



Section 8

Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms

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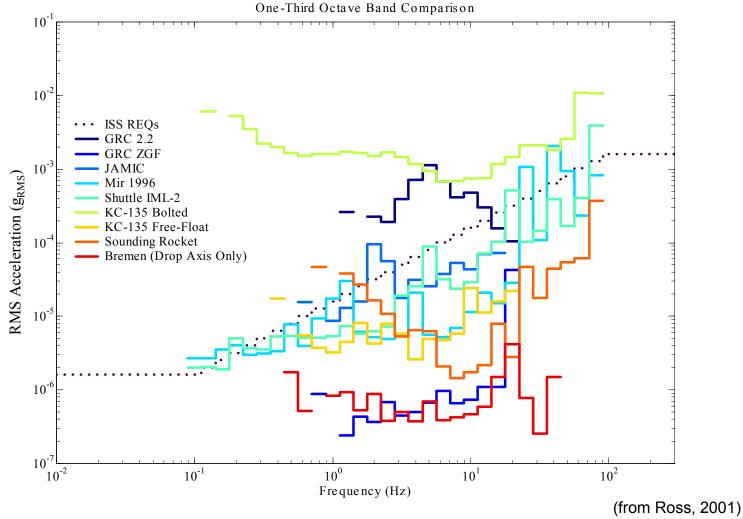
Acceleration measurements for experiments

- Experiments in microgravity are disturbed by accelerations (vibrations or shocks)
- Experiments in ground laboratories are disturbed by accelerations also
 - Gravity
 - Elevator motion
 - Traffic
 - Air conditioning equipment (compressor, fans, etc.)
 - Clumsy lab assistants
- Accelerations should be measured during experiment ground operations - not just during orbital operations





Residual acceleration for various microgravity facilities



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Methods of creating 'zero-g' or microgravity

- Center of Earth's mass $(g_e = 0 m/s^2)$
- Very distant from Earth or other celestial body ($g_e = 10^{-6} \text{ m/s}^2$)
- Free fall
 - Zero horizontal velocity -----> drop tower (g_e = 9.8 m/s²)
 - 400 kph horizontal velocity -----> aircraft (g_e = 9.8 m/s²)
 - 30,000 kph horizontal velocity -----> orbital $(g_e = 9 m/s^2)$
 - Where g_e is the acceleration due to Earth's gravitational pull
- The reduced gravity features comes from free fall, not the absolute reduction or elimination of Earth's gravitational acceleration!





Ground-based facilities with zero horizontal velocity

- Seismic mass / vibration isolation
 - Not free-fall but vibrationally quiet
 - Still 1-g environment
 - Isolated floor mass
 - Vibration isolation platform
- Drop tower
 - Carrier with experiment is dropped
 - May be rather complex experiments
- Drop tube
 - Sample material is dropped
 - Most often sample is molten metal drops



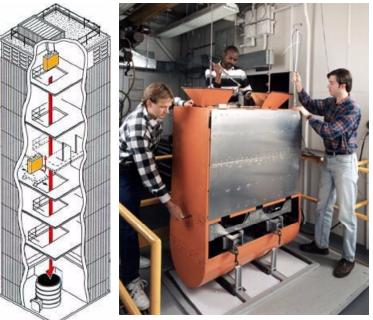


Ground Facilities with zero horizontal velocity



National Aeronautics and Space Administration John H. Glenn Research Center at Lewis Field

Seismic Mass Plum Brook Station Base of huge vacuum chamber (illustrative of method to utilize vibration-quiet laboratory conditions)



2.2 Second Drop Tower NASA Glenn Drag shield being assembled for an experiment drop





SPF Seismic Mass Characterization

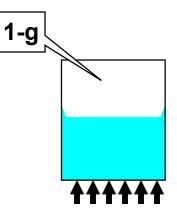
- Figure 8-1 illustrates the conditions existing on a large mass of concrete
 - Concrete foundation of world's largest vacuum chamber
 - The X-axis was vertical
 - a = F/m implies low levels of acceleration with large value of mass with nominal forces from ground and wind

