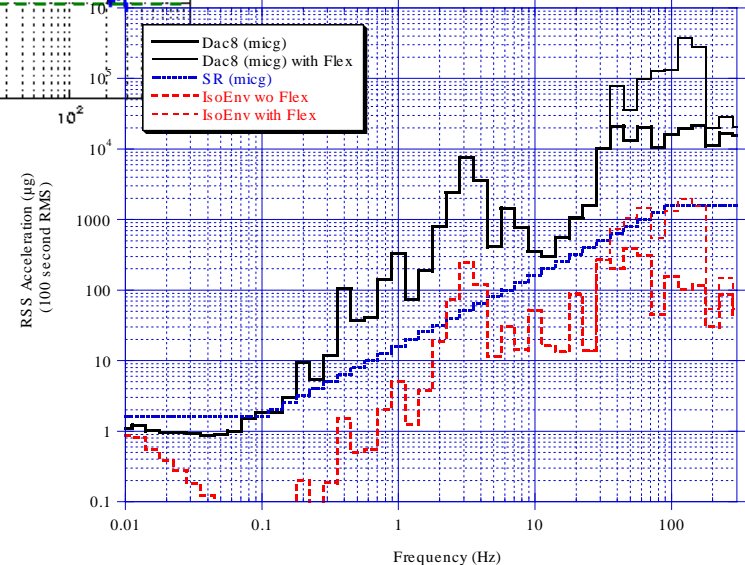
# ARIS



Umbilicals (K)



ARIS FCA/PCA ISOLATION PERFORMANCE ASSESSMENT PLOT 1  
DAC8 Acceleration Environment With & Without Rack Flex Effects



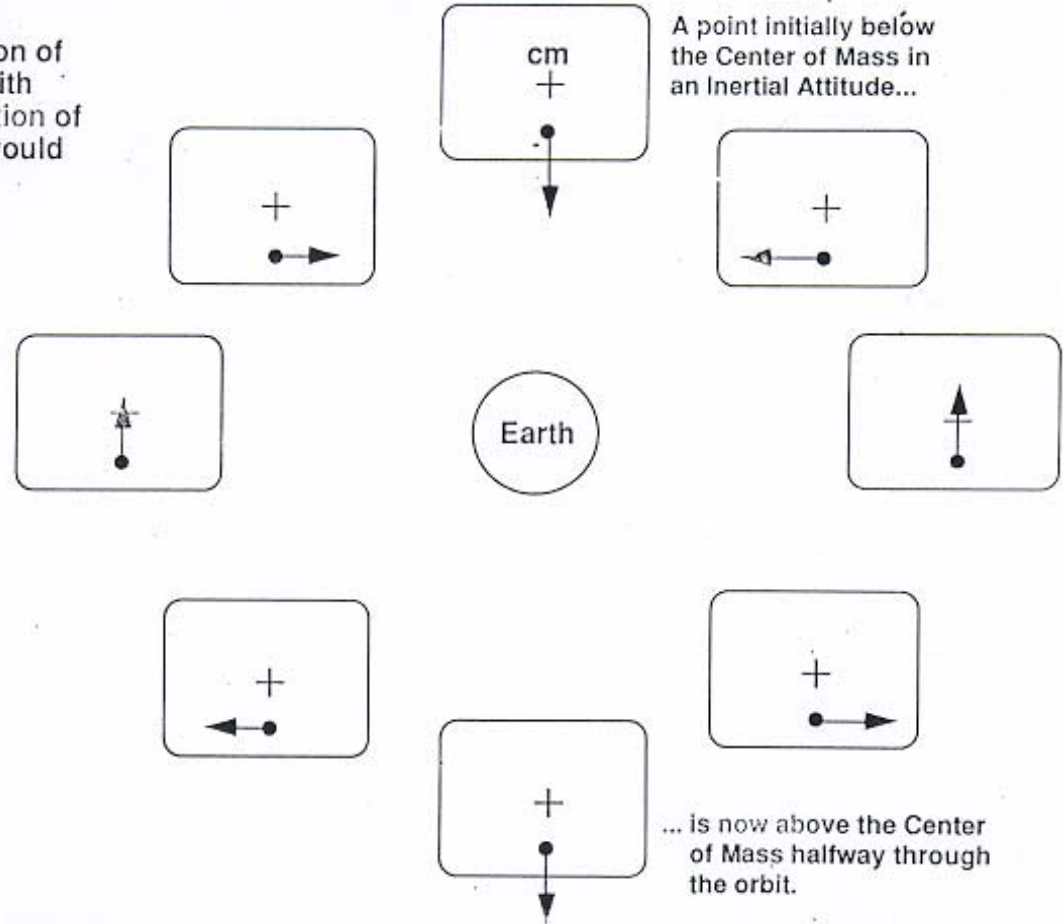
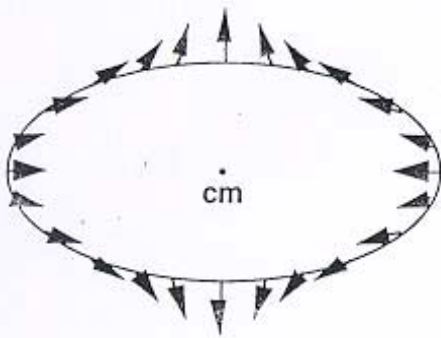
- Resonances between 0.01-1 Hz are rigid rack-umbilical modes (M-K)
- Resonance around 10 Hz is the umbilical loop resonance
- Resonances above 26 Hz are due to rack flexible modes being excited by umbilical and pushrod resonances.

# Forcing Functions

## Quasi-steady Stability - Once Per Orbit Rotation

In an inertial attitude, the orientation of a point on a body would change with respect to Earth; hence, the direction of the gravity gradient acceleration would change with respect to the body.

Recall the Gravity Gradient Ellipsoid

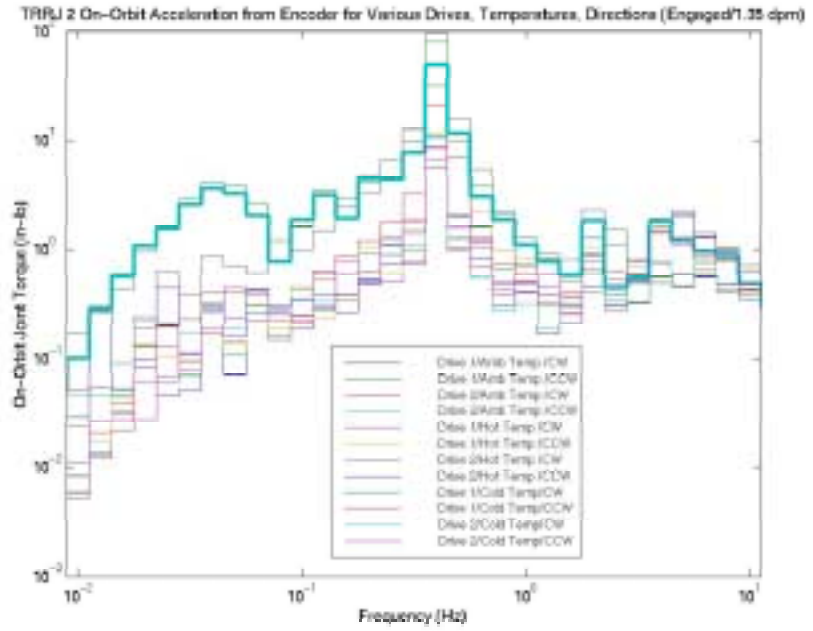


A point initially below the Center of Mass in an Inertial Attitude...

... is now above the Center of Mass halfway through the orbit.

# Forcing Functions Articulate Joints For PV Array Solar Incidence

Solar and Radiator Rotary Joints: Torque Ripple, Bearing Friction, Gear Train Meshing Friction, Position/Resolver Error



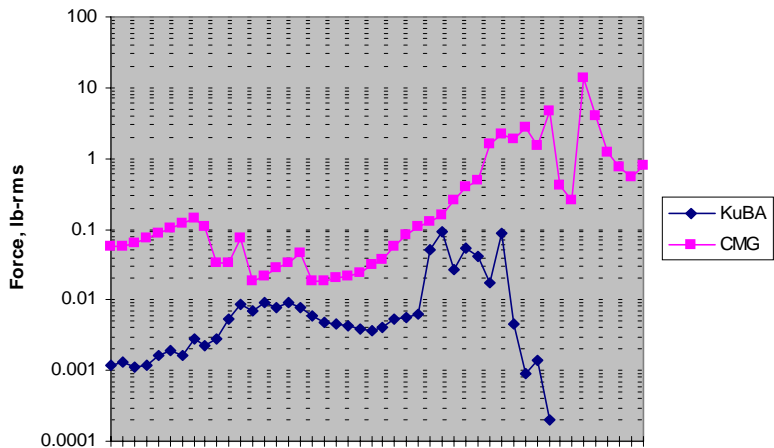
SARJ Drive Motor In Test



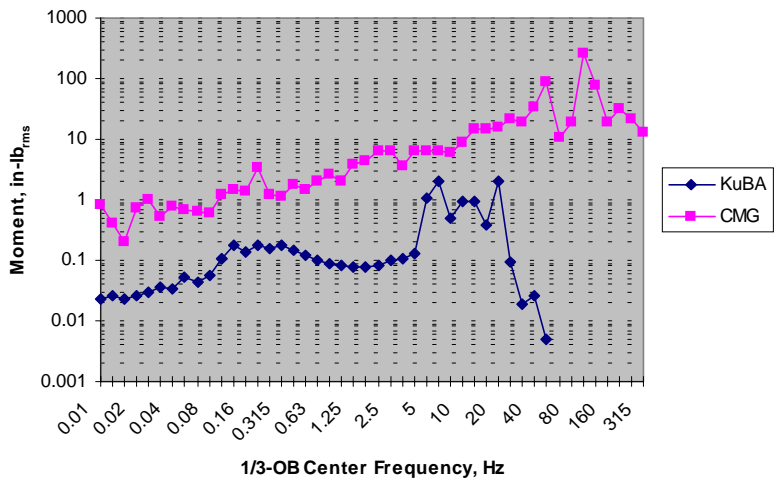
SARJ Qual Unit With Trundle Bearings Installed

# Forcing Functions Control Moment Gyros For Torque Equilibrium Attitude

1/3-Octave Band Force Spectrum



1/3-OCTAVE BAND MOMENT SPECTRUM

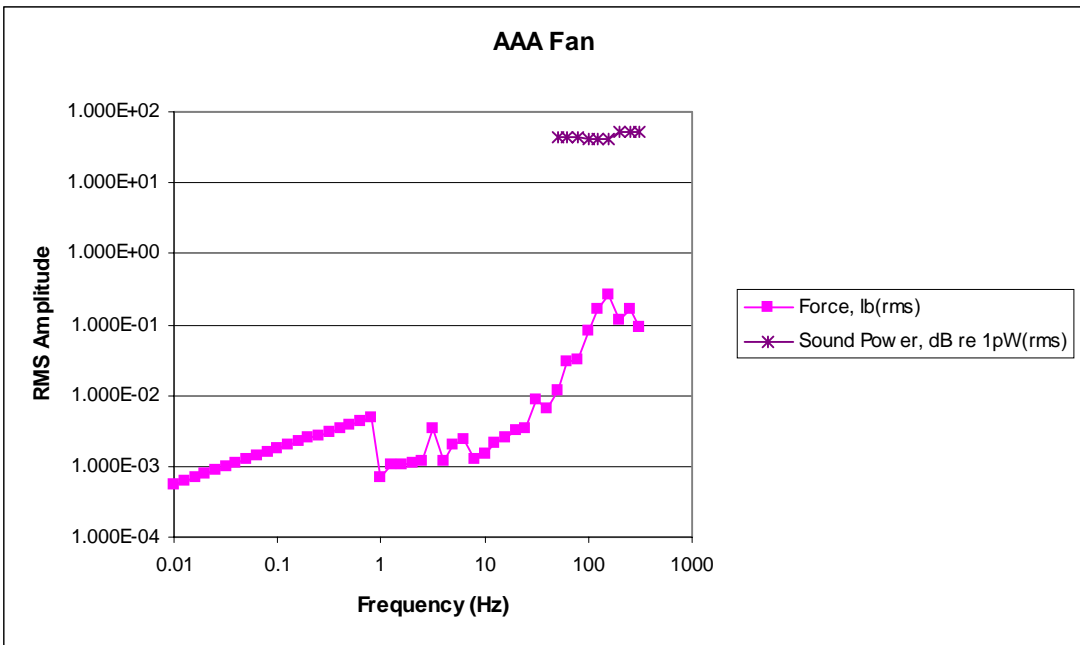


# Forcing Functions

## DISTURBANCE DATABASE

**Pressurized Module Disturbances: Fans, Pumps, Valves, Coldplates, Ducts (Mechanical and Acoustic)**

Co. / Agency	BHV			
Item	Fan, AAA (175 W, nominal)			
Location (Number)	031177,032			
	031177,032			
	031177,032			
Duty	0.2 for each fan			
References	144			
Bibliography	1,2,11,17,26,38,50,52,55,56,75			
Comments	Disturbance force is assumed to be 0.115			
1/3-OB Ctr Freq, Hz	Time, s	Force, lb(rms)	Moment, in-lb(rms)	Sound Power, dB re 1pW(rms)
0.01		5.520E-04		
0.0125		6.175E-04		
0.016		6.960E-04		
0.02		7.810E-04		
0.025		8.730E-04		
0.0315		9.820E-04		
0.04		1.100E-03		
0.05		1.235E-03		
0.063		1.390E-03		
0.08		1.560E-03		
0.1		1.750E-03		
0.125		1.950E-03		
0.16		2.200E-03		
0.2		2.470E-03		
0.25		2.760E-03		
0.315		3.100E-03		
0.4		3.490E-03		
0.5		3.910E-03		
0.63		4.380E-03		
0.8		4.940E-03		
1		6.995E-04		
1.25		1.033E-03		
1.6		1.033E-03		
2		1.113E-03		
2.5		1.212E-03		
3.15		3.497E-03		
4		1.194E-03		
5		2.034E-03		
6.3		2.373E-03		
8		1.288E-03		
10		1.525E-03		
12.5		2.159E-03		
16		2.498E-03		
20		3.200E-03		
25		3.321E-03		
31.5		8.471E-03		
40		6.464E-03		
50		1.197E-02		4.450E+01
63		2.921E-02		4.450E+01
80		3.200E-02		4.450E+01
100		8.052E-02		4.120E+01
125		1.643E-01		4.120E+01
160		2.564E-01		4.120E+01
200		1.155E-01		5.200E+01
250		1.633E-01		5.200E+01
315		9.077E-02		5.200E+01

