



# **Section 22**

# International Space Station (ISS) Measured Vibratory Environment

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# **Acronyms & Abbreviations**

	(		2
μg	micro-g, 10 <sup>-o</sup> g (sometimes ug – "you gee")	mg	milli-g, 10 <sup>-3</sup> g
ADVASC	Advanced Astroculture	MSG	Microgravity Science Glovebox
AOS	Acquisition Of Signal	MTL	Medium Temperature Loop
ARIS	Active Rack Isolation System	NASA	National Aeronautics and Space Administration
ATL	Attitude Time Line	OARE	Orbital Acceleration Research Experiment
CCAA	Common Cabin Air Assembly	ORU	Orbital Replacement Unit
CCAA	Common Cabin Air Assembly	OSS	OARE Sensor Subsystem
CDT	Central Daylight Time	ОТО	One-Third Octave
CDT	Central Daylight Time	PAD	PIMS Acceleration Data
СЕТА	Crew and Equipment Translation Assembly	PAO	Public Affairs Office
CEVIS	Cycle Ergometer with Vibration Isolation System	РСМ	Process Chamber Module
CMG	Control Moment Gyro	PCMCIA	Personal Computer Memory Card International Association
DC	Direct Current (mean value)	PCSA	Principal Component Spectral Analysis
EDT	Eastern Daylight Time	PFE	Periodic Fitness Evaluation
ER	EXPRESS Rack	PFMI	Pore Formation and Mobility Investigation
EVA	Extravehicular Activity	PIMS	Principal Investigator Microgravity Services
EXPRESS	Expedite the Processing of Experiments to the Space Station	PSD	Power Spectral Density
FE	Flight Engineer	PuFF	Pulmonary Function in Flight
FGB	Functionalui Germatischeskii Block	RMS	Root-Mean-Square
g	acceleration due to free-fall (9.81 m/s2)	RPM	Revolutions Per Minute
GASMAP	Gas Analysis System for Metabolic Analysis of Physiology	RTS	Remote Triaxial Sensor
GMT	Greenwich Mean Time	SAMS	Space Acceleration Measurement System
GRC	Glenn Research Center	SKV	Russian acronym for Air Conditioner
HiRAP	High Resolution Accelerometer Package	SM	Service Module
HRF	Human Research Facility	SSA	Space Station Analysis
Hz	Hertz	STS	Space Transportation System
ISS	International Space Station	TEA	Torque Equilibrium Attitude
ITSC	Internal Thermal Control System	TeSS	Temporary Sleep Station
JSC	Johnson Space Center	TVIS	Treadmill Vibration Isolation System
LAB	Laboratory	UF	Utilization Flight
LAB101	US LAB Overhead 1	UFO	Unidentified Flying Object
LAB102	US LAB Overhead 2	US	United States
LAB1P3	US LAB Port 3	VELO	Velosiped
LAB1S1. 2. 3	US LAB Starboard 1, 2, 3, respectively	ХРН	X-axis Parallel to angular momentum vector, represented by "h"
LOS	Loss Of Signal	XPOP	X Principal Axis Perpendicular to the Orbit Plane
LTL	Low Temperature Loop	XVV	X body axis toward the Velocity Vector
LVLH	Local Vertical Local Horizontal	vvv	Y-axis toward Velocity Vector
MAMS	Microgravity Acceleration Measurement System	71	Zenith position of Unity (Node 1) module
MEC	Medical Equipment Computer		Z-axis in Local Vertical
MEPS	Microencansulation Electrostatic Processing System	ZNN	Z-axis toward Nadir when station at orbital Noon in 12000 frame





# Outline

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Source Title Goes Here Qualify

Representative figure or plot usually goes in this box.

- To qualify, we typically use a spectrogram.
- Not intended to completely characterize a particular disturbance, but rather to show typical or nominal operation.

# Data DescriptionSensoridentifier<br/>sample rate (cutoff frequency)Locationof sensorInc/FlightIncrement #, Flight #Plot Typespectrogram or ...