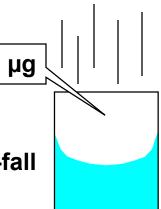




Free-fall vs. 1-g

- 1-g condition
 - Gravity effects are apparent when a retarding force disturbs free fall
 - Beaker exerts a force to stop water from falling
 - Floor exerts a force on people (felt as their weight)
- Microgravity condition in a free fall
 - Gravity effects are not apparent in free fall
 - Beaker falls with the fluid
 - beaker is no longer exerting a retarding force on water
 - sedimentation and buoyancy are reduced
 - surface tension & capillary forces are 'revealed'
 - Acapulco cliff divers feel weightless during their free-fall to the ocean









Drop Towers & Tubes

Drop towers attempt to minimize external forces

- Air drag is a large external force
 - Steady force which gradually increases with increasing velocity

Several mechanisms are used to counteract air drag

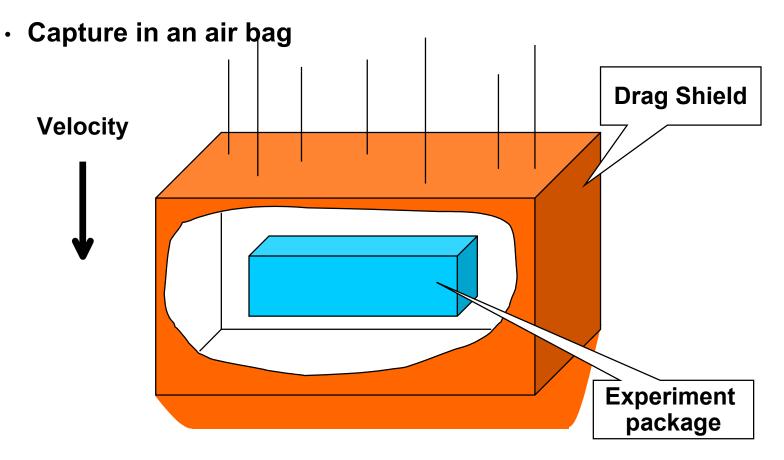
- Drag shield
 - Experiment package surrounded by free falling container
- Vacuum operation
 - Evacuate air from the chamber in which the experiment is dropped
- Drag force compensation
 - Apply compensating force (thrust) to experiment carrier
- Keys for a 'quiet' drop
 - Smooth release mechanism to minimize initial transient vibration
 - Structural relaxation depends on design of carrier and experiment
 - Moving parts dynamically balanced





Drag Shield

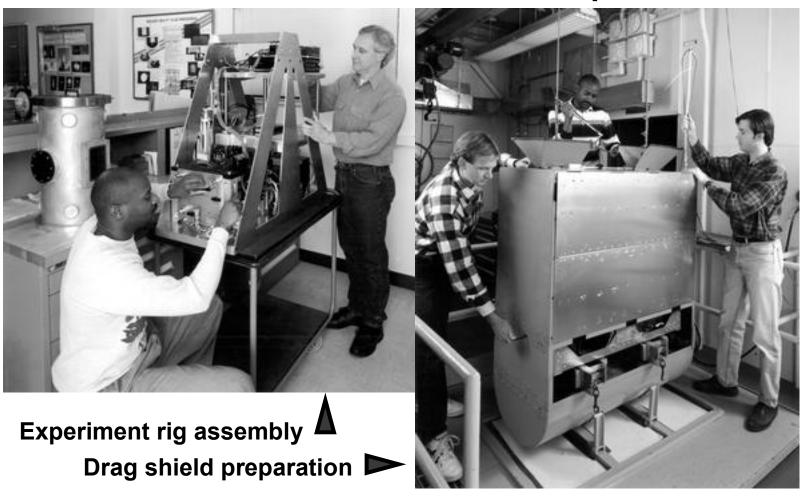
NASA GRC 2.2 Second Drop Tower uses a drag shield







NASA GRC 2.2 Second Drop Tower



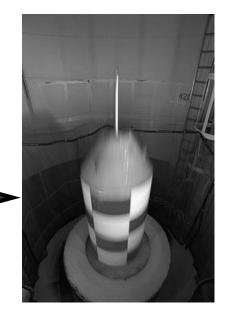
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Vacuum Operation

- Vacuum drop towers include:
 - Zero Gravity Research Facility at NASA GRC
 - Capture in foam pellet container
 - ZARM facility at University of Bremen, Germany
 - Capture in foam pellet container



ZARM tower exterior



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Experiment capture in Zero Gravity Research Facility