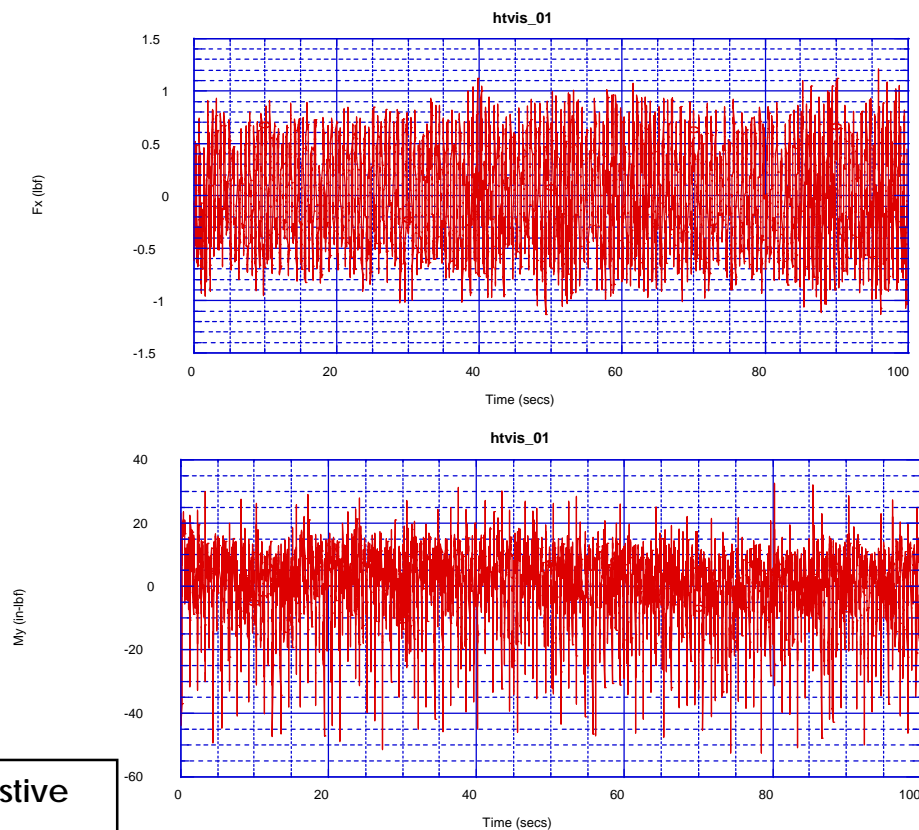


# Forcing Functions

TVIS Certification Test



6 DOF Transient Force/Moment For Various Subjects



**Crew Exercise Equipment:** Treadmill, Ergometer, Resistive Exercise Device (Isolated/Non-isolated)

**InterVehicular Activity:** Translation, Station Keeping, Console Operations, ... Scheduled Maintenance.



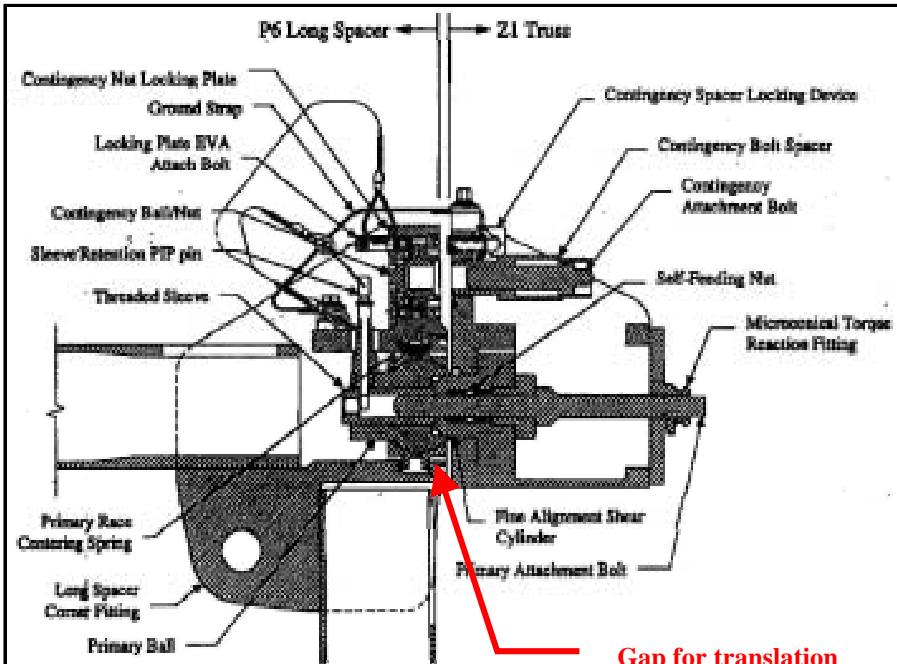
# Forcing Functions

Thermal Induced Vibration

HARDWARE ITEM	STATIC FRICTION RELEASE (STICK-SLIP)	THERMAL STEP & MODAL DEFLECTION	SLOWLY VARYING DEFORMATION (~ORBITAL RATE)	THERMAL BUCKLING (OIL CANNING)
SHORT SPACER/ LONG SPACER INTERFACE	<p>SIGNIFICANT</p> <ul style="list-style-type: none"> <li>Rocketdyne Truss Attachment System (RTAS) forcing function developed by BHB (Refs. 10, 11, &amp; 12).</li> <li>BHOU assessment indicates that RTAS stick/slip is a Microgravity Critical Item (MGCL) (Refs. 4).</li> <li>Disturbance adequacy rating of 7 meets verification criteria.</li> </ul>	NOT APPLICABLE TO INTERFACE	NOT APPLICABLE TO INTERFACE	NOT APPLICABLE TO INTERFACE
LONG SPACERS	<p>NONE</p> <ul style="list-style-type: none"> <li>No sliding joints other than at interface with short spacer – see short spacer/long spacer interface (Ref. 6).</li> </ul>	<p>NONE</p> <ul style="list-style-type: none"> <li>No vibration modes below 30 Hz (Ref. 6).</li> </ul>	<p>NOT APPLICABLE</p> <ul style="list-style-type: none"> <li>Item by itself is very stiff. Only when integrated with other elements (including non-PG2) will item experience low frequency motion (Ref. 17).</li> </ul>	<p>NONE</p> <ul style="list-style-type: none"> <li>Constructed of hollow, extruded aluminum tubes with 3/16 inch minimum thickness. There are no thin plates or long slender members (Ref. 6).</li> </ul>
IEAs	<p>NONE</p> <ul style="list-style-type: none"> <li>No sliding joints other than at interface with EPS radiator (Ref. 6) – see IEA/EPS radiator interface.</li> </ul>	<p>NONE</p> <ul style="list-style-type: none"> <li>No vibration modes below 30 Hz (Ref. 6).</li> <li>An IEA with full sun exposure could see a heat-up rate of 4 degrees F per hour. The rate is slow due to the mass of the structure (Ref. 20).</li> </ul>	<p>NOT APPLICABLE</p> <ul style="list-style-type: none"> <li>Item by itself is very stiff. Only when integrated with other elements (including non-PG2) will item experience low frequency motion (Ref. 17).</li> </ul>	<p>NONE</p> <ul style="list-style-type: none"> <li>Free thermal expansion with no thin plates or long slender members (Ref. 6)</li> </ul>
EPS RADIATORS	<p>NONE</p> <ul style="list-style-type: none"> <li>No sliding joints other than at interface with EPS radiator (Ref. 6) – see IEA/EPS radiator interface.</li> </ul>	<p>NEGLIGIBLE</p> <ul style="list-style-type: none"> <li>Fundamental vibration mode at 0.23 Hz is too high to be affected by slow temperature variations (Ref. 6).</li> <li>Other than the PV Arrays, most items have a long thermal time constant, e.g. 15 minutes for the radiators (Ref. 15).</li> <li>Each radiator weighs about 1600 lbs, compared to 2400 lbs for the PV Array, and about half of it is a concentrated load at the base. The radiator is about a quarter of the size of the PV Array. The forces and moments generated at the base of the radiator will be much smaller than that generated at the base of the PV Array which are negligible (Ref. 17).</li> </ul>	<p>NEGLIGIBLE</p> <ul style="list-style-type: none"> <li>Each radiator weighs about 1600 lbs, compared to 2400 lbs for the PV Array, and about half of it is a concentrated load at the base. The radiator is about a quarter of the size of the PV Array. The forces and moments generated at the base of the radiator will be much smaller than that generated at the base of the PV Array which are negligible (Ref. 17).</li> </ul>	<p>NONE</p> <ul style="list-style-type: none"> <li>The radiators are freely expanding structures (Refs. 6 &amp; 17).</li> </ul>



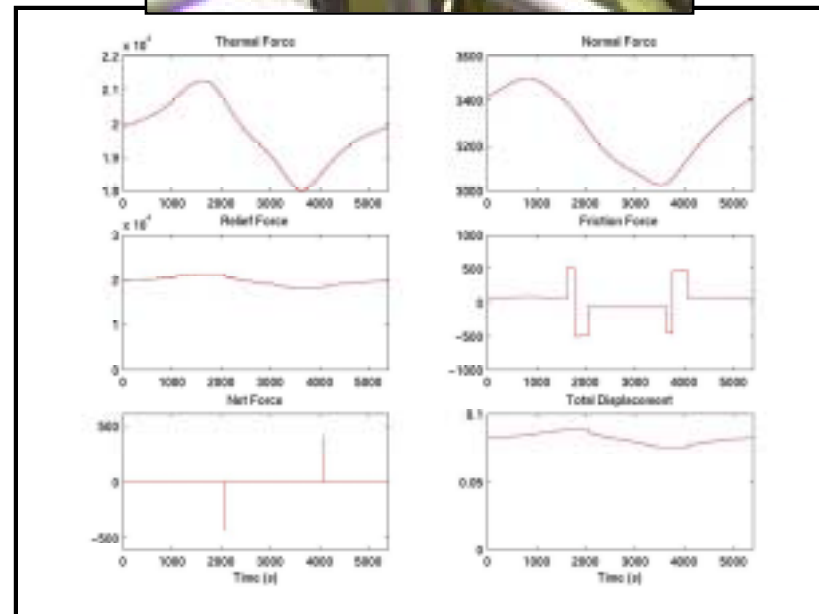
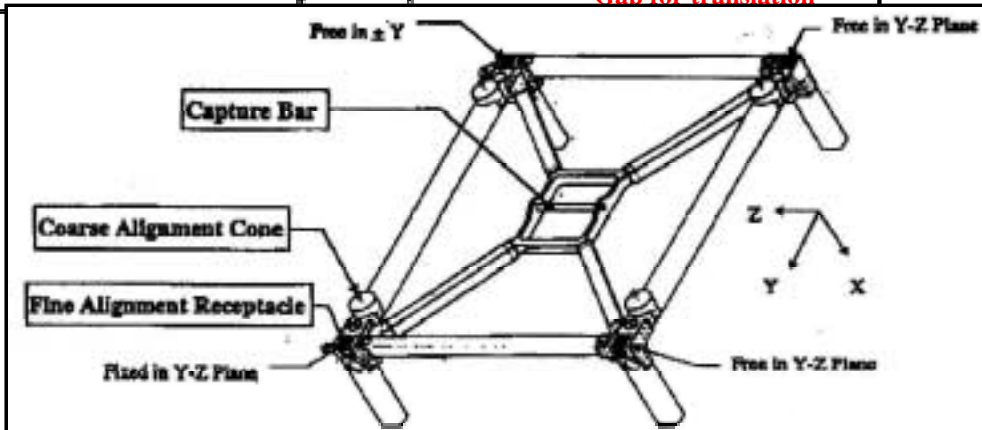
# Forcing Functions



RTAS Stick-Slip

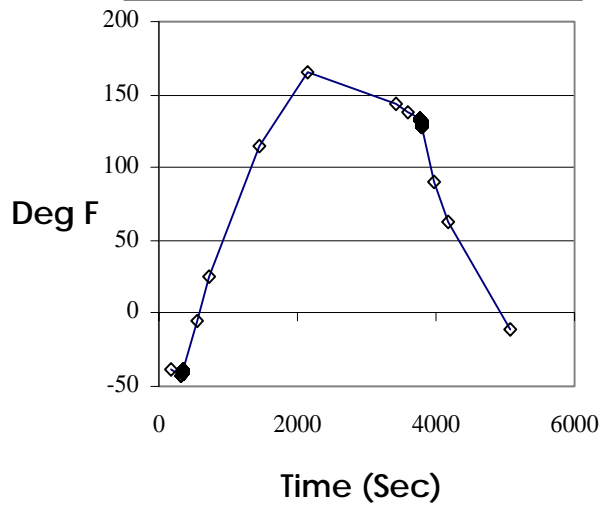


Gan for translation



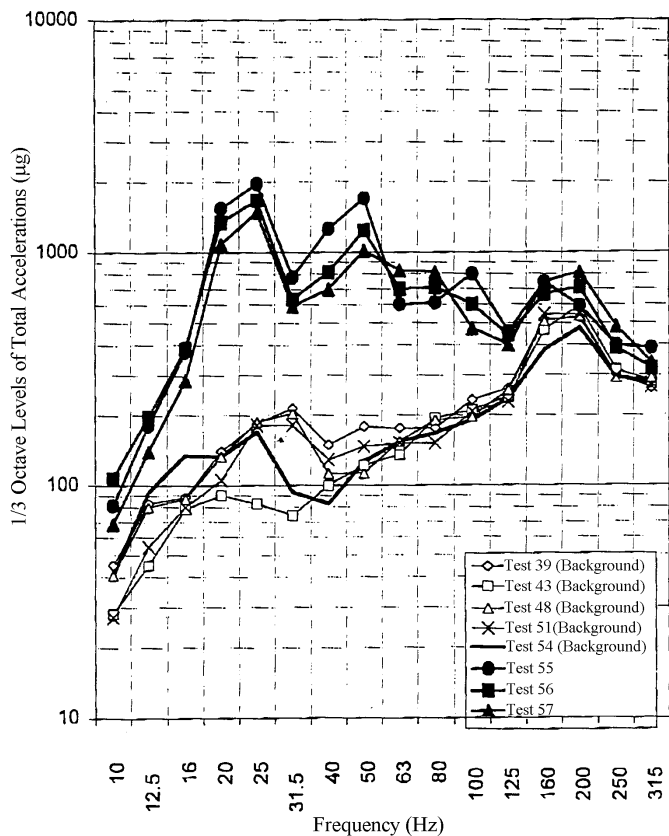
# Forcing Functions

No Shadow Temp Profile @  
Typical Mast Grid  
(Day-Night Transition)



# Forcing Functions

## RS Service Module Element Ground Test



## ESA Columbus Module Component Ground Test

ECLSS : -

- \* one Cabin fan assy (CFA EM5) (test data eq. &sect.)
- \* one Cabin fan assy as IMV Supply fan (test data eq. & sect.)
- \* one Cabin fan Assy as IMV Return Fan (test data - eq. &sect.)
- \* two Condensate Water Separator Assies (CWSA EM) (test data - eq. & sect.)
- \* one Condensate Heat Exchanger/Thermal Control valve (CHX/TCV) (testdata - eq. & sect.)
- \* TWO WASTE GAS Line shut Off Valve (LSOV) (test data -eq.)
- \* One WLSV EM (test data - eq.)
- \* Two PPO2 (test data -eq.)
- \* Airbox (Test data-Section)

TCS:

- \* one WPA (test data -eq.)
- \* one WOO (actuated) (test data -eq.)
- \* two WTMO (actuated) (test data - eq.)
- \* fluxed ducting (test data - sect.)

Structural Stick/slip :

- \* Stick/slip at MDPS/bracket interface (analytical evaluation)

## NASDA ICS Antenna Slew & Tracking



# ISS Traffic Model

- **The traffic plan includes a complete traffic event schedule and a projected resupply/return loading by cargo category starting with first element launch through end of life.**
- **The integrated traffic plan is also used to support design analysis, unique transportation system studies, off-nominal operations planning, and to assess the viability of long-term planning inputs from International Partners.**



## DAC8 DURATION ASSESSMENT

---

---



### **What are the major disturbers to ISS micro-g**

- **Docking events**
- **Undocking events**
- **Reboots**
- **EVAs**

### **Threats to micro-gravity periods**

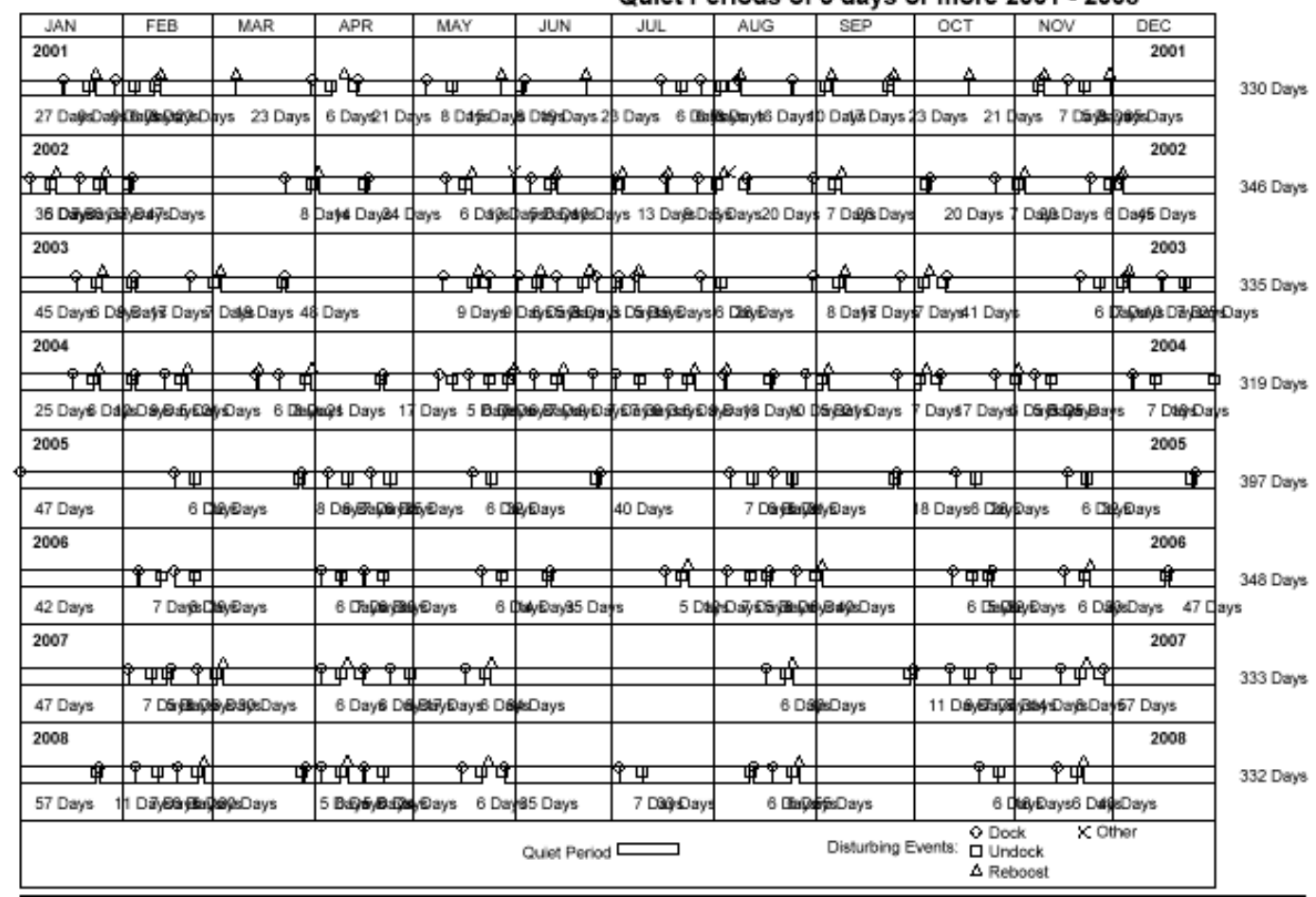
- **Debris Avoidance Maneuvers**
- **Deferred or contingency EVAs**
- **Launch schedule changes**



# DAC8 Assembly >5 Day Periods

## International Space Station Traffic Model

### Quiet Periods of 5 days or more 2001 - 2008



Date: 9/6/00 4:59:51 PM  
 Imported 04/09/2000 Imported 05/13/2000

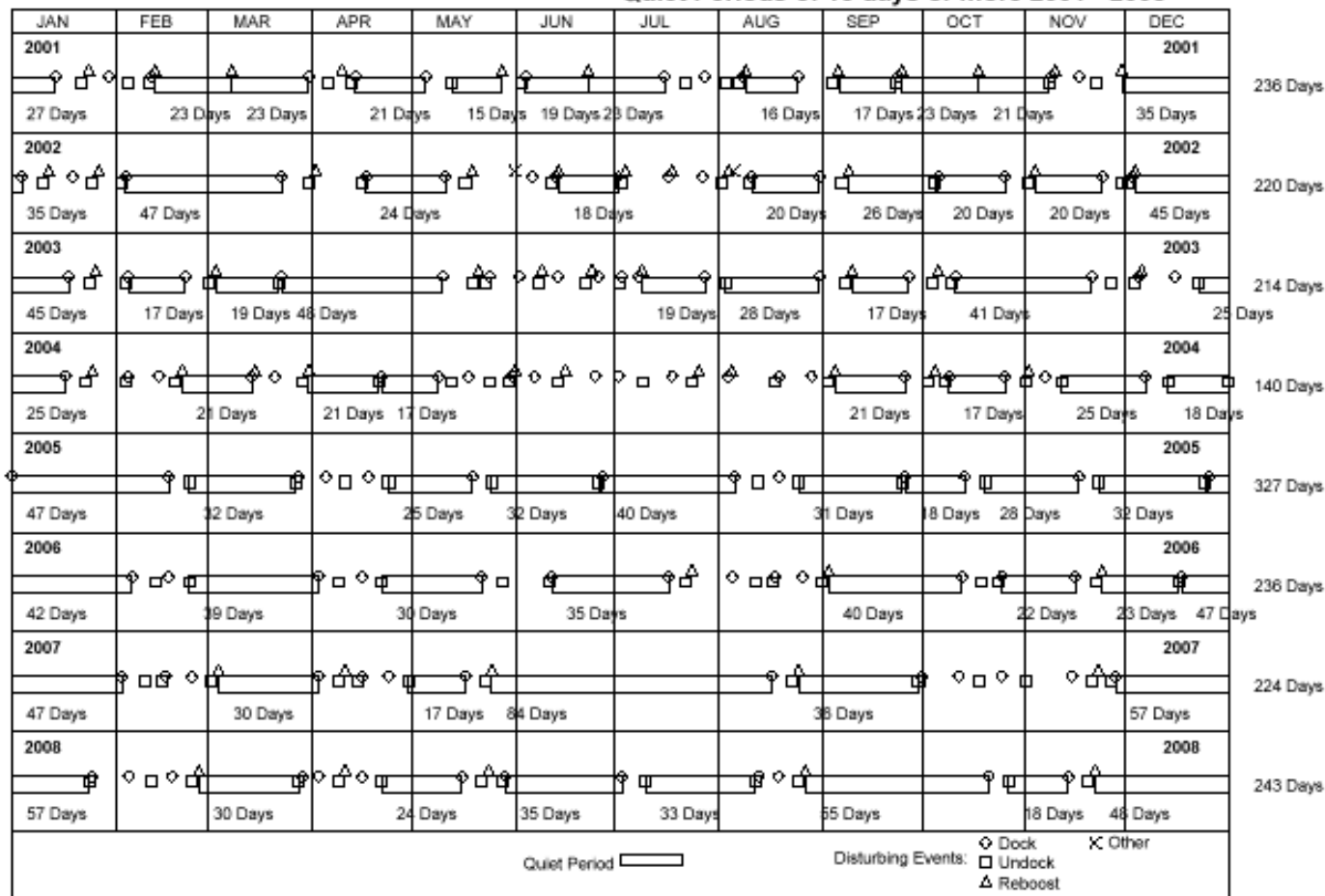
Version 16 DAC8 (ATV & more HTVs)

ISS Traffic Model Version 8.2  
 Page 1 of 2

# DAC8 Assembly >15 Day Periods

## International Space Station Traffic Model

### Quiet Periods of 15 days or more 2001 - 2008



Date: 9/6/00 4:59:51 PM  
 Imported 04/09/2000 Imported 05/13/2000

Version 16 DAC8 (ATV & more HTVs)