#### Notes:

The text in this box serves to qualify the disturbance source under consideration. It might, for instance, describe some of the structures and boundaries observed in both time and frequency.

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Regime:	Vibratory	
Category:	Crew or Vehicle or Equipment	
Source:	Source Title Goes Here Too	



Source Title Goes Here Quantify

# Representative figure or plot usually goes in this box.

- To quantify, we typically use RMS values & may use peak values for transient events.
- Sometimes, handbook pages show no discernible effect.

Data Description	
Sensor	identifier sample rate (cutoff frequency)
Location	of sensor
Inc/Flight Increment #, Flight #	
Plot Type	interval RMS or

#### Notes:

The text in this box serves to quantify the disturbance source under consideration. It might, for instance, show how the RMS value over a narrow band of frequencies varies with time as a disturbance source turns on/off.

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Actinal INVESTIGATOR MICROGRAVITY SEAT	



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Regime:	Vibratory
Category:	Crew or Vehicle or Equipment
Source:	Source Title Goes Here Too



Date last modified 6/4/03

Unidentified "Swoosh"





<b>Data Description</b>		
Sensor	121f02 250.0 sa/sec (100.00 Hz)	
Location	LAB1O2, ER1, Drawer 1	
Inc/Flight	Increment: 4, Flight: 8A	
Plot Type	spectrogram	

#### Notes:

- This Russian air conditioner is part of the Environmental Control and Life Support System (ECLSS).
- As part of preparation for an ExtraVehicular Activity (EVA), the crew will move ducting in order to work with hatches. It has been noted that this is accompanied by a temporary deactivation of the air conditioner.
- Nominally one SKV is operating, but there are times when both SKV-1 and SKV-2 are on.
- The nearly continuous operation of this equipment produces a narrowband disturbance near 23.5 Hz. This spectral peak serves as vibratory beacon signal.

Regime:	Vibratory
Category:	Vehicle
Source:	SKV Air Conditioner
	·



Data Description		
Sensor	121f02 250.0 sa/sec (100.00 Hz)	
Location	LAB1O2, ER1, Drawer 1	
Inc/Flight	Increment: 4, Flight: 8A	
Plot Type	interval RMS	

#### Notes:

For the 8-hour period shown in the figure, Parseval's theorem was used to derive the RMS acceleration level for a narrow band around the SKV air conditioner's operating frequency. The results for the frequency band from 23 to 24 Hz is tabulated below:

4	SKV	GMT	Median (µg <sub>RMS</sub> )	
	ON	08:00 - 11:00	55.4	
Ĺ	OFF	11:00 - 13:28	6.8	
7	ON	13:28 - 16:00	91.2	
15				

Regime:	Vibratory		
Category:	Vehicle		
Source:	SKV Air Conditioner		



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Regime:	Vibratory	1
Category:	Crew Activity	
Source:	Resistive Exercise Device (RED)	

**Data Description** 

250.0 sa/sec (100.00 Hz)

LAB1O2, ER1, Drawer 1

Increment: 5, Flight: UF2

121f02

spectrogram



Source:

Resistive Exercise Device (RED)

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#### Common Cabin Air Assembly (CCAA) Qualify





Regime:	Vibratory
Category:	Vehicle
Source:	Common Cabin Air Assembly (CCAA)

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# Common Cabin Air Assembly (CCAA) Quantify



Sum Hanning, k = 9783 Span = 24.00 hours

Data Description		
Sensor	121f03 500.0 sa/sec (200.00 Hz)	
Location	LAB101, ER2, Lower Z Panel	
Inc/Flight	Increment: 6, Flight: 11A	
Plot Type	interval RMS	

#### Notes:

In order to quantify the port CCAA (LAB1P6) shutdown event, the interval RMS curves for the 24-hours shown in this figure were computed. These curves show that the higher frequency (red trace) water separator transitioned from nominal RMS values of about 268.3  $\mu$ g<sub>RMS</sub> to about 152  $\mu$ g<sub>RMS</sub> during dry-out before returning this narrow portion of the spectrum to a baseline of about 34  $\mu$ g<sub>RMS</sub> during nominal operated between about 413  $\mu$ g<sub>RMS</sub> during nominal operation up to 550  $\mu$ g<sub>RMS</sub> before its step down to a lower frequency for dry-out. Note that the lower frequency operation of the inlet fan was not quantified due to its proximity to another strong, narrowband signal just above its operational rate.