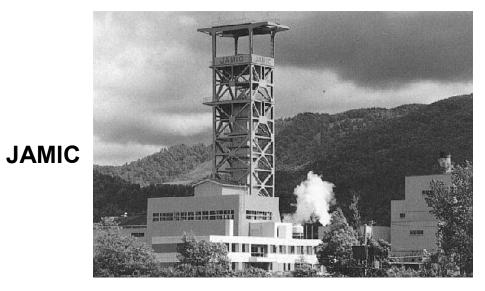
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Drag Force Compensation

- Japan Microgravity Center
 - Inner & outer capsule (i.e. drag shield)
 - Vacuum drawn between inner & outer capsules
 - Acceleration added to outer capsule for drag compensation
 - Cold-gas jet
 - Capture accomplished with air pressure then mechanical brake

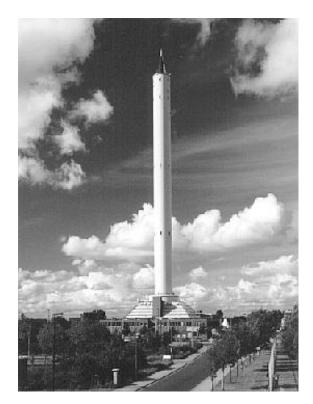






Drop Tower Comparison

• NASA GRC 2.2 S	Second Drop T	ower
 2.2 seconds 	24.1 m	10 ⁻⁴ g
• ZARM Drop Tow	/er	
 4.74 seconds 	123 m	10⁻ ⁵ g
• NASA GRC Zero	o Gravity Resea	arch Facility
 5.18 seconds 	145 m	10⁻⁵ g
• Japan Micrograv	vity Center	
 10 seconds 	490 m	10⁻⁵ g









Acceleration Environment Features of Drop Towers

- Release
 - Step change transition from 1-g to sub-milli-g level
 - Transition occurs over very short time that the mechanism actually releases carrier
- Vibrations from release mechanism
 - The release transition is similar to ringing a bell
 - Step change causes (unwanted) vibration in experiment carrier
 - The 'bell ringing' is damped by carrier and experiment mechanical design
 - May persist for major portion of microgravity time
 - Figure 8-2





Acceleration Environment Features of Drop Towers

- Vibrations from experiment equipment operation, such as:
 - Camera shutters
 - Film transport
 - Solenoid and relay actions
 - Pumps
 - Motor-driven fluid mixers
 - Figure 8-3
- High level of deceleration at capture
 - Levels depend on capture mechanism and final velocity
 - Figures 8-2 and 8-4





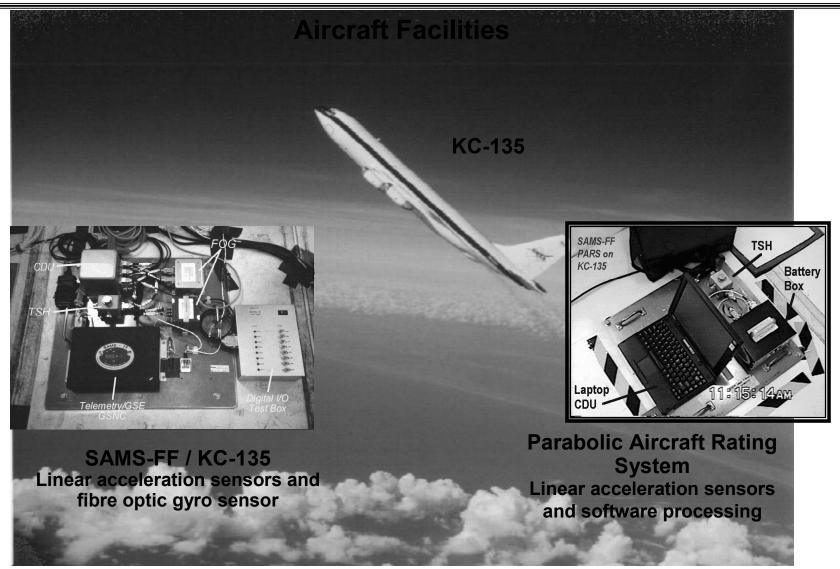
Non-orbital flight platforms

(~ 300 kph horizontal velocity)