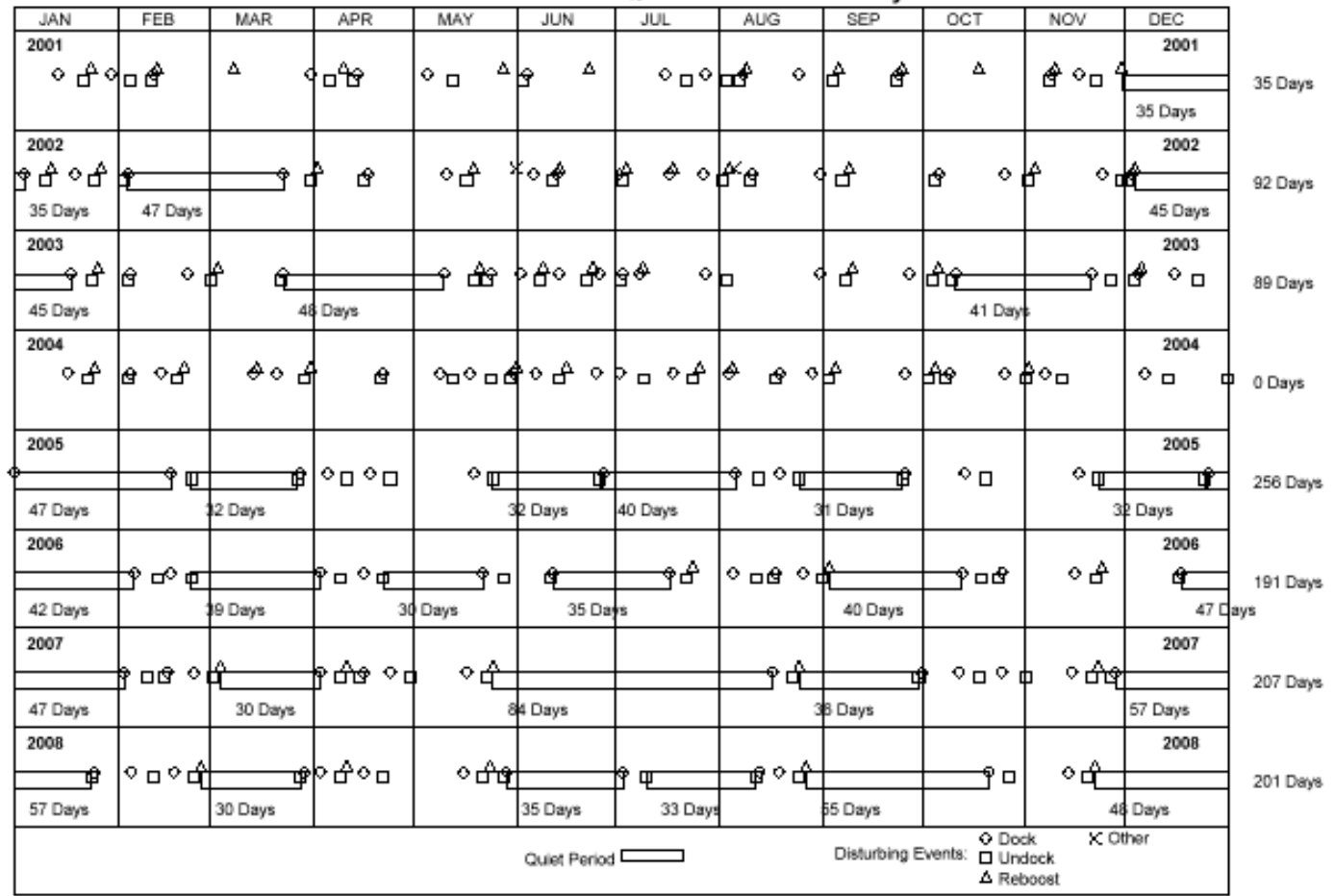
ISS Traffic Model Version 6.2  
 Page 1 of 2



# DAC8 Assembly >30 Day Periods

## International Space Station Traffic Model

### Quiet Periods of 30 days or more 2001 - 2008



Date: 9/6/00 4:59:51 PM  
 Imported 04/09/2000 Imported 05/13/2000

Version 16 DAC8 (ATV & more HTVs)

ISS Traffic Model Version 6.2  
 Page 1 of 2

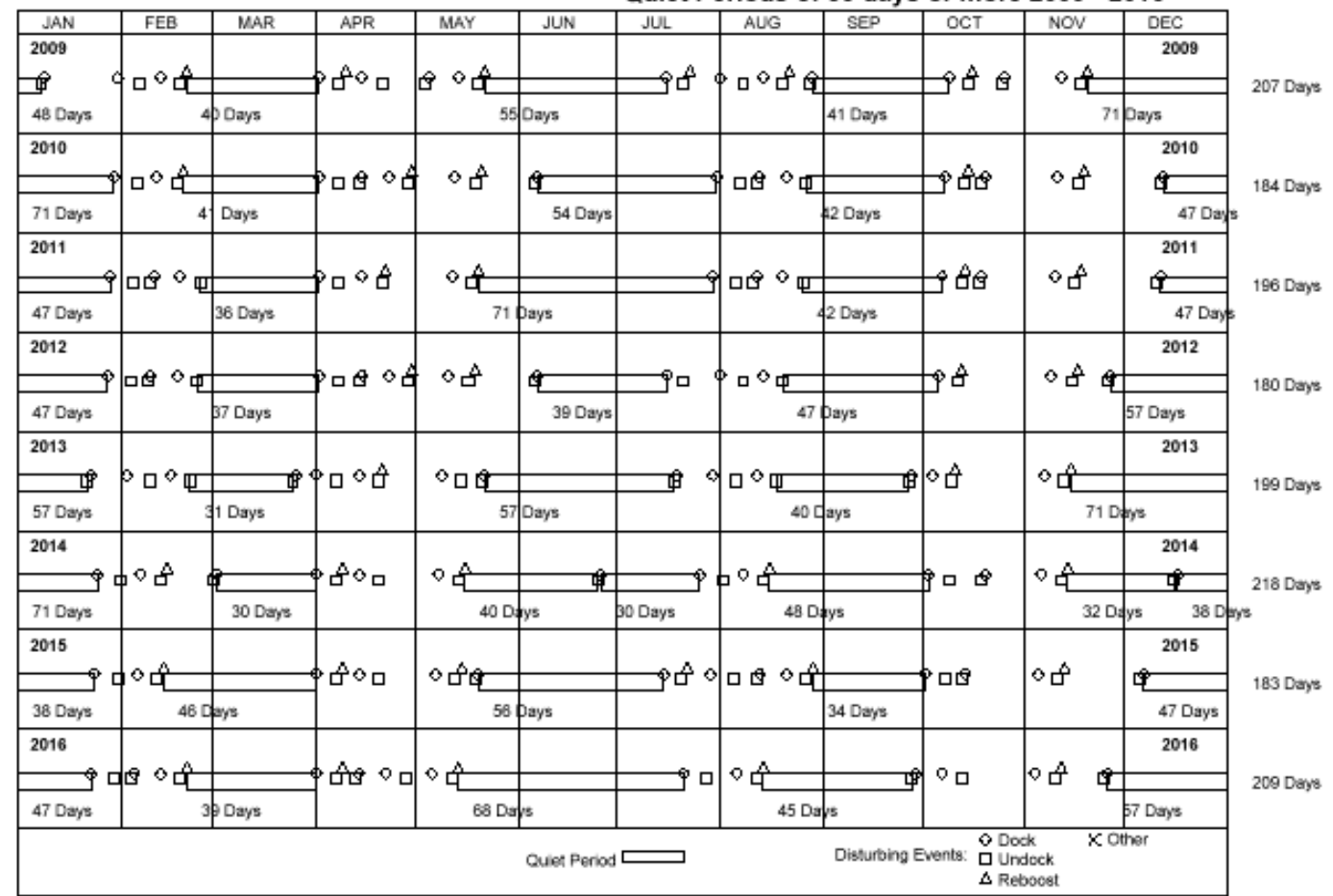




# DAC8 Assembly Complete >30 Day Periods

## International Space Station Traffic Model

### Quiet Periods of 30 days or more 2009 - 2016



Date: 9/6/00 4:59:51 PM

Version 16

DAC8 (ATV & more HTVs)

ISS Traffic Model Version 6.2

Imported 04/09/2000 Imported 05/13/2000

Page 2 of 2



## DAC8 DURATION ASSESSMENT

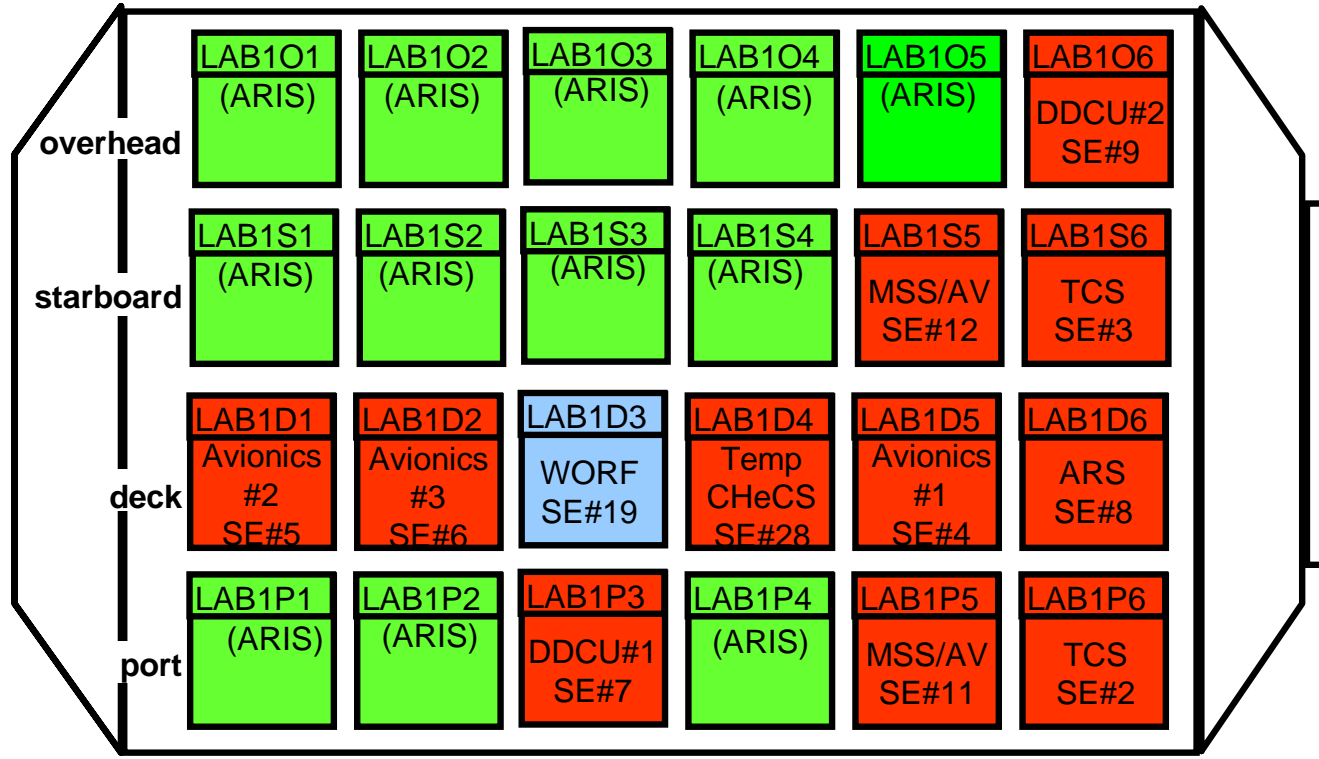
---

---

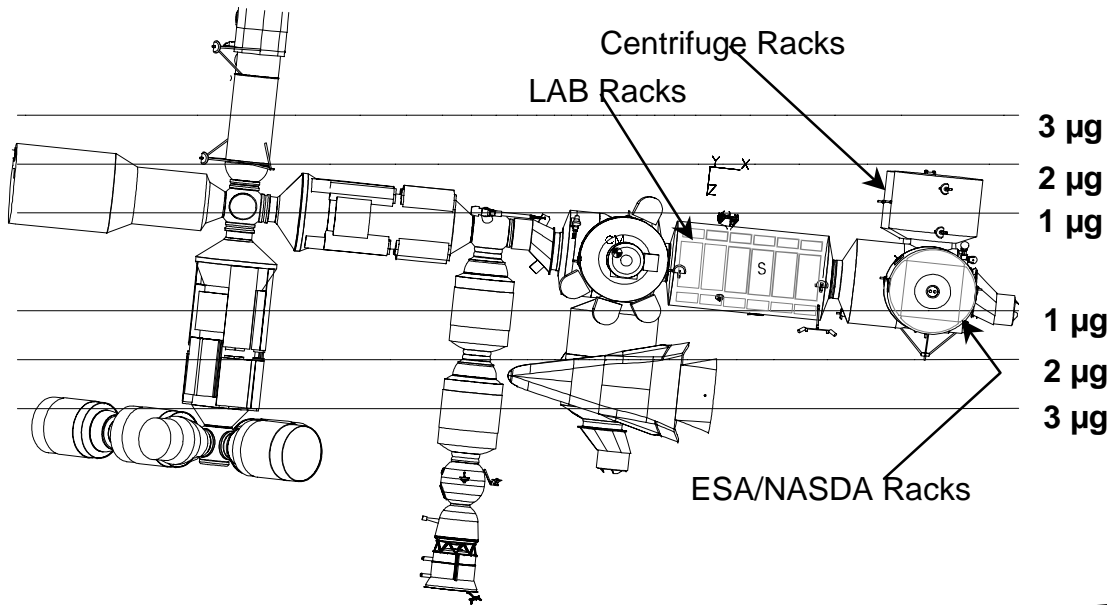
### Conclusion

- **Currently there is no requirement to meet the micro-gravity period requirement during assembly**
- **Based on analysis the micro-gravity requirement can be satisfied during the assembly complete period**

# Rack Topology at Assembly Complete (Analysis Configuration)



# DAC8 Quasi-Steady Performance

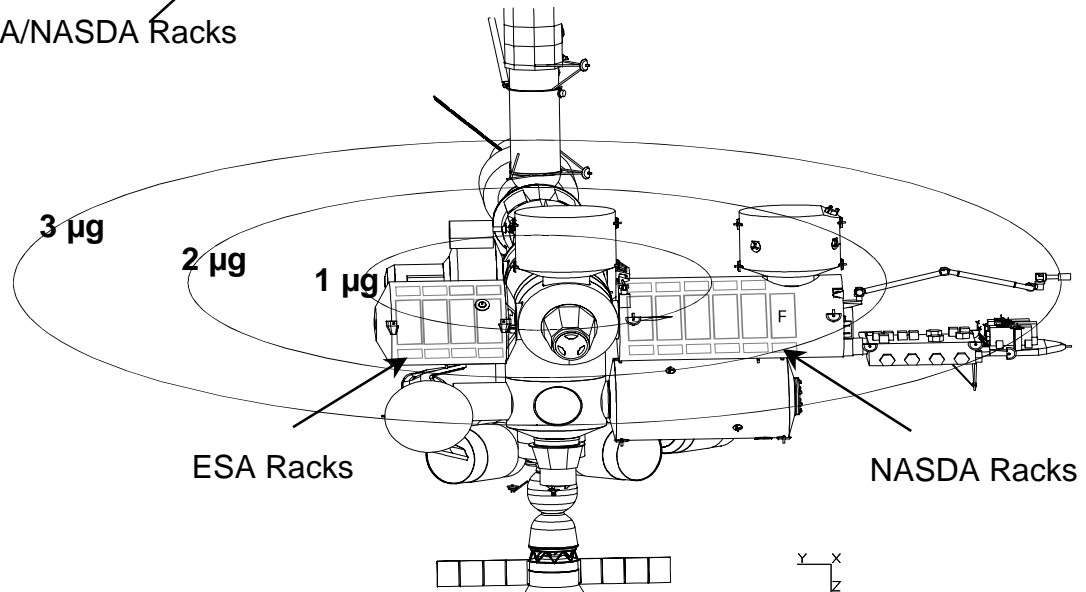


**Quasi-steady Performance:**

- 15 of 32 ISPRs < 1.0  $\mu\text{g}$
- 16 of 32 ISPRs < 1.2  $\mu\text{g}$
- All satisfy stability criteria

**Flight Attitude:**

- Pitch -6.97 degrees
- Yaw -8.07 degrees
- Roll 1.16 degrees





# DAC8 Quasi-Steady Performance



**15 of 32 racks less than 1  $\mu\text{g}$  magnitude & 0.2  $\mu\text{g}$  perpendicular component.**

Location	Rack Position in ISS Frame			$\mu\text{G}$ Vector		Unit Vector			Max angle from unit vector (deg)	Cone Angle $\perp$ Component @ max angle ( $\mu\text{G}$ )	Magnitude at max angle ( $\mu\text{G}$ )
	X (ft)	Y (ft)	Z (ft)	Magnitude ( $\mu\text{G}$ )	$\perp$ Component ( $\mu\text{G}$ )	X	Y	Z			
CG	-15.34	-1.28	14.87	0.210	0.038	-0.994	-0.107	0.013	20.660	0.025	0.065
USL-C1	15.55	0.00	11.26	0.245	0.064	-0.624	-0.773	-0.119	24.100	0.054	0.122
USL-C2	12.05	0.00	11.26	0.232	0.063	-0.665	-0.722	0.191	26.258	0.050	0.101
USL-C3	8.55	0.00	11.26	0.230	0.070	-0.635	-0.584	0.506	26.070	0.051	0.104
USL-C4	5.05	0.00	11.26	0.243	0.078	-0.546	-0.406	0.733	23.624	0.056	0.129
USL-C5	1.55	0.00	11.26	0.266	0.084	-0.446	-0.247	0.860	20.229	0.062	0.168
USL-S1	15.55	4.84	16.11	0.689	0.087	-0.321	0.068	-0.945	7.346	0.087	0.672
USL-S2	12.05	4.84	16.11	0.645	0.086	-0.340	0.108	-0.934	7.765	0.086	0.628
USL-S3	8.55	4.84	16.11	0.602	0.084	-0.362	0.154	-0.919	8.219	0.084	0.584
USL-S4	5.05	4.84	16.11	0.560	0.083	-0.386	0.207	-0.899	8.793	0.076	0.488
USL-P1	15.55	-4.84	16.11	0.722	0.088	-0.217	-0.488	-0.845	7.082	0.088	0.707
USL-P2	12.05	-4.84	16.11	0.671	0.087	-0.230	-0.497	-0.837	7.551	0.087	0.656
USL-P4	5.00	-4.84	16.11	0.570	0.085	-0.264	-0.519	-0.813	8.725	0.084	0.546
JPM1-A1	29.66	-10.82	15.92	1.035	0.091	-0.126	-0.652	-0.748	5.190	0.091	1.006
JPM2-F1	40.00	-10.82	15.92	1.193	0.093	-0.118	-0.617	-0.778	4.618	0.093	1.156
JPM3-A2	29.66	-14.32	15.92	1.121	0.092	-0.097	-0.726	-0.680	4.810	0.092	1.089
JPM4-F2	40.00	-14.32	15.92	1.274	0.094	-0.094	-0.688	-0.720	4.339	0.094	1.234
JPM5-A3	29.66	-17.82	15.92	1.217	0.092	-0.072	-0.783	-0.617	4.450	0.092	1.182
JPM6-F3	40.00	-17.82	15.92	1.364	0.094	-0.072	-0.744	-0.664	4.068	0.094	1.321
JPM7-A4	29.66	-21.32	15.92	1.320	0.093	-0.050	-0.827	-0.561	4.122	0.093	1.283
JPM8-A5	29.66	-24.82	15.92	1.429	0.093	-0.032	-0.860	-0.510	3.831	0.093	1.392
JPM9-F5	40.00	-24.82	15.92	1.566	0.095	-0.036	-0.825	-0.564	3.585	0.095	1.520
JPM10-F6	40.00	-28.32	15.92	1.675	0.096	-0.021	-0.854	-0.521	3.384	0.096	1.627
APM-CLG1	34.84	14.39	10.74	0.517	0.089	-0.435	0.684	-0.586	9.998	0.089	0.505
APM-CLG2	34.84	18.33	10.74	0.640	0.093	-0.379	0.794	-0.475	8.422	0.093	0.629
APM-FWD1	40.00	14.39	15.91	1.078	0.094	-0.272	0.266	-0.925	5.027	0.094	1.067
APM-FWD2	40.00	18.33	15.91	1.146	0.095	-0.277	0.390	-0.878	4.781	0.095	1.135
APM-FWD3	40.00	22.26	15.91	1.229	0.096	-0.277	0.493	-0.825	4.521	0.096	1.219
APM-FWD4	40.00	26.19	15.91	1.326	0.098	-0.274	0.576	-0.771	4.267	0.098	1.316
APM-AFT1	29.67	14.39	15.91	0.963	0.092	-0.297	0.366	-0.882	5.528	0.092	0.951
APM-AFT2	29.67	18.33	15.91	1.045	0.094	-0.295	0.491	-0.820	5.173	0.094	1.033
APM-AFT3	29.67	22.26	15.91	1.142	0.095	-0.290	0.587	-0.756	4.824	0.095	1.131
APM-AFT4	29.67	26.19	15.91	1.251	0.098	-0.282	0.661	-0.695	4.504	0.098	1.242
CAM-MID	36.08	0.00	4.17	0.608	0.091	-0.045	-0.410	0.911	8.877	0.091	0.581
CAM-TOP	36.08	0.00	0.00	1.077	0.092	0.033	-0.216	0.976	5.019	0.092	1.042