Category:	Vehicle
Source:	Common Cabin Air Assembly (CCAA)

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**ADVanced AStroCulture (ADVASC) Experiment Equipment** 

# Data DescriptionSensorHiRAP<br/>1000.0 sa/sec (100.00 Hz)LocationLAB102, ER1, Lockers 3,4Inc/FlightIncrement: 2, Flight: 6APlot Typespectrogram



• ADVASC experiment equipment<sup>\*</sup>:

• **pump** – narrowband signal centered at about 53.5 Hz

• **2 fans** – narrowband signals centered at about 48 and 88 Hz.

• 2 blowers – broadband signals centered at about 72 and 78 Hz

\* as confirmed by ADVASC team at University of Wisconsin

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Regime:	Vibratory		
Category:	Experiment Equipment		
Source:	ADVanced AStroCulture (ADVASC)		

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Data Description		
Sensor	HiRAP 1000.0 sa/sec (100.00 Hz)	
Location	LAB1O2, ER1, Lockers 3,4	
Inc/Flight	Increment: 2, Flight: 6A	
Plot Type	spectrogram	

Notes:

Frequency (Hz)				RMS Acceleration (µg <sub>RMS</sub> )		
HiRAP Measured		Exported	Disturbance	ADVASC	ADVASC	
Center	Range	Expected		ON	OFF	
49.4	49.1 - 49.7	48.3	2,900 RPM fan	41.6	19.0	
57.6	57.3 - 57.9	52 - 55	air pump	568.9	31.4	
69.5	68.1 - 70.9	71.7	4,300 RPM blower	512.9	97.4	
76.5	73.0 - 79.7	78.3	4,700 RPM blower	940.9	86.9	
88.0	87.6 - 88.4	88.3	5,300 RPM CPU fan	284.3	32.8	
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Regime:	Vibratory
Category:	Experiment Equipment
Source:	ADVanced AStroCulture (ADVASC)

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# Gas Analysis System for Metabolic Analysis of Physiology (GASMAP) Qualify

Sensor121f02<br/>500.0 sa/sec (200.00 Hz)LocationLAB1O2, ER1, Drawer 1Inc/FlightIncrement: 4, Flight: UF1Plot Typespectrogram

**Data Description** 

#### Notes:

The GASMAP device is used to monitor and analyze both inhaled and exhaled breath streams to determine their gas concentrations. Two GASMAP signatures are noted in the figure near 60 Hz: a sample pump and a fan. This equipment is located in the HRF rack #1 (LAB1S2) and used for the Pulmonary Function in Flight (PuFF) experiment, which studies effects of extravehicular activity (EVA) and long-term exposure to microgravity on the pulmonary function. As discussed with payload developers, the frequency changes away from nominal operation are likely a function of varying loads on the sample pump. The pump frequency ranged from 54 Hz (for brief calibrations) up to 62 Hz after the second PuFF run. The fan is tightly controlled in frequency but also transitions from baseline of about 57.4 Hz up to 58.1 Hz noted during calibrations.