- "Parabolic" trajectory
 - In reality, an elliptical path
- KC-135 aircraft (NASA)
 - Operated by NASA Johnson Space Center
 - Each parabola provides 15-20 seconds of reduced gravity environment
 - Periodic free-fall interspersed with high-g pull-out
 - Approximately 40-50 parabolas per flight (campaign)
- Terrier-Black Brant sounding rocket
 - Achieves free-fall conditions on the order of 500 seconds after motor burn-out
 - One of several types of sounding rockets







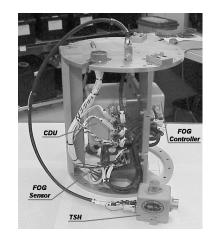
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Sounding Rockets



SAMS-FF / Sounding Rocket Linear acceleration sensors and fiber optic gyro sensor



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KC-135 Environment Characterization

- Figure 8-5 illustrates the KC-135 overall environment over multiple parabolas during a typical campaign
- Figure 8-6 is a detailed plot of the KC-135 environment during the reduced gravity portion of the parabola
- Figure 8-7 is a plot of KC-135 parabola recorded in support of SAL experiment. Shows free-float of SAL test equipment and timelines the activity within the parabola
- Figure 8-8 is a detailed plot of the free-float period of the parabola





Sounding Rocket Environment Characterization

- Terrier-Black sounding rocket DARTFire flight timeline is shown in the graphic in Figure 8-9
- Figure 8-10 illustrates the acceleration vector magnitude for the time period when the sampling rate was 25 samples per second
 - environment measured at less than 30 µg root sum square (RSS) for the time interval analyzed
- Figure 8-11 is the RSS power spectral density for the time period when the sampling rate was 25 samples per second
 - frequency domain characteristics track known disturbance sources originating internal to the DARTFire equipment
 - Intensified Multispectral Imager filter wheel operates at 5 Hz
 - Infrared Imager filter wheel operates at 1 Hz



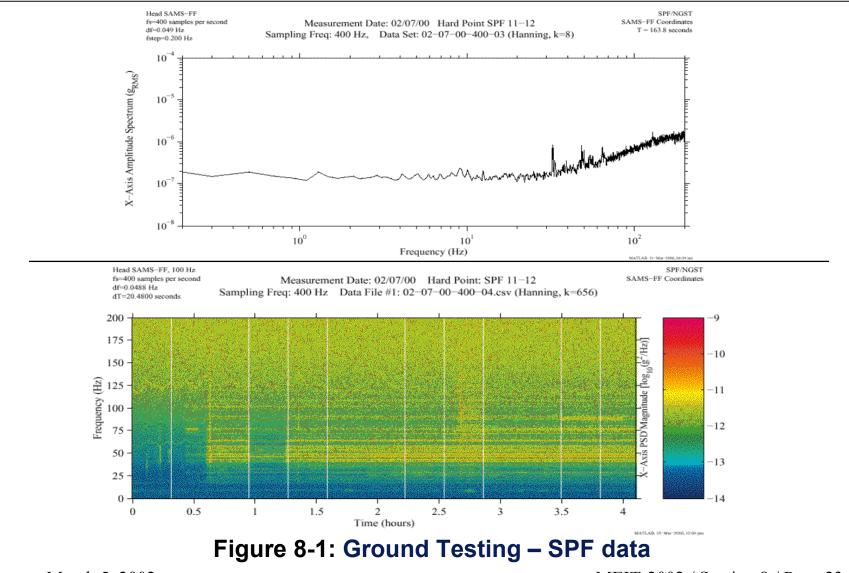


References

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 - http://microgravity.grc.nasa.gov/drop2/
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 - http://www.zarm.uni-bremen.de/main.htm
 - ZARM Drop Tower Bremen Users Manual, Version 28, April 2000
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Data from the vertical axis in NASA GRC 2.2 Second Drop Tower facility.