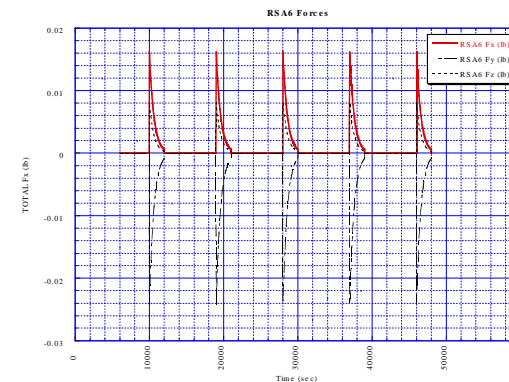
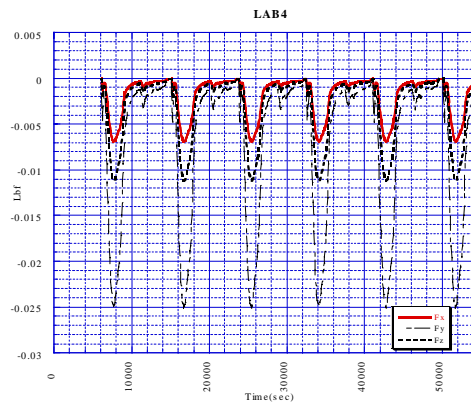
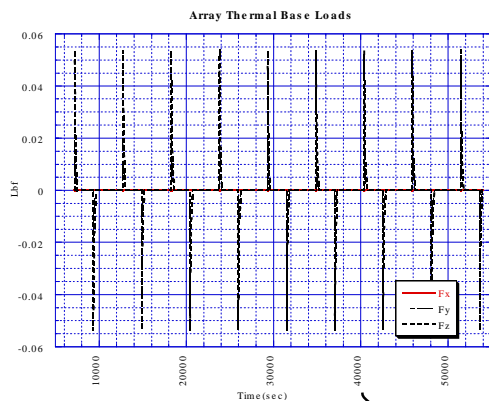


## DAC8 Quasi-steady Individual Disturbance Inputs

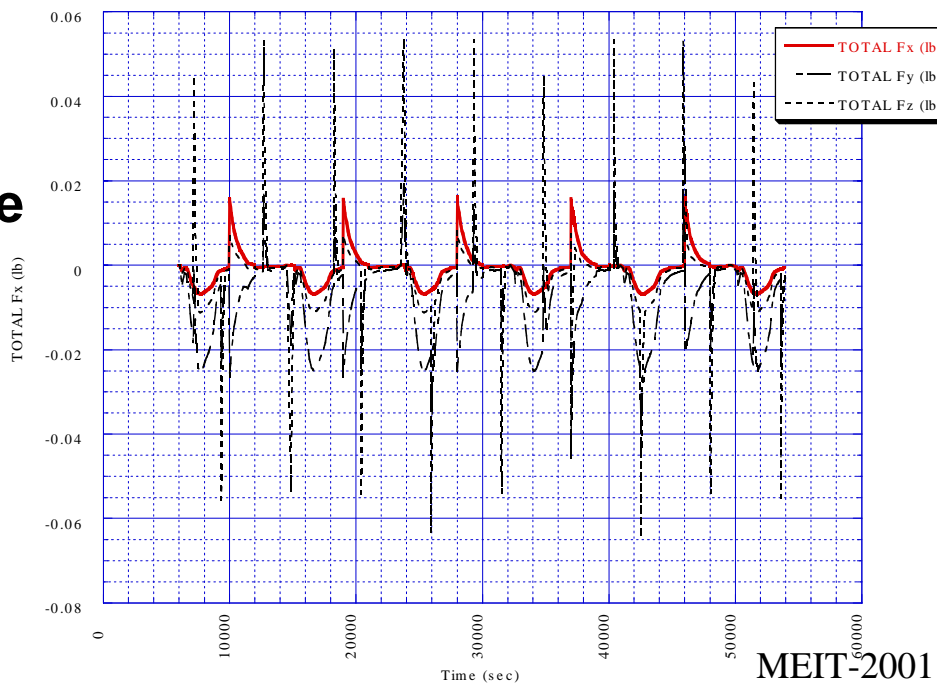


- **Centrifuge startup and shut down**
  - Spin-up for 120 sec to 236 deg/s, spin for 6.4 hours, spin-down for 120 sec.
  - Starts at 17000 sec
- **TRRJ slew at low betas**
  - TRRJ 0 beta slew rates - TRRJ Torque Power Spectral Density has 87.7% of its power below .01 Hz.
  - Not Applicable
- **Solar Thermal base loads**
  - Exponential decay for 210 seconds every 2160 seconds (night), 3360 (day), forces combined for eight arrays
  - Lighting dependent , continuous
- **LAB4 Vent**
  - Force profile, duration of 8700 seconds
  - Starts at 6000 seconds
- **RSA6 Vent**
  - Exponential decay of 600 seconds every 9000 seconds
  - Starts at 10000 seconds
- **Treadmill Gyro Start-up**
  - +.23 ft-lbs. for 10minutes, 0 ft-lbs. for 60 minutes, -.23 ft-lbs. for 10 minutes, repeated every 30 minutes.
  - Starts at 6000 seconds

# DAC8 Quasi-steady Individual Disturbance Inputs

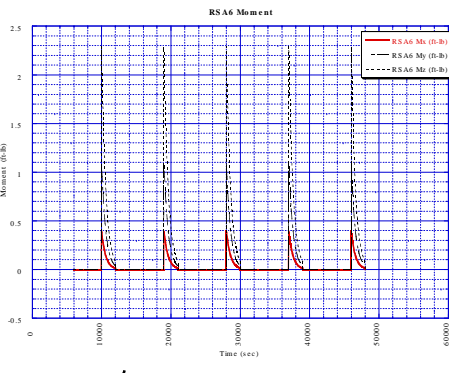
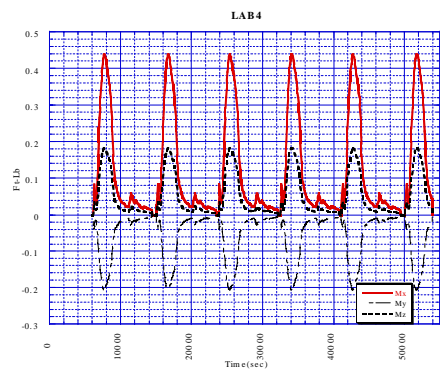
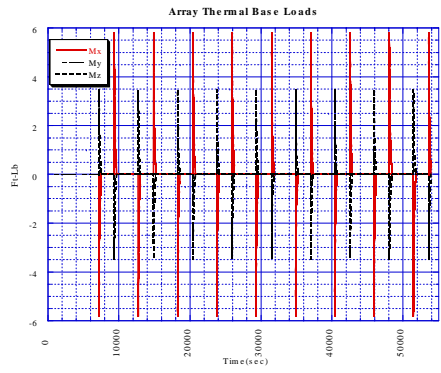
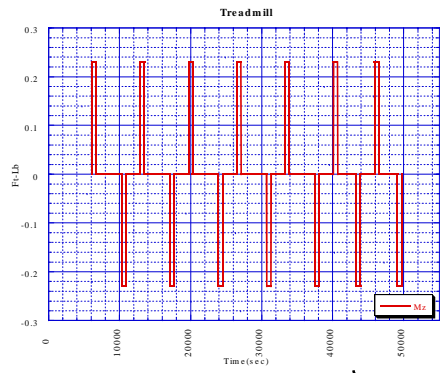


Combined Force

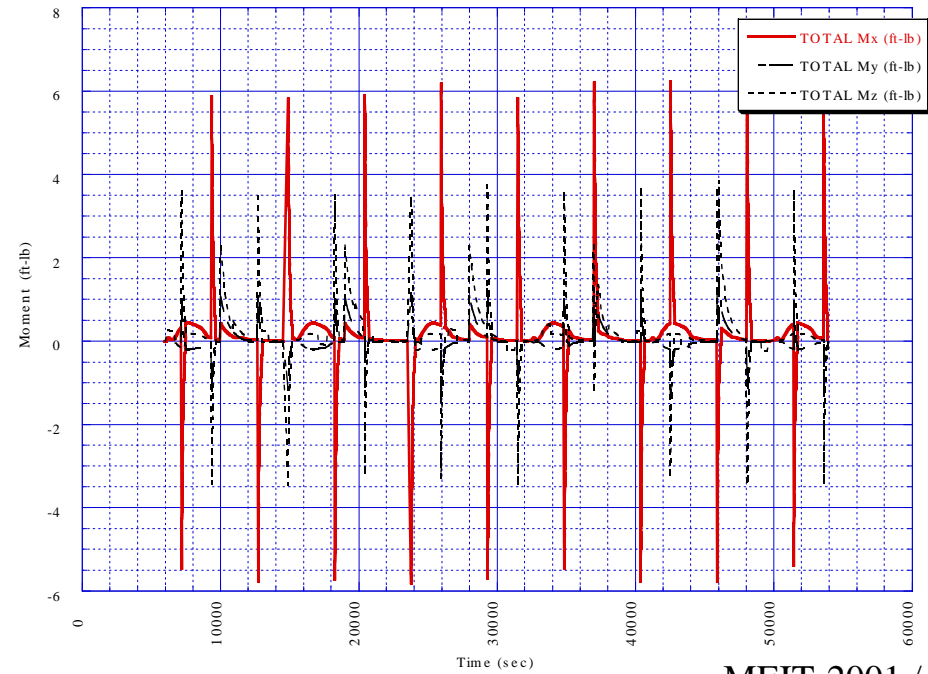


**Force files  
combined into one  
file**

# DAC8 Quasi-steady Individual Disturbance Inputs



## COMBINED MOMENTS



**Moments combined into one file**





# DAC8 Quasi-Steady Performance With Individual Disturbances Delta Comparison



**14 versus 15 of 32 racks under 1  $\mu\text{g}$  magnitude and .2  $\mu\text{g}$  perpendicular component (APM AFT1 to 1.068 & 0.22)**

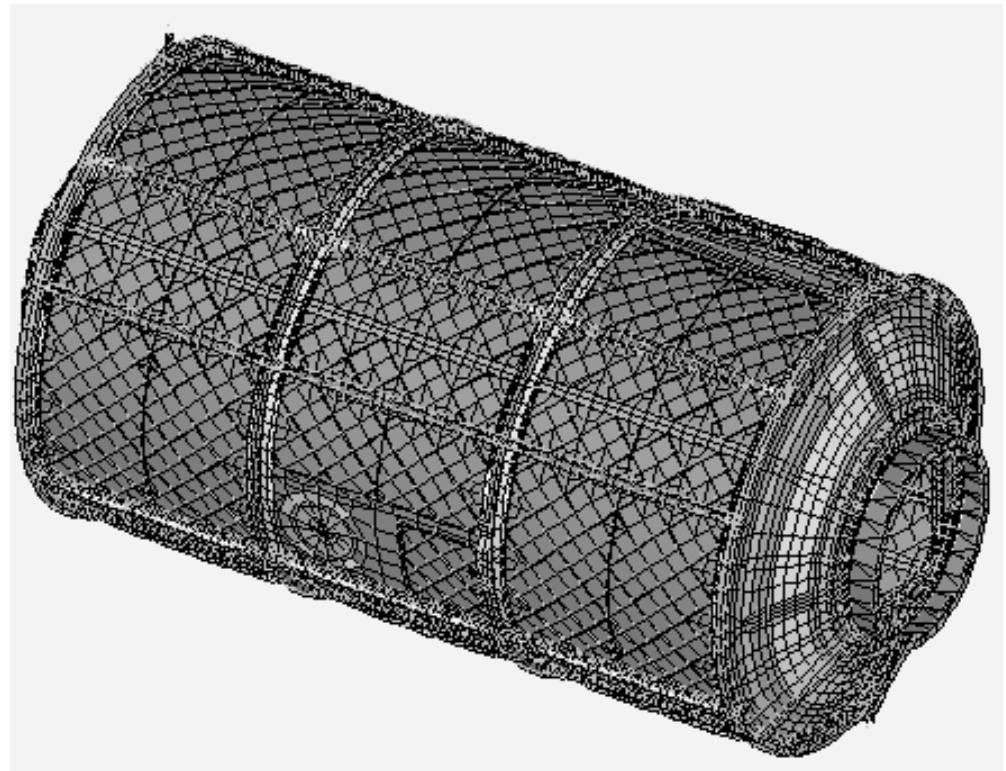
Location	Magnitude Disturbance ( $\mu\text{G}$ )	Magnitude Nominal ( $\mu\text{G}$ )	Magnitude Delta Dist-Nom ( $\mu\text{G}$ )	Mag % Difference	$\perp$ Component Disturbance ( $\mu\text{G}$ )	$\perp$ Component Nominal ( $\mu\text{G}$ )	$\perp$ Component Delta Dist-Nom ( $\mu\text{G}$ )	$\perp$ Component % Difference
CG	0.211	0.210	0.001	0%	0.080	0.046	0.203	74%
USL-C1	0.293	0.245	0.048	20%	0.158	0.064	0.094	147%
USL-C2	0.269	0.232	0.037	16%	0.150	0.063	0.087	138%
USL-C3	0.258	0.230	0.028	12%	0.140	0.070	0.070	100%
USL-C4	0.259	0.243	0.016	7%	0.128	0.078	0.050	64%
USL-C5	0.293	0.266	0.027	10%	0.116	0.084	0.032	38%
USL-S1	0.711	0.689	0.022	3%	0.170	0.087	0.083	95%
USL-S2	0.668	0.645	0.023	4%	0.156	0.086	0.070	81%
USL-S3	0.625	0.602	0.023	4%	0.142	0.084	0.058	69%
USL-S4	0.584	0.560	0.024	4%	0.128	0.083	0.045	54%
USL-P1	0.791	0.722	0.069	10%	0.139	0.088	0.051	58%
USL-P2	0.735	0.671	0.064	10%	0.127	0.087	0.040	46%
USL-P4	0.623	0.570	0.053	9%	0.105	0.085	0.020	24%
JPM1-A1	1.132	1.035	0.097	9%	0.150	0.091	0.059	65%
JPM2-F1	1.293	1.193	0.100	8%	0.188	0.093	0.095	102%
JPM3-A2	1.225	1.121	0.104	9%	0.153	0.092	0.061	66%
JPM4-F2	1.383	1.274	0.109	9%	0.172	0.094	0.078	83%
JPM5-A3	1.327	1.217	0.110	9%	0.157	0.092	0.065	71%
JPM6-F3	1.480	1.364	0.116	9%	0.174	0.094	0.080	85%
JPM7-A4	1.435	1.320	0.115	9%	0.162	0.093	0.069	74%
JPM8-A5	1.547	1.429	0.118	8%	0.168	0.093	0.075	81%
JPM9-F5	1.691	1.566	0.125	8%	0.183	0.095	0.088	93%
JPM10-F6	1.804	1.675	0.129	8%	0.189	0.096	0.093	97%
APM-CLG1	0.710	0.517	0.193	37%	0.151	0.089	0.062	70%
APM-CLG2	0.856	0.640	0.216	34%	0.133	0.093	0.040	43%
APM-FWD1	1.184	1.078	0.106	10%	0.268	0.094	0.174	185%
APM-FWD2	1.283	1.146	0.137	12%	0.259	0.095	0.164	173%
APM-FWD3	1.393	1.229	0.164	13%	0.249	0.096	0.153	159%
APM-FWD4	1.513	1.326	0.187	14%	0.242	0.098	0.144	147%
APM-AFT1	1.068	0.963	0.105	11%	0.219	0.092	0.127	138%
APM-AFT2	1.176	1.045	0.131	13%	0.211	0.094	0.117	124%
APM-AFT3	1.296	1.142	0.154	13%	0.206	0.095	0.111	117%
APM-AFT4	1.423	1.251	0.172	14%	0.206	0.098	0.108	110%
CAM-MID	0.650	0.608	0.042	7%	0.238	0.091	0.147	162%
CAM-TOP	1.100	1.077	0.023	2%	0.252	0.092	0.160	174%

# DAC8 Finite Element Model

## US Lab Model Frequencies

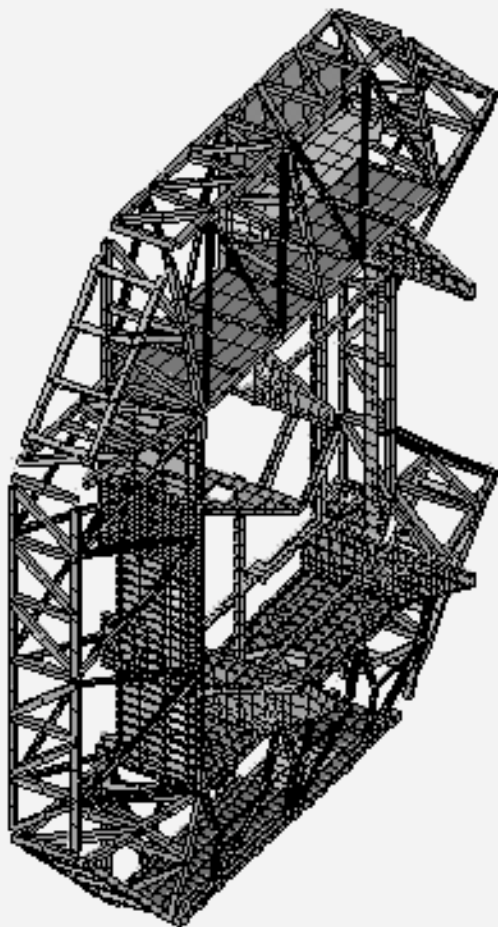
### Integrated US Lab Model

9.29E-04	Rigid Body Mode
1.60E-03	Rigid Body Mode
2.06E-03	Rigid Body Mode
2.33E-03	Rigid Body Mode
2.69E-03	Rigid Body Mode
3.93E-03	Rigid Body Mode
2.39E+00	
2.83E+00	
2.89E+00	
2.99E+00	
3.04E+00	
3.08E+00	
3.12E+00	
3.29E+00	
3.39E+00	
3.62E+00	
3.75E+00	
4.04E+00	