Regime:	Vibratory
Category:	Experiment Equipment
Source:	GASMAP

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Gas Analysis System for Metabolic Analysis of Physiology (GASMAP) Ouantify		Data Description					
	Zuuung			Sens	or 121f02 500.0 sa/se	ec (200.00	) Hz)
				Locati	on LAB1O2,	ER1, Dra	wer 1
				Inc/Flig	ht Increment:	4, Flight	: UF1
sams2, 121102 at LAB1O2, ER1, Drawer 1:[128.73 -23.53 144.15] 500.0 sa/sec (200.00 Hz) Af = 0.122 Hz, NfH = 4096 SAMS 121f02 (Dra Temp. Res. = 8.192 sec, No = 0 GASMAP Sample Pump	wer 1, ER1, I 250.0 sa/sec (100.00 Hz)	SAMS 121f0 SAMS 121f0 GASMAP Sampl	<mark>3 (Z-panel, ER2, LAB101)</mark> 4 (Z-panel, ER1, LAB102) e Pump (58.2 < f < 61.2 Hz	Plot Ty	pe interval RN	MS	
0.4	0.4						
0.35 -	0.35 -	Sensor	Sensor Location	GASMAP Equipment	Frequency Range (Hz)	State	RMS Acceleration (ug <sub>RMS</sub> )
0.3 -	0.3 -	121f02	LAB1O2, ER1, Drawer 1			OFF ON	24 >200
	~	121f03	LAB1O1, ER2, Lower Z Panel	SAMPLE PUMP	58.2 – 61.2	OFF ON	91 >115
<sup>2</sup> 20.25 −	\$0.25 -	121f04	LAB1O2, ER1, Lower Z Panel			OFF ON	70 >115
		121f02	LAB1O2, ER1, Drawer 1	FAN	57.2 – 57.6	OFF ON	8 19
SE 0.15 0.1	0.15 0.15 0.1 0.1 0.1 0.1 0.1 0.1 0.1 0.1 0.1 0.1	00 19:00 GMT 26–J	20:00 21:00 22:00 anuary-2002, 026/hh:mm rever Lipsbards, Share				
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		MFIT-200	4/Section 22/Page 19	Regim	ie: Vibratory		
	PIMS ISS Acceleration Handbook Date last modified 10/2/02			Catego	ry: Experimen	t Equipmo	ent
					Source: GASMAP		



# Microencapsulation Electrostatic Processing System (MEPS) Qualify



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<b>Data Description</b>		
Sensor	121f02 250.0 sa/sec (100.00 Hz)	
Location	LAB1O2, ER1, Drawer 1	
Inc/Flight	Increment: 5, Flight: UF2	
Plot Type	spectrogram	

# Notes:

The MEPS is located in locker #8 of ER1 (LAB1O2) near the 121f02 sensor in RTS drawer 1. This 24-hour spectrogram readily shows 5 MEPS sample runs with the start/stop delimited by 2 narrowband signals. The weaker of these was centered at 47.1 Hz and the stronger at 52.8 Hz. Note that each of the 5 runs is preceded by the impulsive events of Process Chamber Module (PCM) insertion.

Regime:	Vibratory		
Category:	Experiment Equipment		
Source:	MEPS		

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Source:

MEPS

#### **Cycle Ergometer with Vibration Isolation System (CEVIS) QUALIFY**



Data Description		
Sensor	121f05 62.5 sa/sec (25.00 Hz)	
Location	LAB1O1, ER2, Light Tray	
Inc/Flight	Increment: 4, Flight: UF1	
Plot Type	spectrogram	

#### Notes:

The CEVIS exercise device is located in the US Lab at LAB1P3. The narrowband peak at about 2.5 Hz marked on the lower right of the spectrogram is the pedaling frequency for this CEVIS exercise period. For Shuttle ergometer exercise, the pedaling signature was accompanied by that of shoulder sway with frequency around half the pedal rate. On the ISS for this CEVIS exercise period, the shoulder sway signature is obscured by structural modes that fall in the same frequency range.

Regime:	Vibratory
Category:	Crew
Source:	Cycle Ergometer with Vibration Isolation System (CEVIS)

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#### Cycle Ergometer with Vibration Isolation System (CEVIS) **QUANTIFY**



**Data Description** see upper left of figure Sensor see upper left of figure Increment: 4, Flight: UF1 cumulative RMS

To quantify the impact of a CEVIS exercise period from four sensor locations, the cumulative RMS acceleration versus frequency curves shown in the figure were computed. The legend at the upper left shows which trace was computed for each of the different sensors. The curves in this figure all step up about 70  $ug_{RMS}$  at the pedaling frequency, but vary to some degree across the rest of the acceleration spectrum below 10 Hz. The variability is expected as the SAMS sensors used for the analysis were distributed throughout ER1 and ER2 as indicated by the legend.