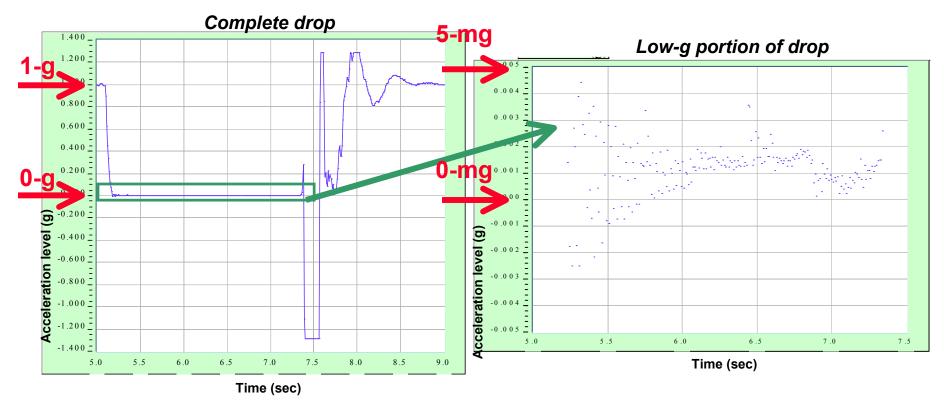


Figure 8-2: Acceleration level for drop tower test





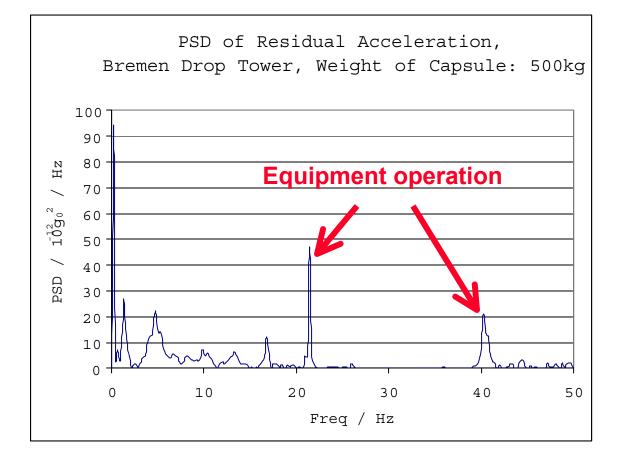


Figure 8-3: Power Spectral Density plot during drop (ZARM) (note: release disturbances not included)





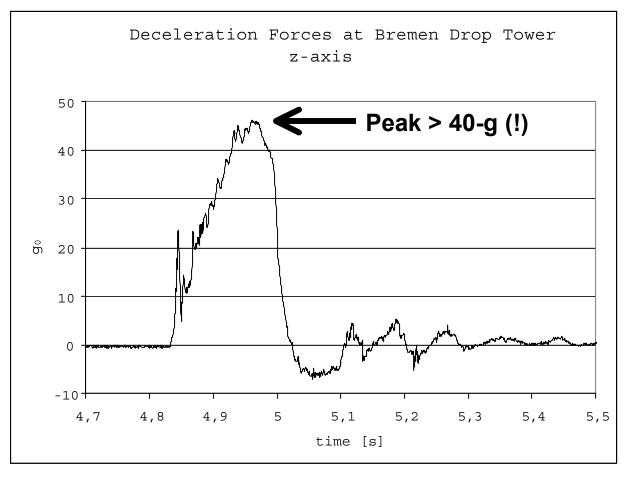
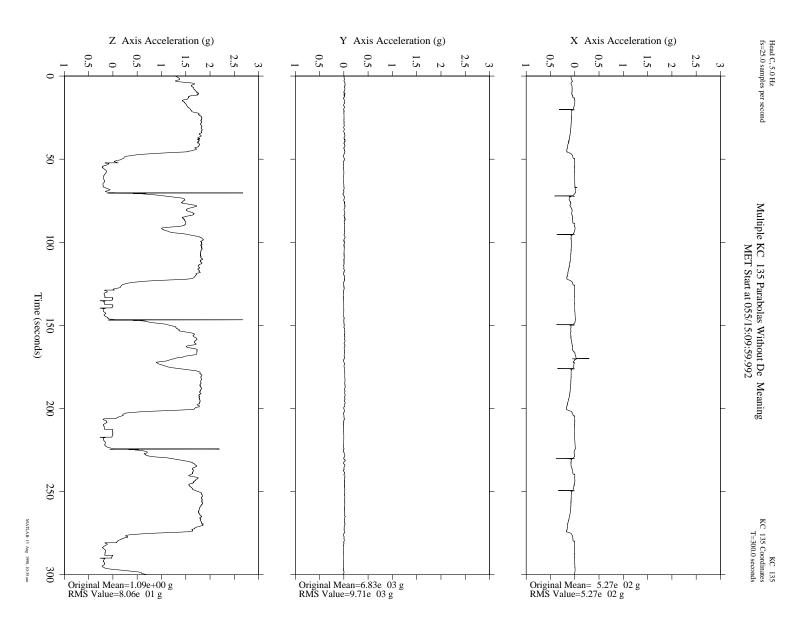
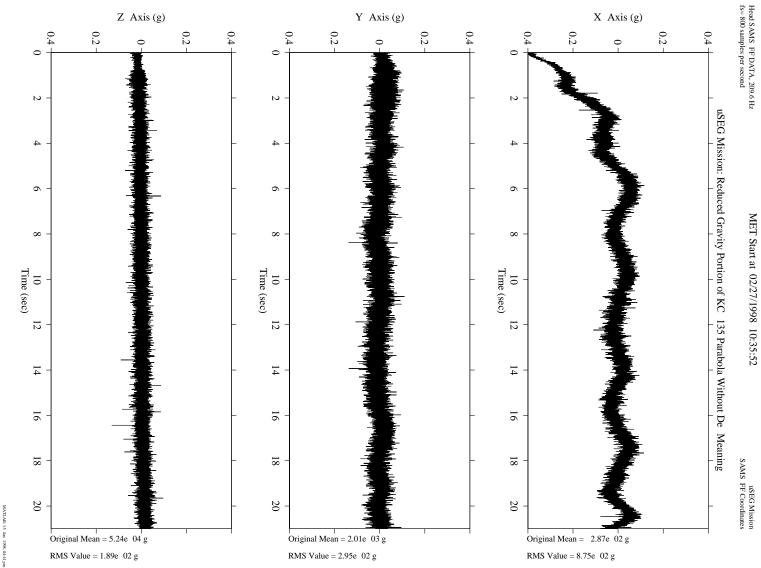