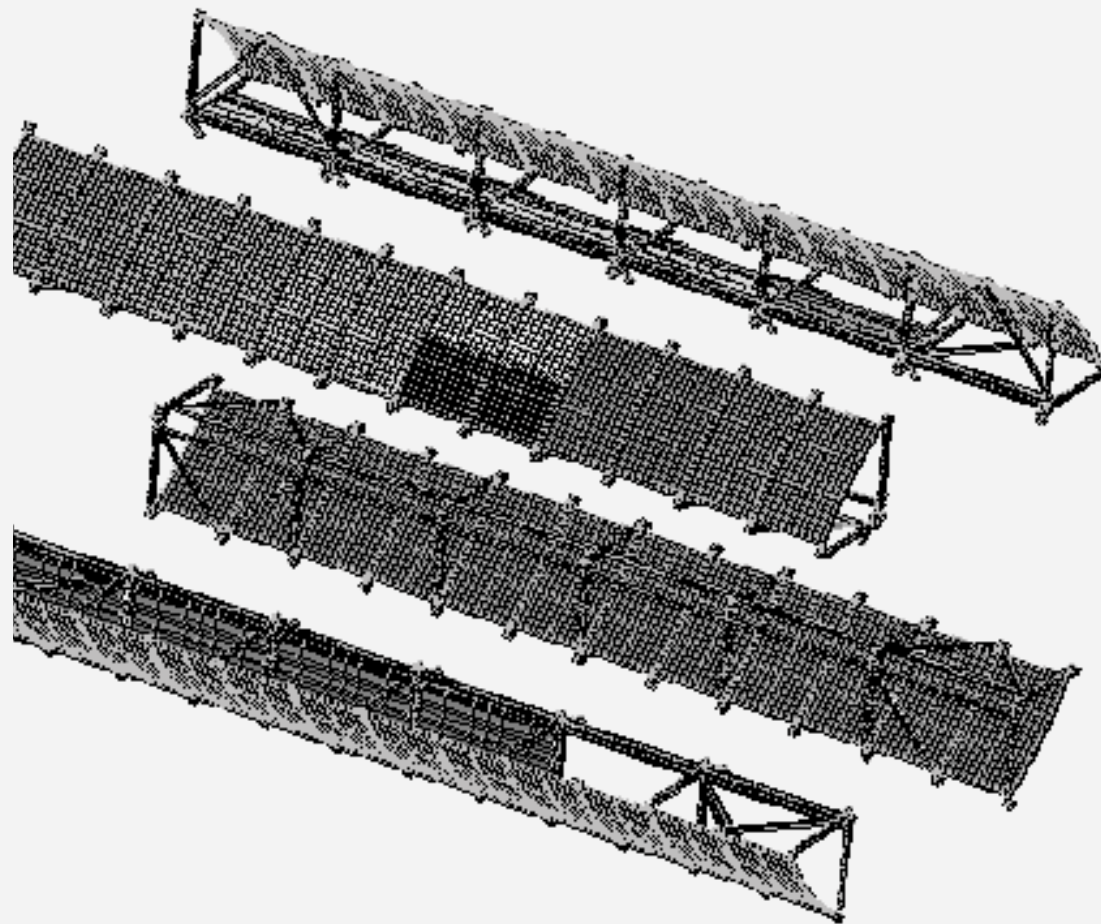


# DAC8 Finite Element Model

**Aft ESS**

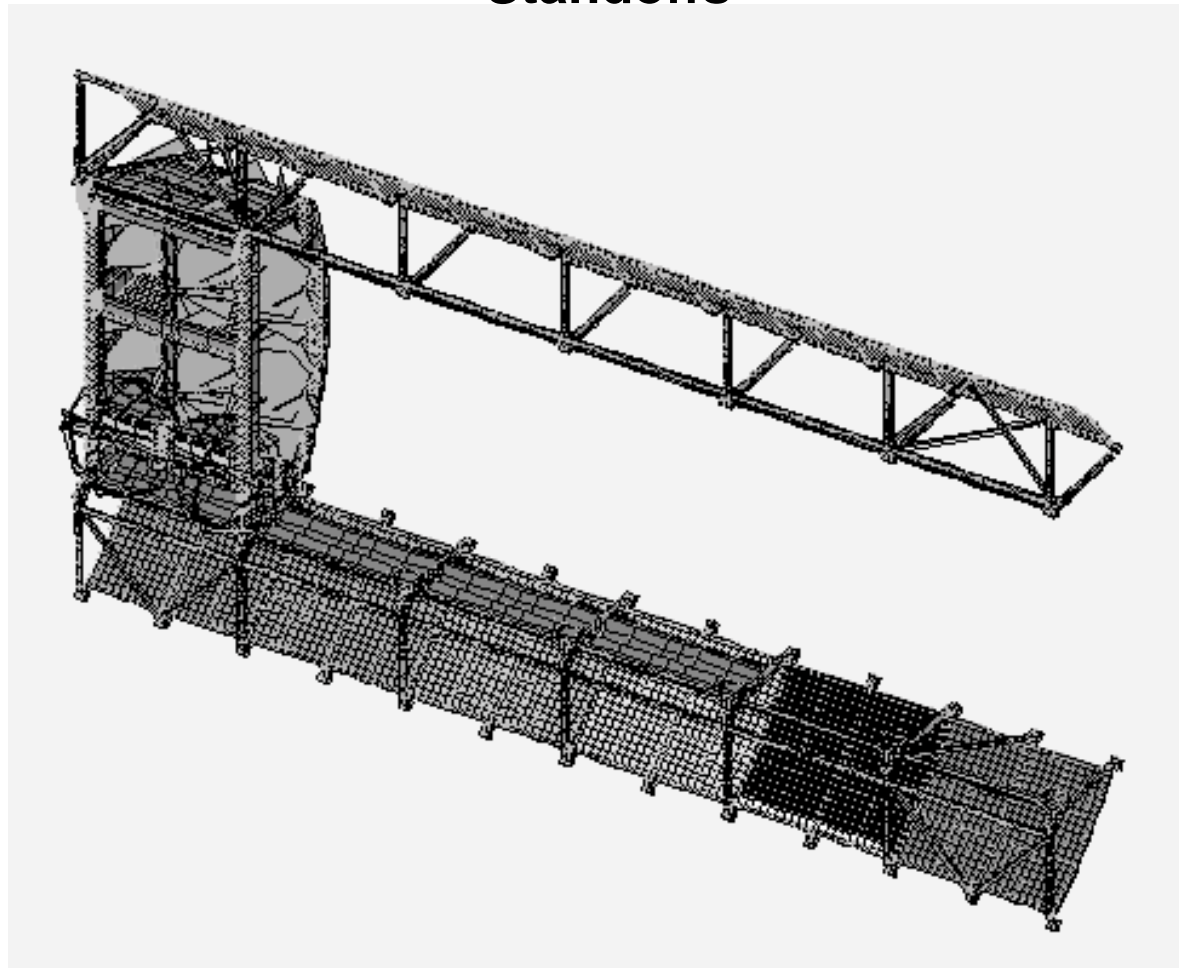


**Standoffs**



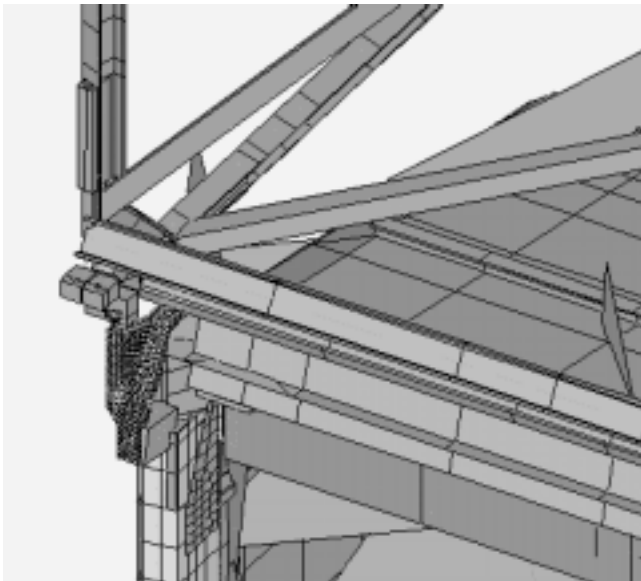
## DAC8 Finite Element Model

### Rack Integrated with Standoffs

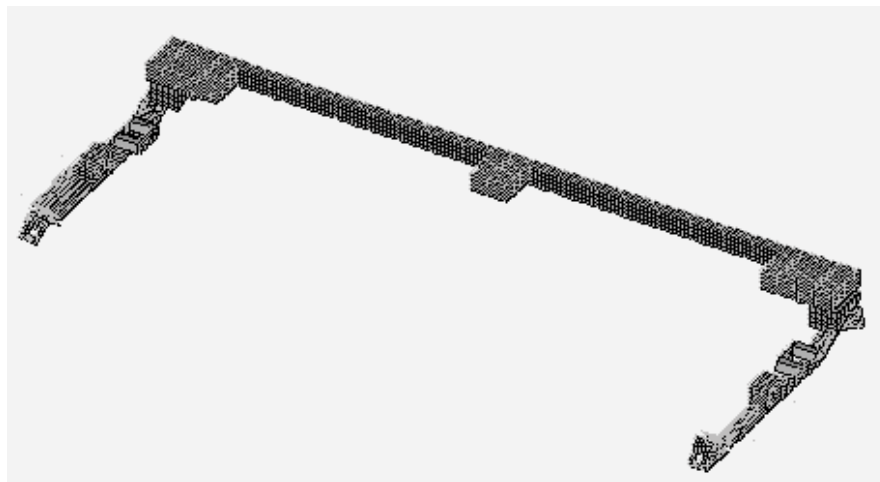
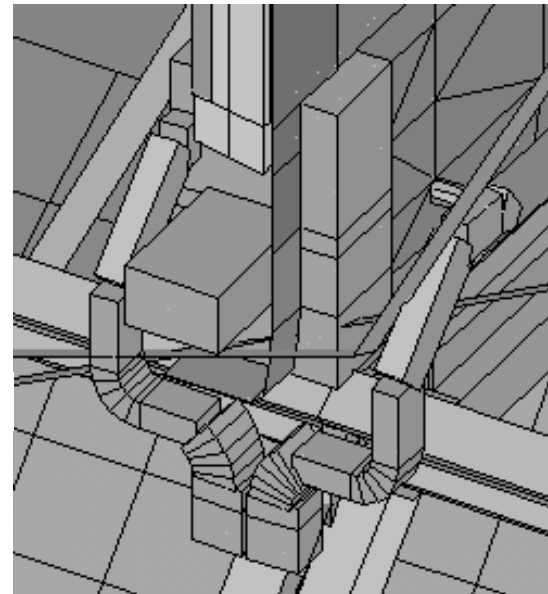


# DAC8 Finite Element Model

**K-Bar**



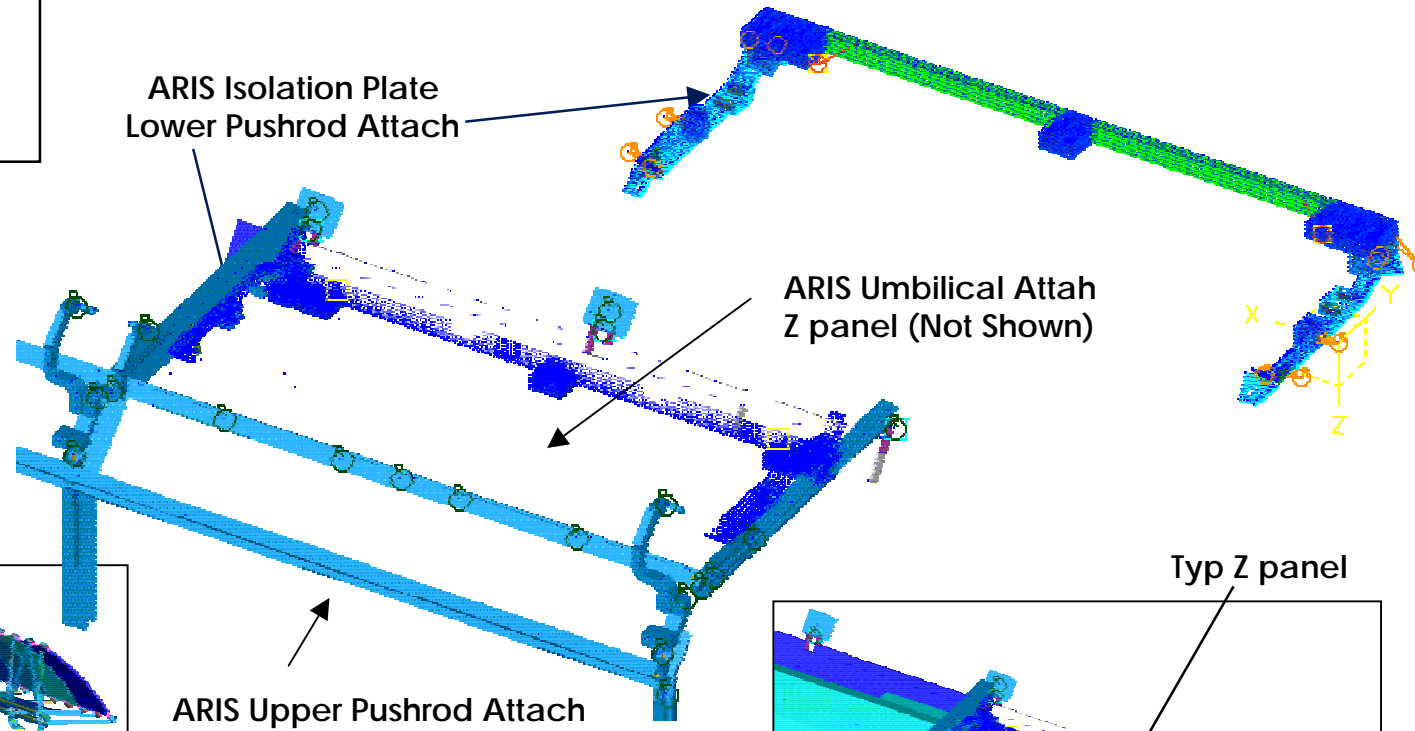
**Pivot Pins**



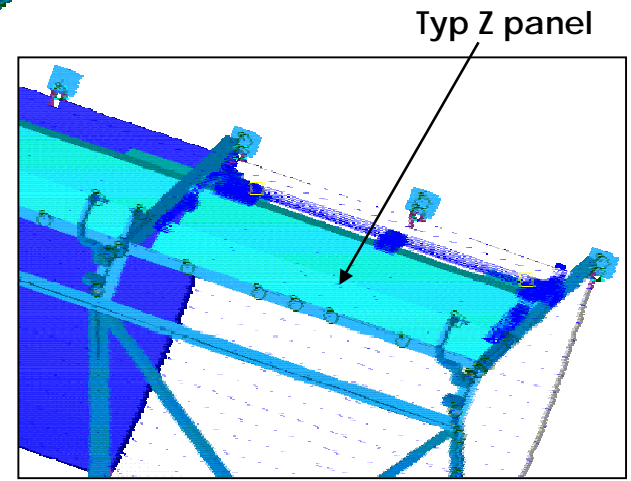
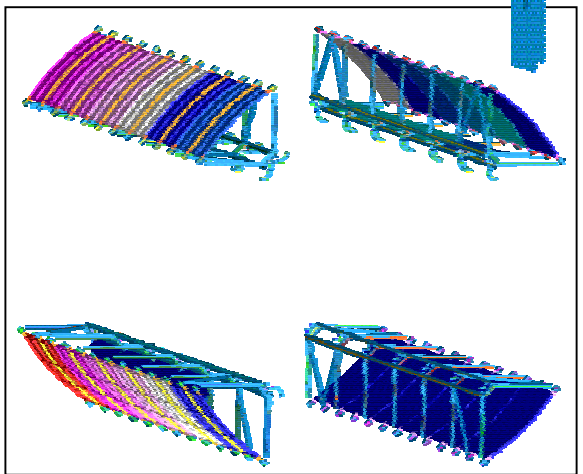
**Isolation  
Plate**

# Requirement Applicability

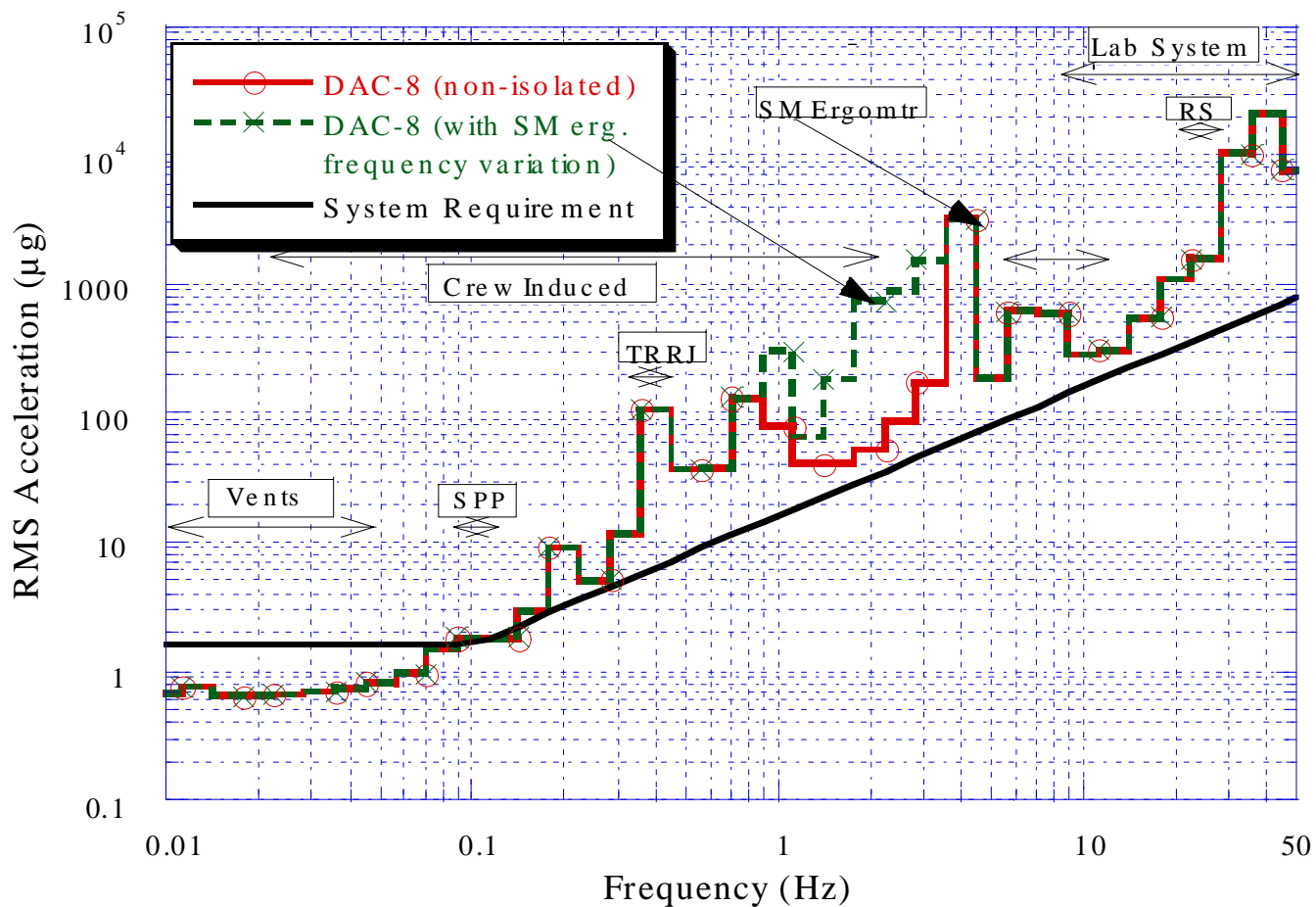
@ 50% Of ISPRs In  
APM/JEM/LAB  
Vibratory @ Rack To Module  
Interface