Figure 8-4: Deceleration at capture (ZARM)









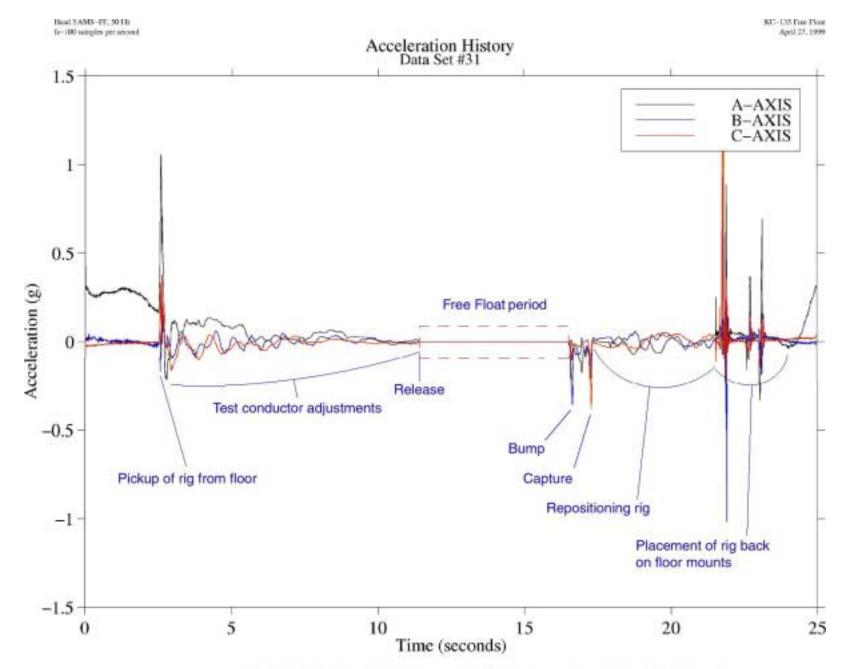


Figure 11-6: SAMS-FF Data Recorded in Support of SAL Experiment Showing Free-Float Interval