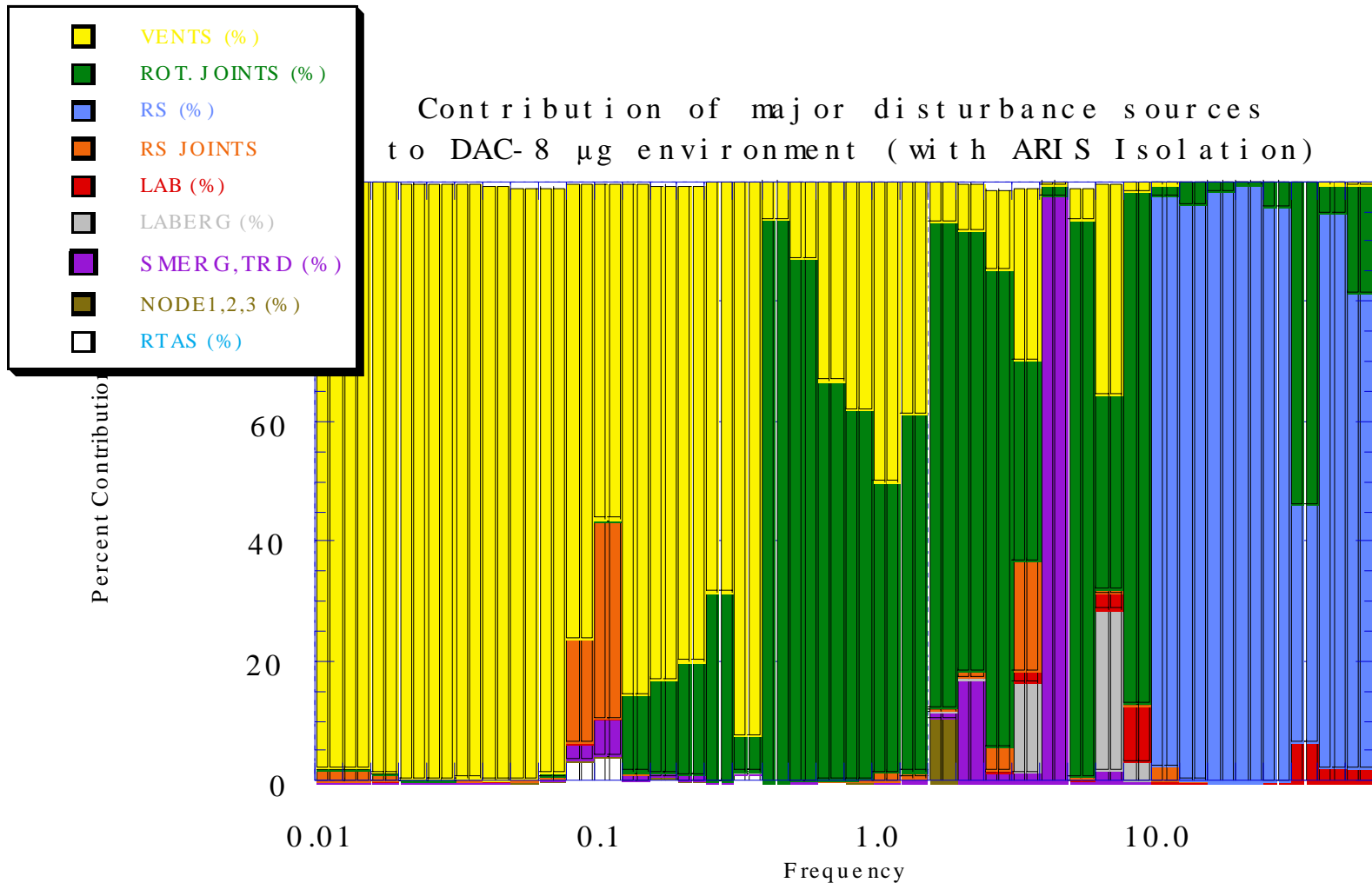
Lab Standoffs



# DAC8 Non-Isolated Performance Structural Dynamic Frequency Range



# DAC8 Performance Structural Dynamic Frequency Range



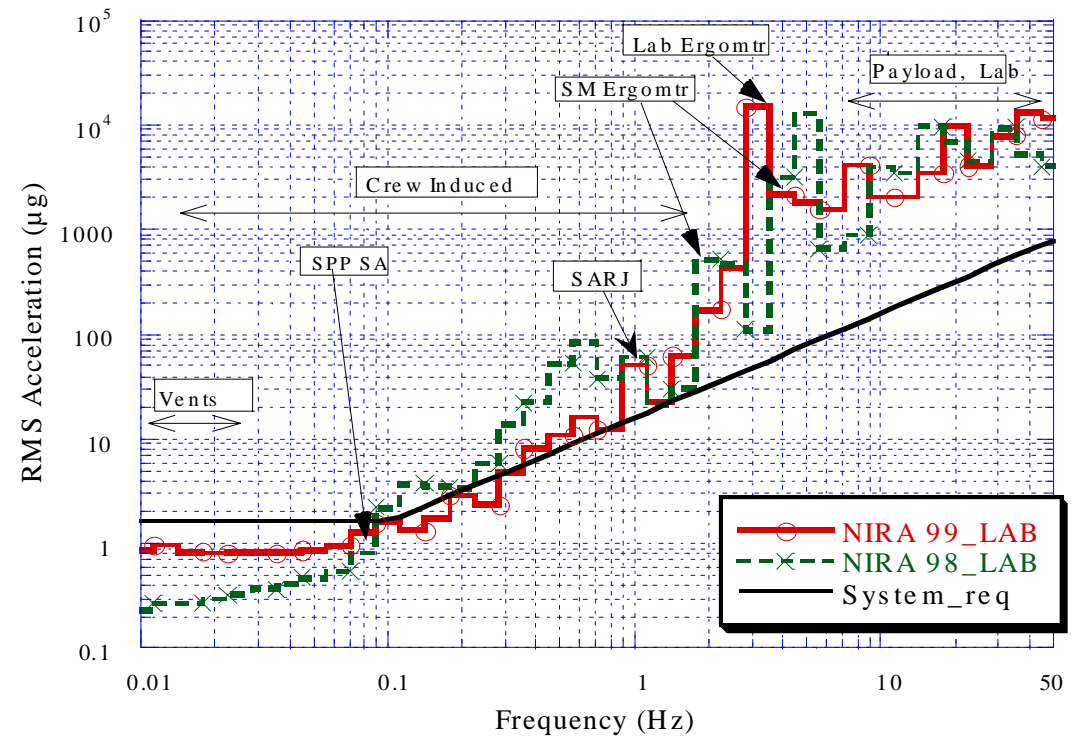




# NIRA 99 - US Lab Structural Dynamic Frequency Range

## Non-Isolated Rack Assessment Differences From DAC8 Requirement Compliance Results

- 1% Damping
- + 2Crew translations & 2console ops
- + Payload disturbances (8 racks in Lab, 3 in COF and 2 in JEM)(21 sources per rack includes AAA fan.)
- @ Non-isolated rack interfaces
- Non-isolated Lab ergometer - subsequently isolated (see DAC8)



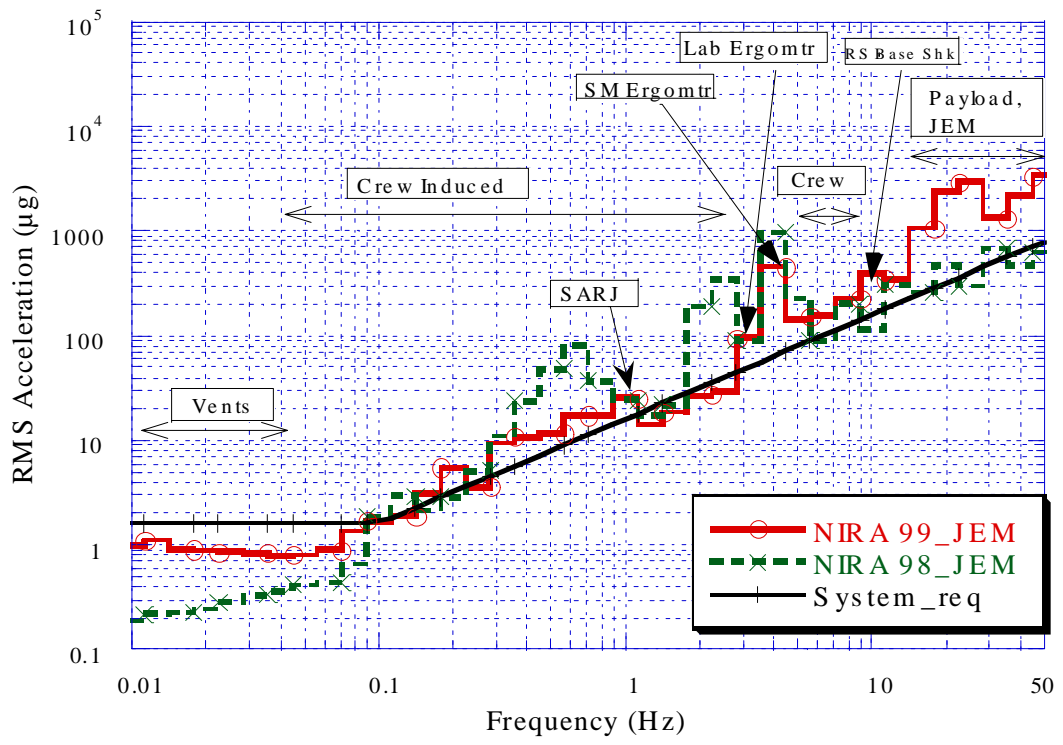


# NIRA 99 - JEM-PM

## Structural Dynamic Frequency Range

### Non-Isolated Rack Assessment Differences From DAC8 Requirement Compliance Results

- 1% Damping
- + 2Crew translations & 2console ops
- + Payload disturbances (8 racks in Lab, 3 in COF and 2 in JEM)(21 sources per rack includes AAA fan.)
- @ Non-isolated rack interfaces
- Non-isolated Lab ergometer - subsequently isolated (see DAC8)



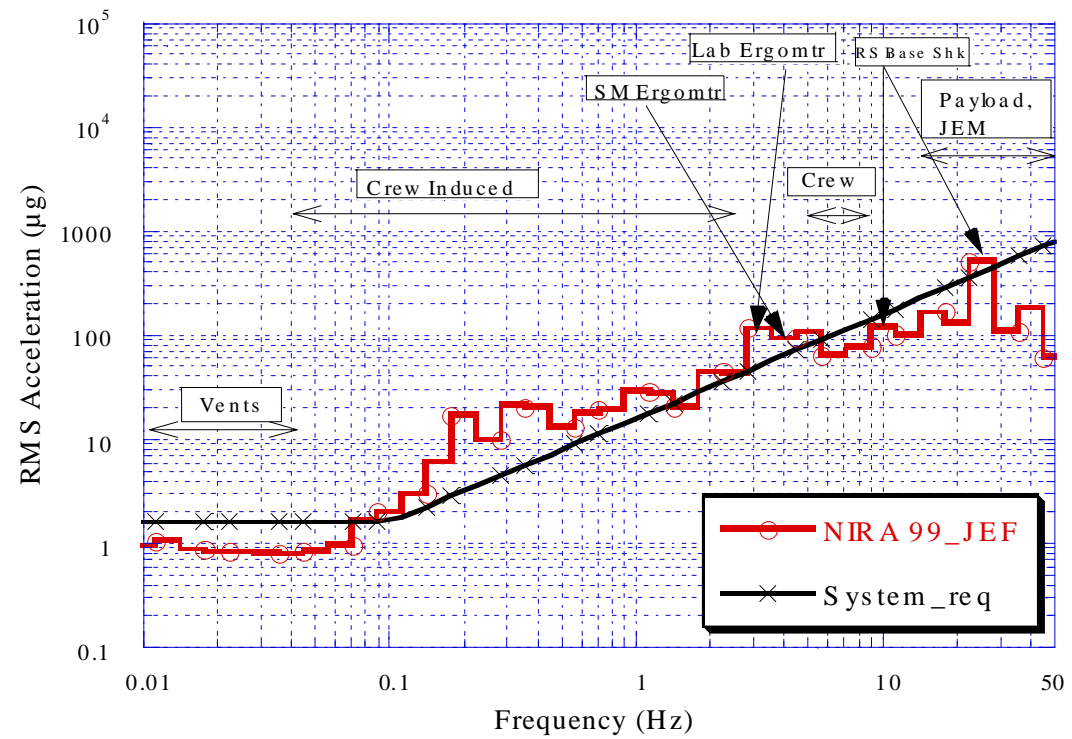


# NIRA 99 - JEM-EF

## Structural Dynamic Frequency Range

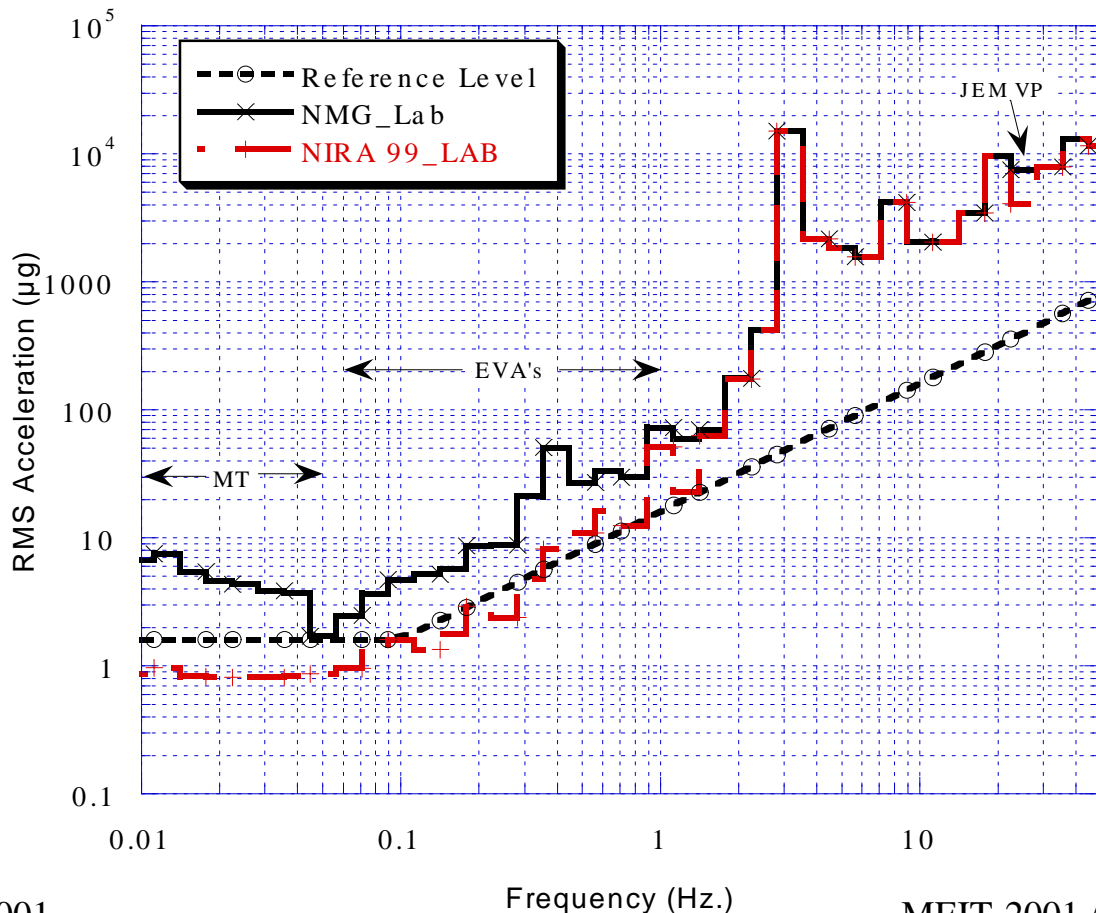
### Non-Isolated Rack Assessment Differences From DAC8 Requirement Compliance Results

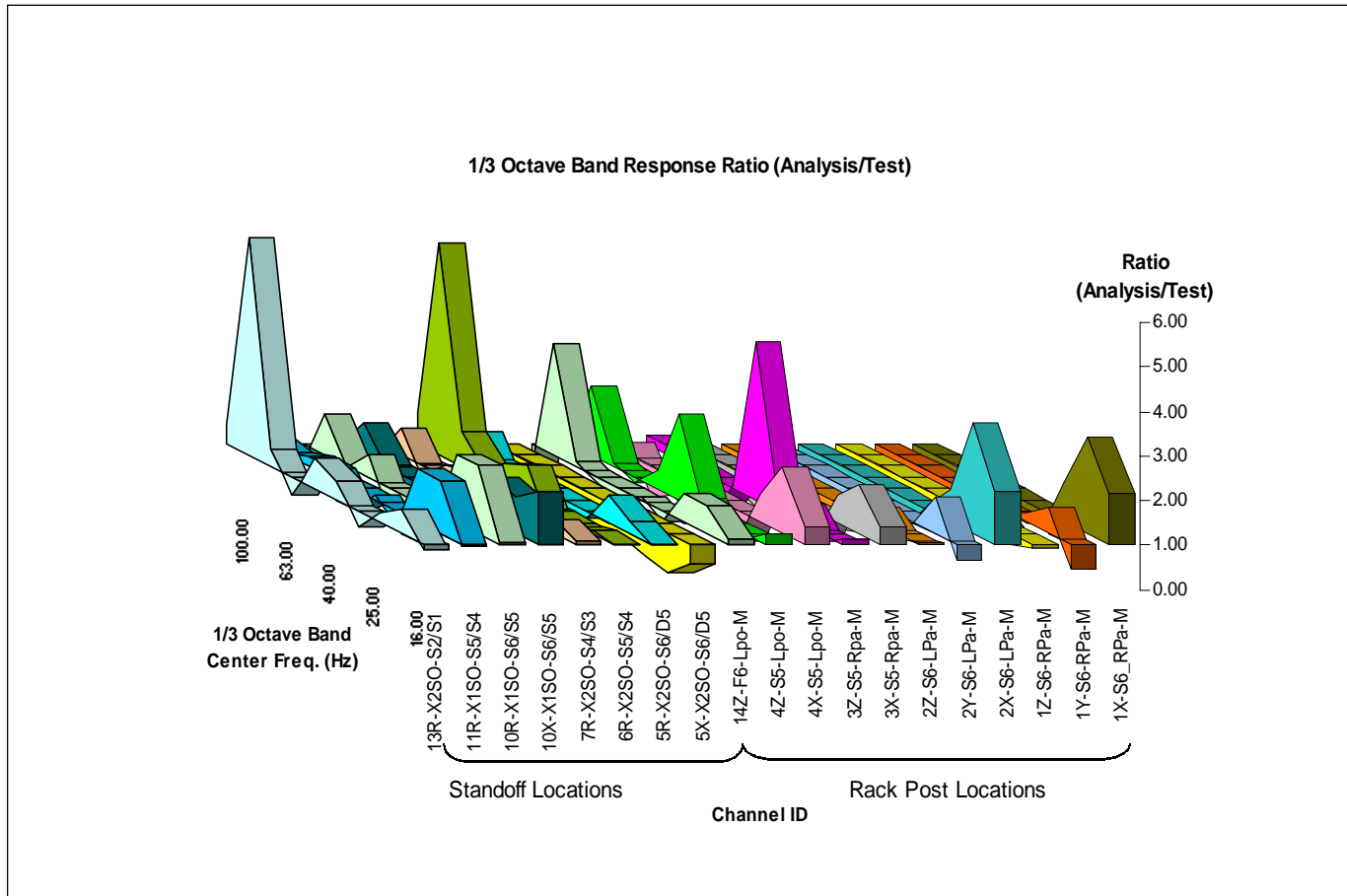
- 1% Damping
- + 2Crew translations & 2console ops
- + Payload disturbances (8 racks in Lab, 3 in COF and 2 in JEM)(21 sources per rack includes AAA fan.)
- @ Non-isolated rack interfaces
- Non-isolated Lab ergometer - subsequently isolated (see DAC8)



## Non-Microgravity Mode Differences From NIRA-99

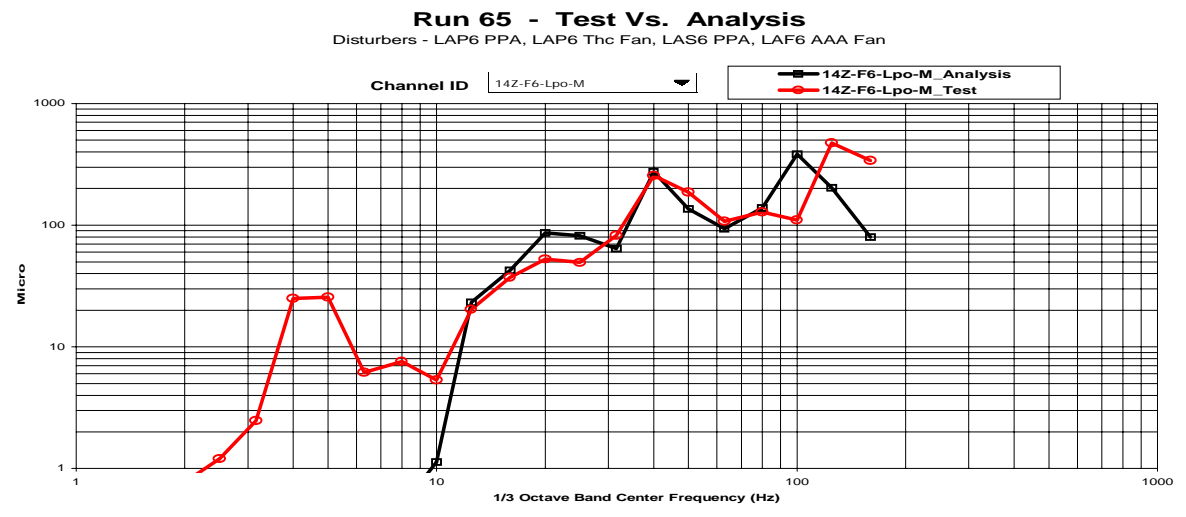
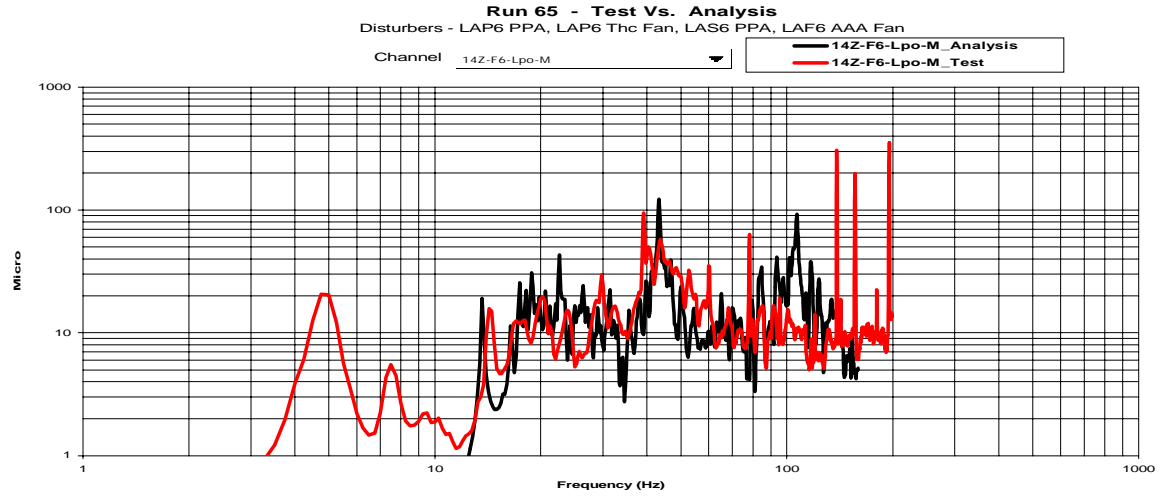
- Add non-microgravity mode disturbances to NIRA-99
- External Operations Case presented includes 2 EVA's, JEM Airlock and Mobile Transporter ops
- Other cases examined focused on thruster activity - reboost, CMG de-saturation, attitude hold
- Cases still to be examined: docking, berthing, rack rotation, et cetera





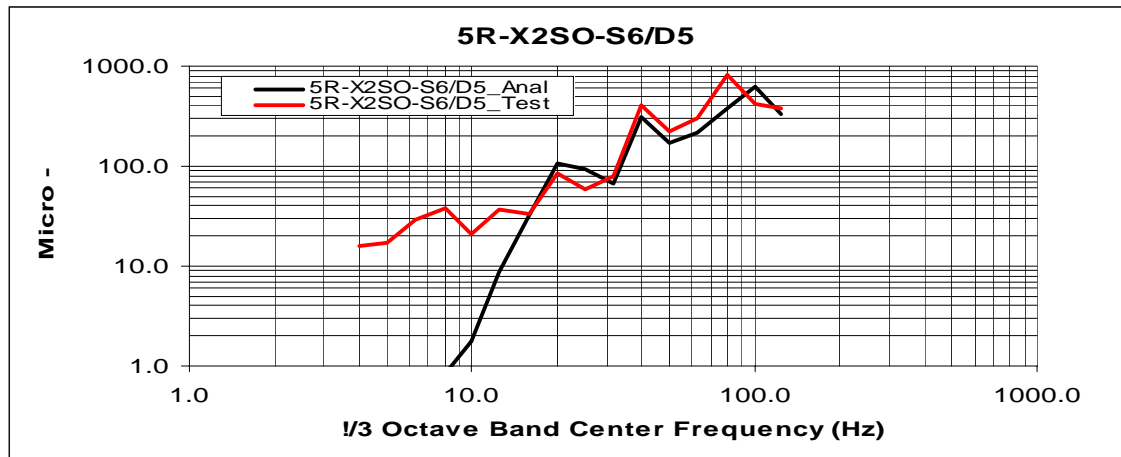
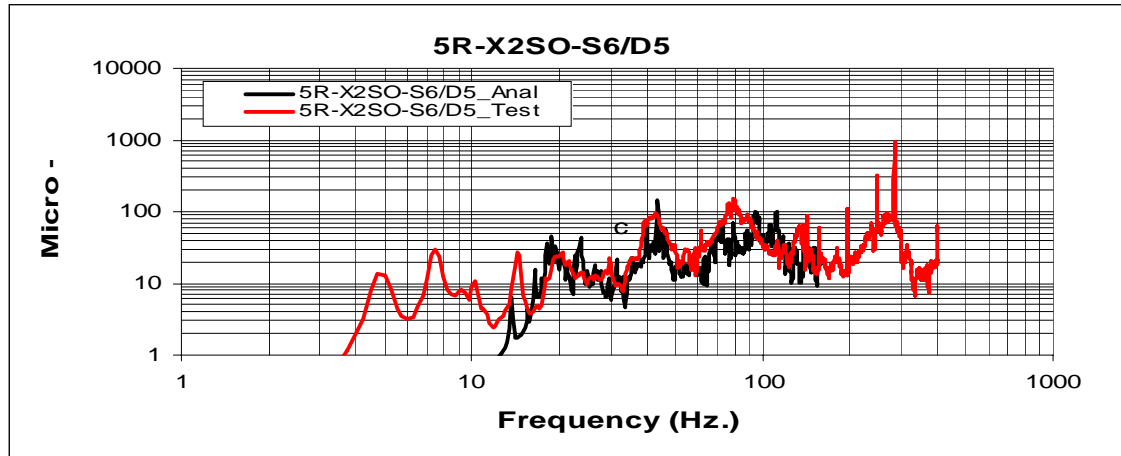


# U.S. Lab Ground Test To Analysis Comparison Rack F6 Response

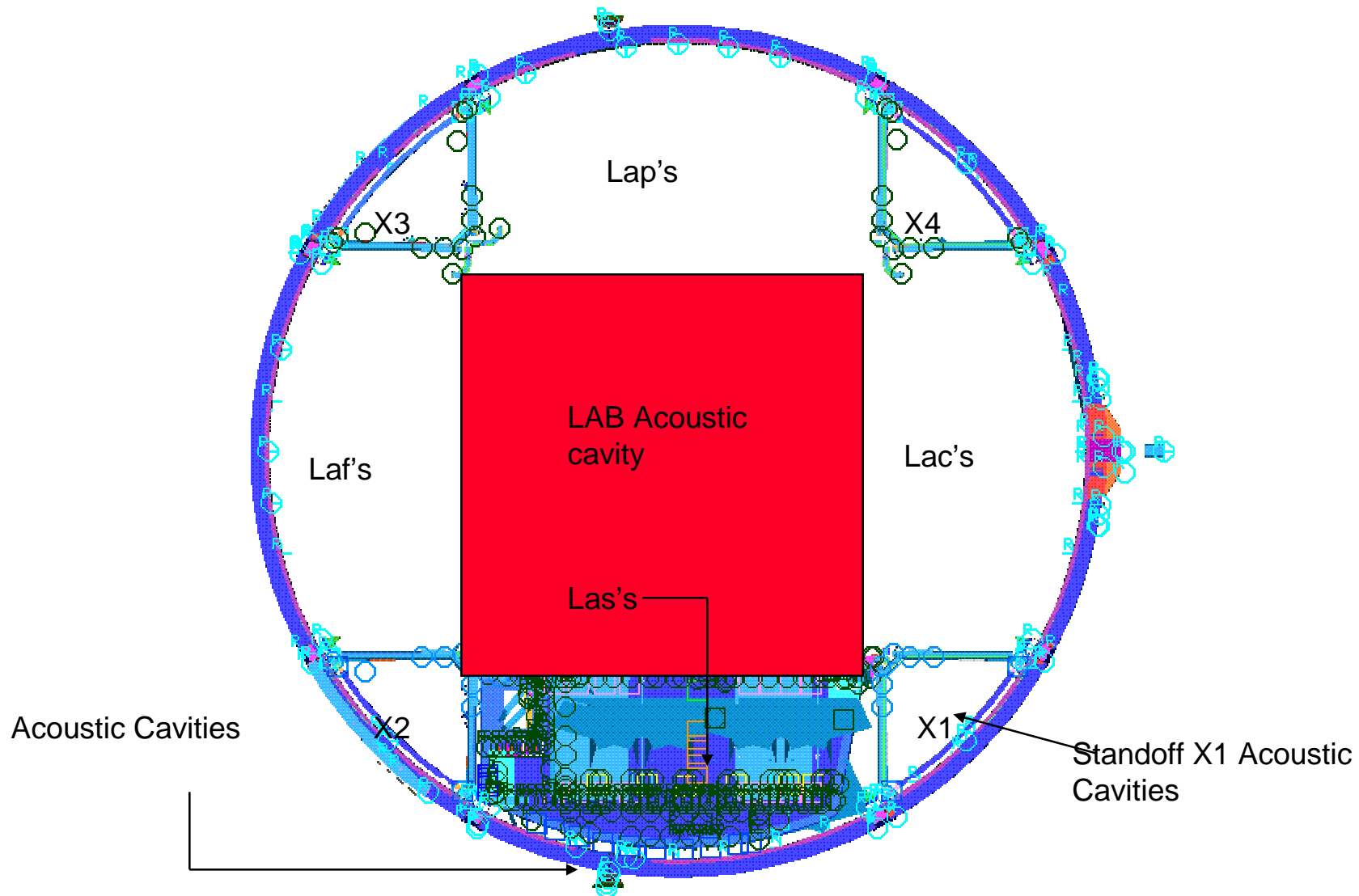




# U.S. Lab Ground Test To Analysis Comparison Standoff S6/S5 Response

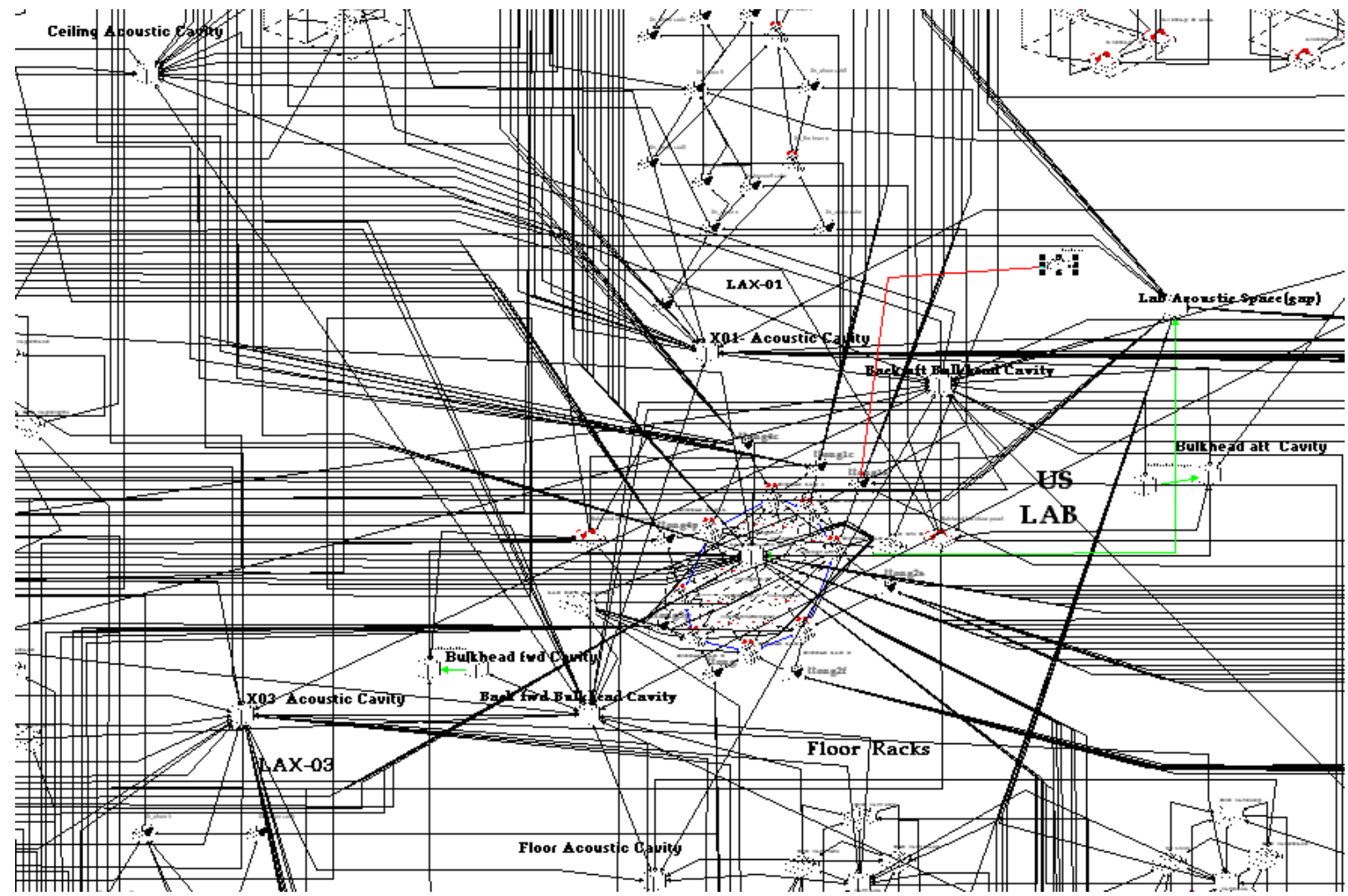


# DAC8 Statistical Energy Analysis Model



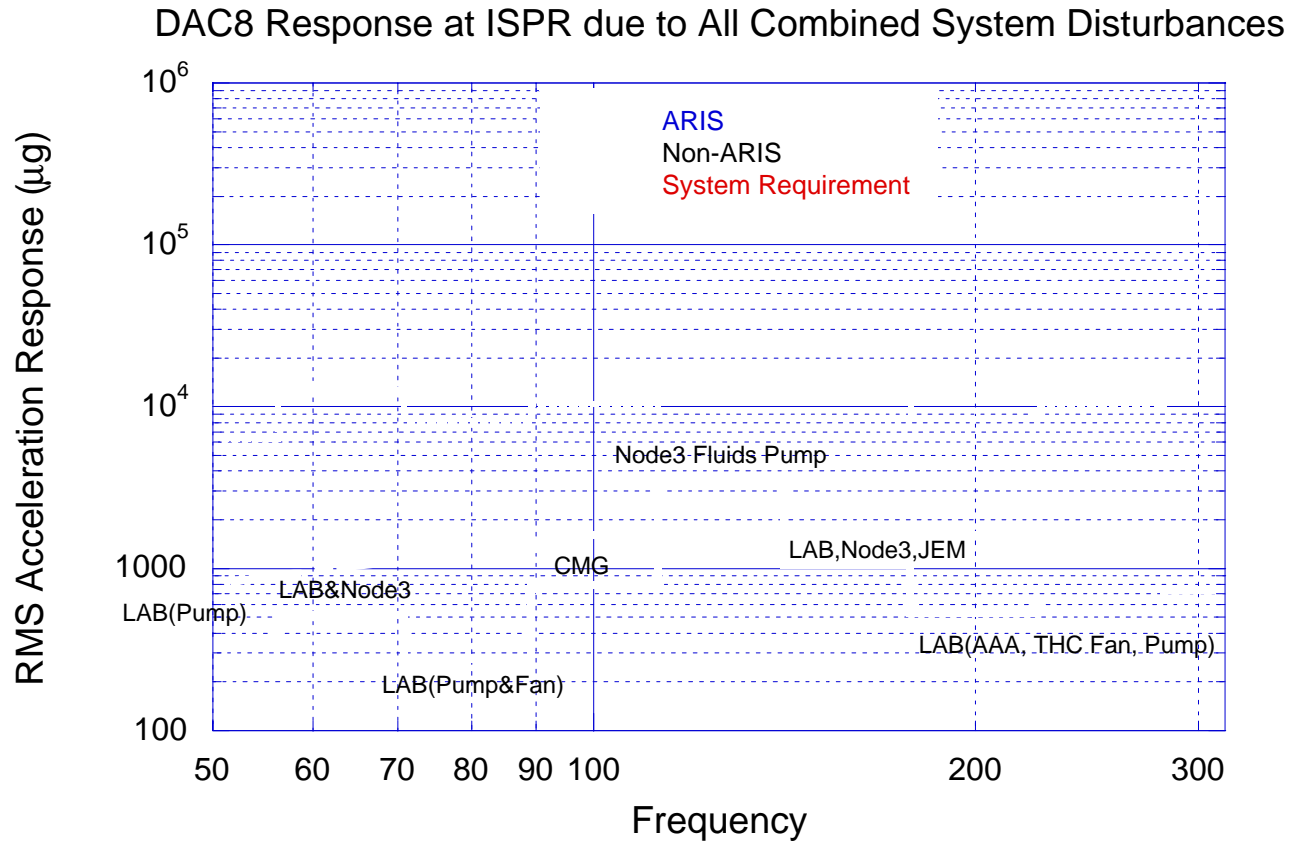


# DAC8 Statistical Energy Analysis Model

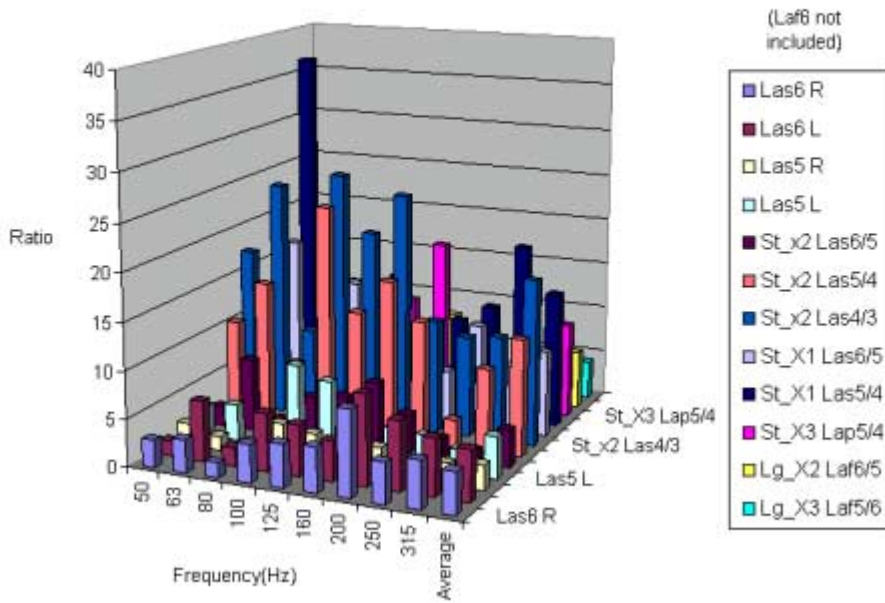




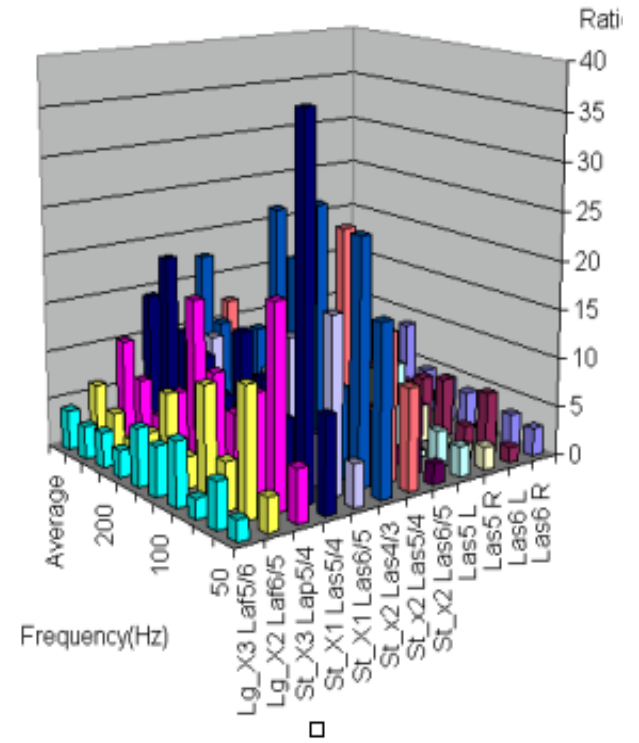
# DAC8 Performance Vibroacoustic Frequency Range