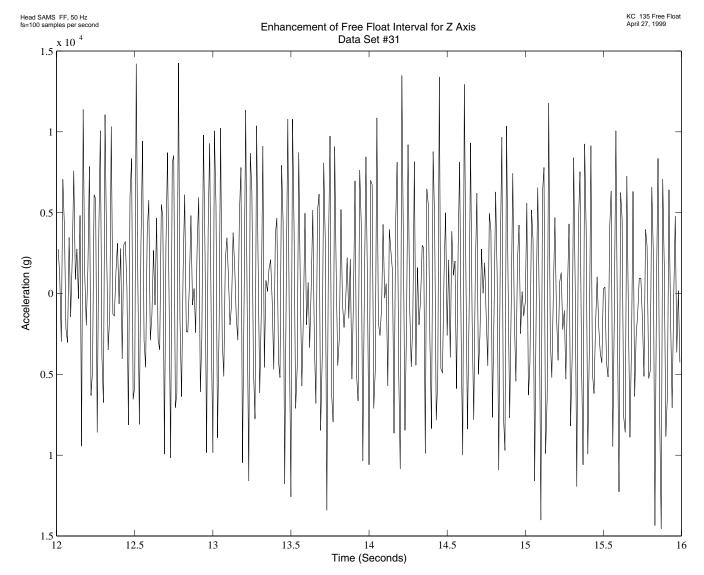
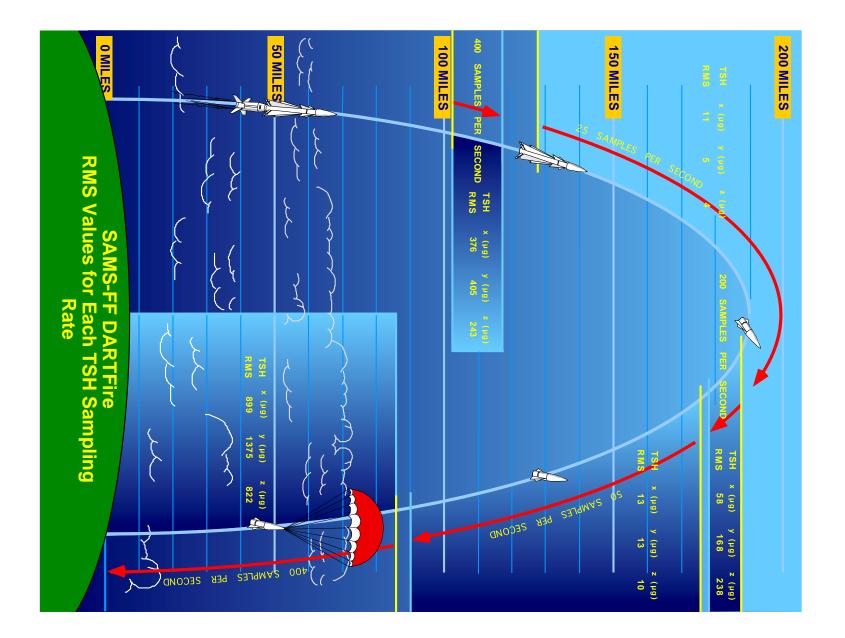
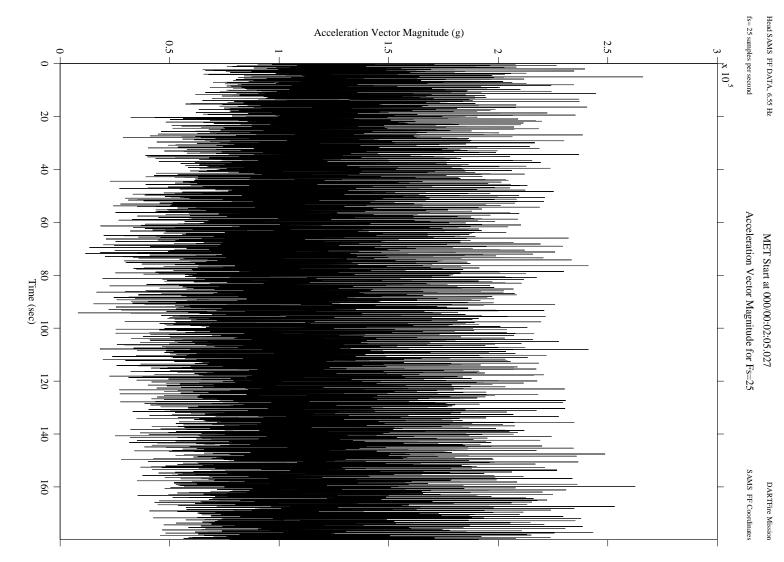


Figure 8 7: Enhancement of the Free Float Period for the Z Axis





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