SEA/TEST Response Ratio to DAC8 USL Equipment Operating (No CDRA)



SEA/TEST Response Ratio to DAC8 USL Equipment Operating

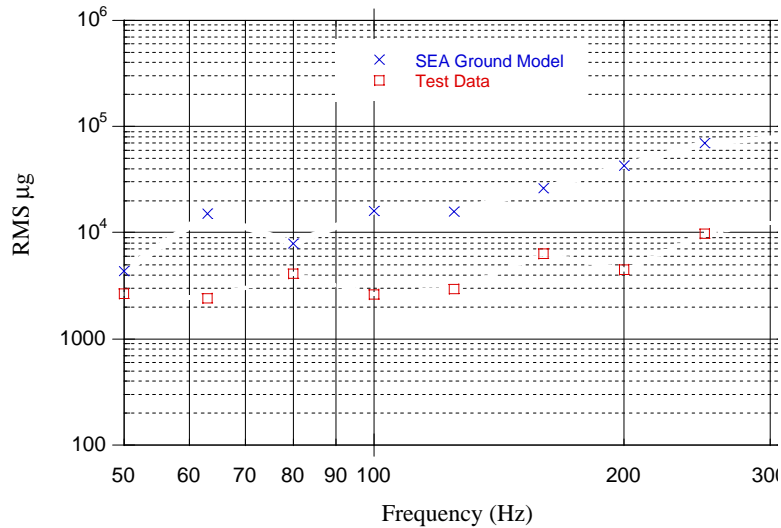




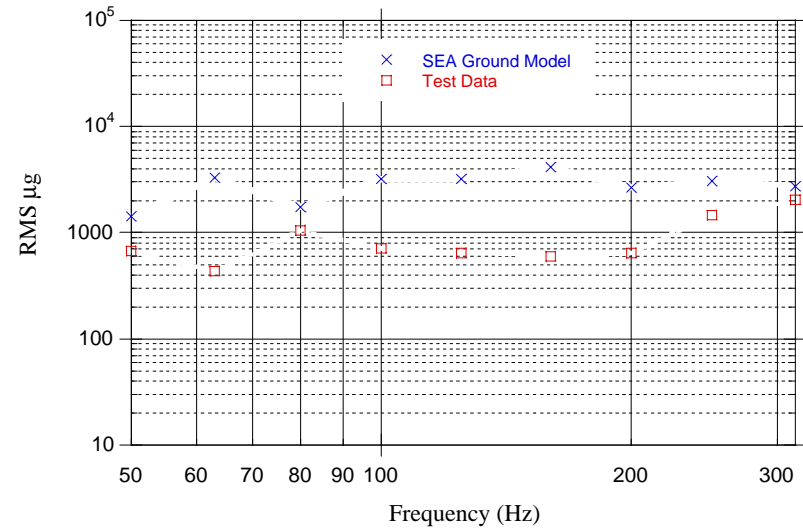
# U.S. Lab Ground Test To Analysis Comparison Rack and Standoff Response



LAB Test Correlation with SEA Ground Test Model  
Input @ All USL Equipment Operating (No CDRA)  
Output @ Las6 Left Post (Rss Ch's 4,5,6)



LAB Test Correlation with SEA Ground Test Model  
Input @ All USL Equipment Operating (No CDRA)  
Output @ Standoff X2 Las5/Las6 (Rss Ch's 13,14 )

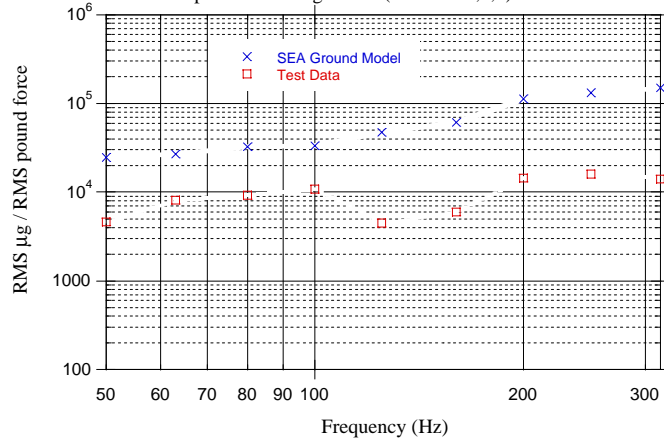




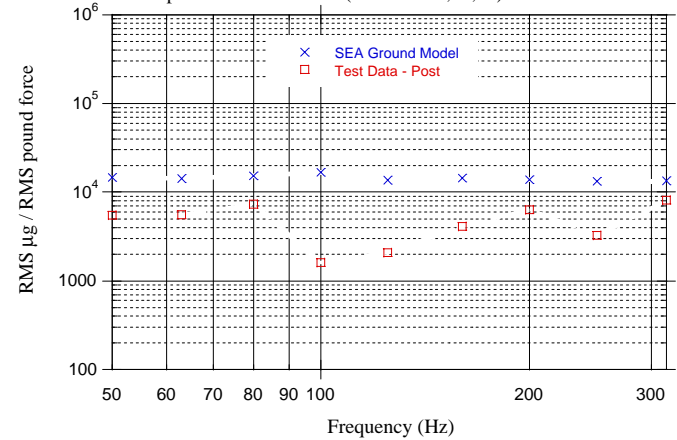
# U.S. Lab Ground Test To Analysis Comparison Transfer Functions



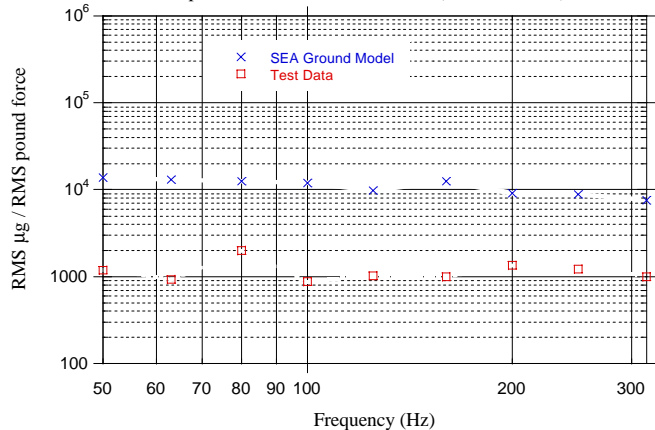
LAB Test Correlation with SEA Ground Test Model  
Input @ Las6 Left Post (Ch 5)  
Output @ Las6 Right Post (Rss Ch's 1,2,3)



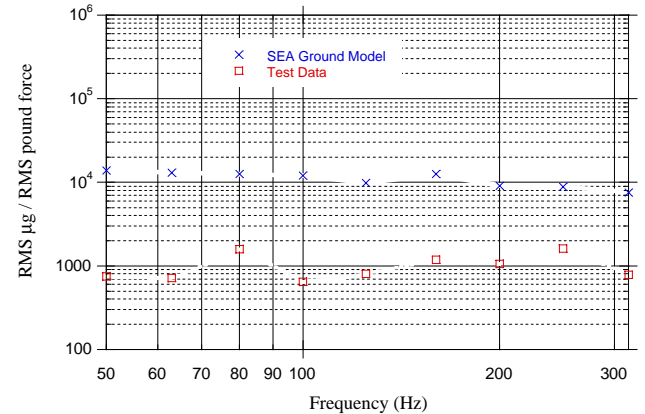
LAB Test Correlation with SEA Ground Test Model  
Input @ Las6 Left Post (Ch 5)  
Output @ Las5 Left Post (Rss Ch's 10,11,12)



LAB Test Correlation with SEA Ground Test Model  
Input @ Las5 Left Post (Ch 11)  
Output @ Standoff x2 & Las5/las6 (Rss Ch's 13,14)

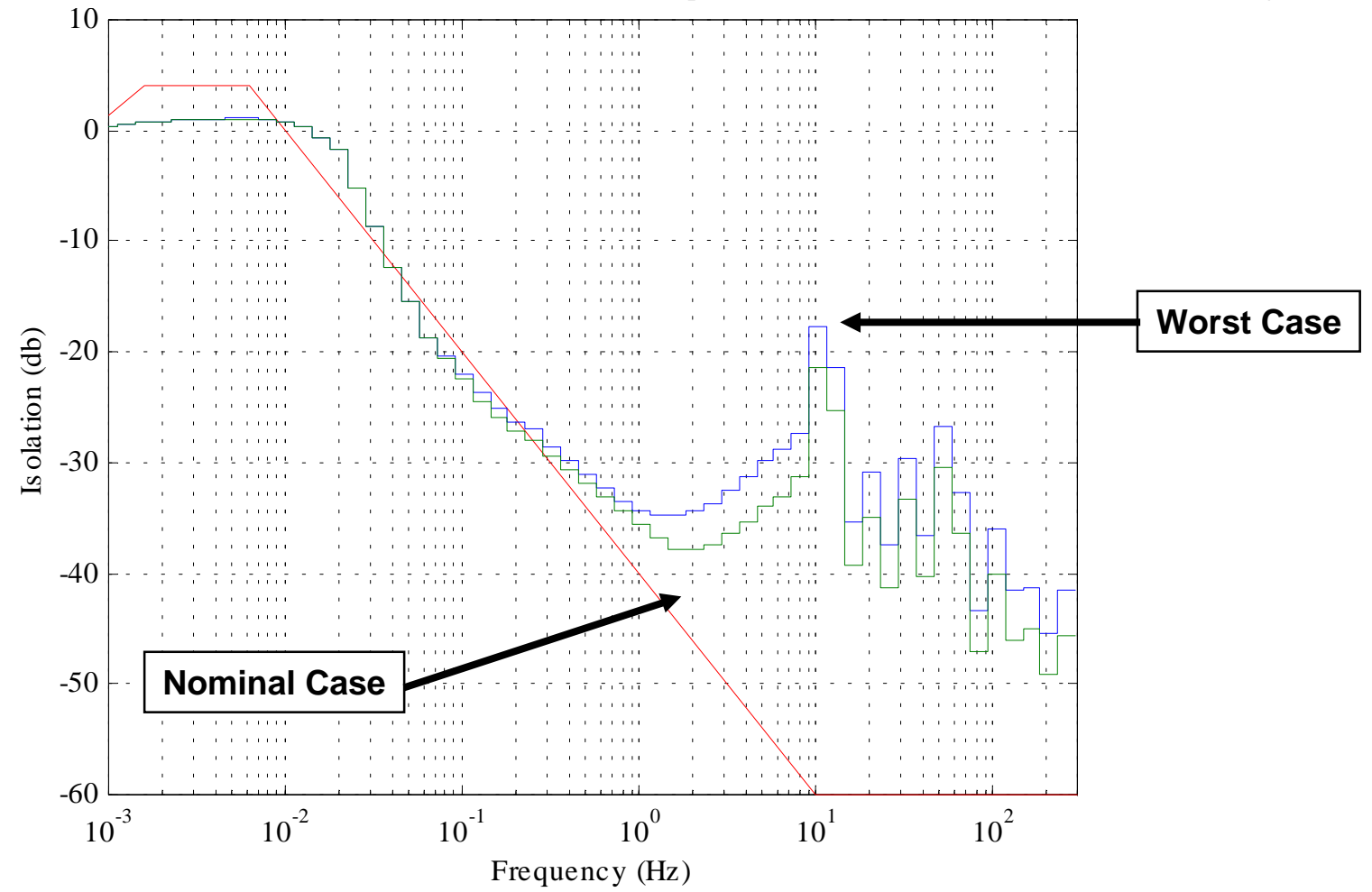


LAB Test Correlation with SEA Ground Test Model  
Input @ Las5 Left Post (Ch 11)  
Output @ Standoff x2 & Las5/Las4 (Ch 15)

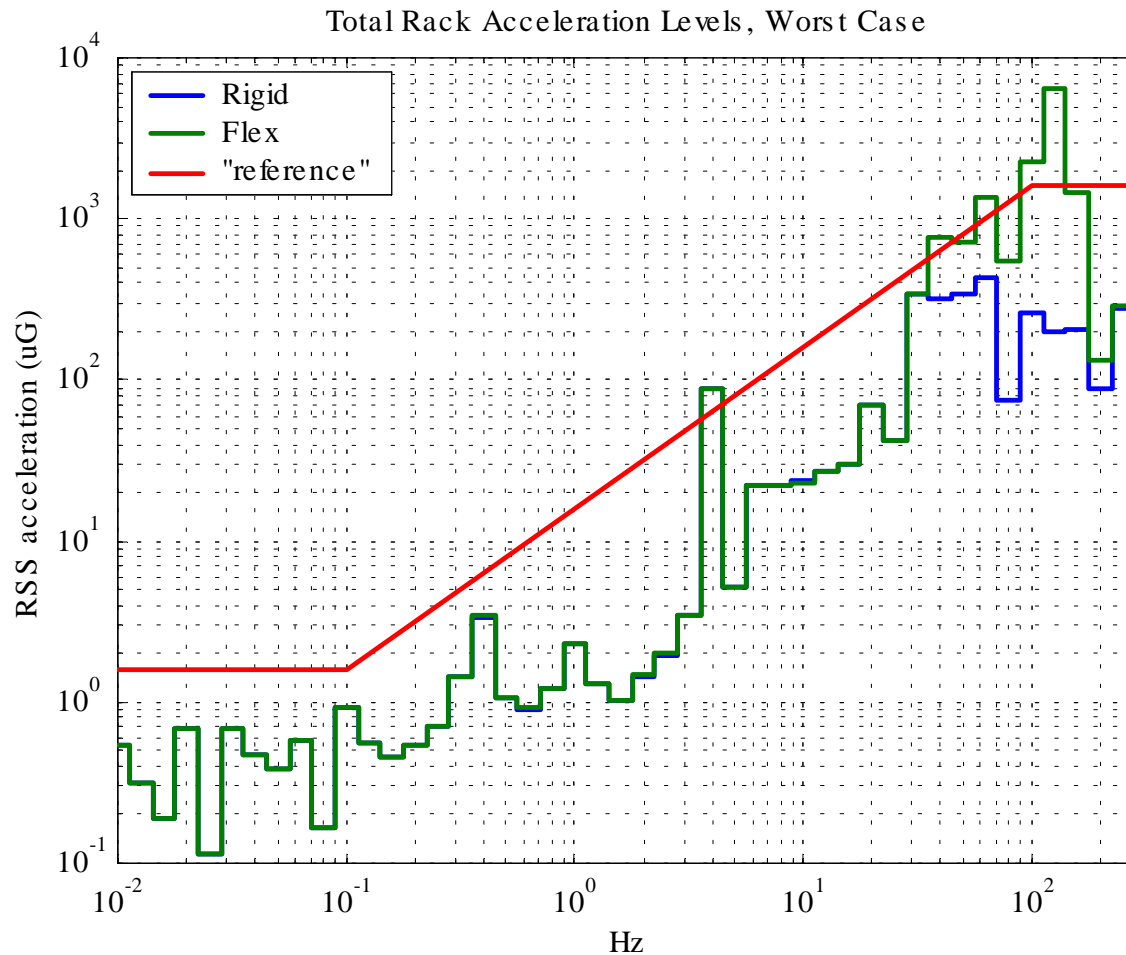


# ARIS Isolation Performance

Worst case & Nominal isolation, CG Variations, Worst VP, Worst Input Direction, Worst Ksmall corner 3 or 5, Rigid Rack



# Total Isolated Rack Acceleration Levels (ARIS Verification Conditions)





## Summary



**The ISS vehicle has been designed to provide researchers a viable microgravity environment established jointly with the science community.**

- **Features:**
  - Laboratories located near the vehicle center of mass
  - Articulating photovoltaic and radiator appendages to enable once per orbit vehicle rotation
  - Non-propulsive attitude control
  - Source isolated exercise equipment
  - Receiver isolation systems
  - Microgravity Mode operations
  
- **Design Convergence:**
  - Requirements
  - Control Plan
  - Key Ground Tests
    - Control Moment Gyros
    - Rotating Joints
    - Node1
    - Service Module
    - Lab
    - COF sub-systems
  - Verification





## Summary (continued)

---

---

**Initial payload microgravity requirements have been approved for the non-isolated, pressurized payloads.**

**Key threats & planned/recommended countermeasures:**

- **ARIS isolation performance - “Shake down” experiment on flight 6A - “ARIS ICE”.**
- **Service Module air conditioner compressor non-compliance - Approved ground test and on-orbit installation of vibration mounts and extended fluid flex lines.**
- **Service Module ergometer non-compliance with verified ARIS performance. - Pursue early measurements to confirm predictions and resolve if necessary.**
- **U.S. Lab ergometer non-compliance due to rack to pivot pin impact. - - Pursue early measurements to confirm predictions and resolve if necessary.**
- **Payload disturbances, payload rack structural dynamics. - Work requirement definition and verification process.**

**Sustaining Engineering Underway:**

- **Use early on-orbit measurement data to establish confidence in analytical models**
- **Support operations**
- **Perform anomaly resolution**
- **Insure Assembly Complete compliance**



## Acronyms

---

---

- CoFR : Certification of Flight Readiness**
- COF : Columbus Orbital Facility**
- GN&C: Guidance, Navigation, and Control**
- IRD : Interface Requirements Document**
- JEM : Japanese Experiment Module**
- PD : Payload Developer**
- PIA : Payload Integration Agreement**
- PEI : Payload Engineering Integration**
- POIC : Payload Operations Integration Center**
- RS : Russian Segment**
- SSP : Space Station Program**
- USOS: United States On-orbit Segment**