# Sleep/Wake **QUALIFY**



**Data Description** 121f03 Sensor 62.5 sa/sec (25.00 Hz) Location LAB101, ER2, Lower Z Panel Inc/Flight Increment: 5, Flight: UF2 Plot Type spectrogram

#### Notes:

Sum

-6

-7

-8

-9

-10

-11

-12

This figure shows 3 sleep periods over a 64-hour span. The impact of crew wake periods relative to sleep is primarily below about 6 Hz. This is seen as a shift toward the blue end of the PSD magnitude color scale below about 6 Hz during the 3 sleep periods. The transition from sleep to wake is typically a sudden event owing to a wake alarm, while the transition from wake to sleep is gradual as might be expected. Signatures for both Russian air conditioners (SKV-1 and SKV-2) are also seen here toward the top of this figure at about 23.3 Hz. The slightly lower frequency and more intense SKV is on for this entire 64-hour duration, while the other one starts just after the end of the  $2^{nd}$ sleep period.



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# Sleep/Wake QUANTIFY



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**Data Description** 

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# Velosiped (Velo) Exercise QUALIFY



**Data Description** 

### Velosiped (Velo) Exercise QUANTIFY



**Data Description** 

# **Shuttle Docking QUALIFY**









Sum

-6

-7

-8

-9

-10

-11

-12

1.50	
Regime:	Vibratory
Category:	Vehicle
Source:	Shuttle Docking

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#### Shuttle Docking QUANTIFY



**Data Description** 

## **Control Moment Gyroscope (CMG) QUALIFY**



Data Description		
Sensor	121f03 500.0 sa/sec (200.00 Hz)	
Location	LAB101, ER2, Lower Z Panel	
Inc/Flight	Increment: 5, Flight: UF2	
Plot Type	PCSA	

#### Notes:

There are 4 control moment gyroscopes (CMGs) located on the Z1 truss structure (currently, only 3 are operational). These rotate at 6,600 revolutions per minute (RPM) within 1 RPM (1/60 Hz) to provide non-propulsive attitude control for the space station. The principal component spectral analysis (PCSA) plot at the left summarizes the acceleration spectrum for a 3-day span. As seen by the narrow spectral peak at 110 Hz, these gyros are tightly controlled in frequency.

0.5

Sum

1.5

Regime:	Vibratory
Category:	Vehicle
Source:	Control Moment Gyroscope (CMG)

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#### **Control Moment Gyroscope (CMG) Data Description OUANTIFY** 121f03 Sensor 500.0 sa/sec (200.00 Hz) sams2, 121f03 at LAB1O1, ER2, Lower Z Panel:[191.54 -40.54 135.25] Increment: 5, Flight: UF2 500.0 sa/sec (200.00 Hz) $\Delta f = 0.122$ Hz, Nfft = 4096 CMGs, 109.983 < f < 110.017 Hz Sum Hanning, k = 31141 Location LAB101, ER2, Lower Z Panel Temp. Res. = 8.192 sec, No = 0 Start GMT 05-October-2002, 278/00:00:00 Span = 72.00 hours 1500 Inc/Flight Increment: 5, Flight: UF2 Plot Type interval RMS 1381 Notes: 1274 The plot shows interval RMS values during a 3day period for a narrow frequency band (109.983 to 110.071 Hz) around the CMG operating frequency (110 Hz). Statistics gathered for this time frame show: 95<sup>th</sup> percentile: 94.9 $\mu g_{RMS}$ RMS Acceleration ( $\mu g_{RMS}$ ) 963 median: $47.7 \,\mu g_{RMS}$ $50.9 \ \mu g_{RMS}$ mean: This plot also shows that this small frequency band will also register much higher RMS levels not necessarily attributable to nominal operation of the 647 CMGs. 364 150 100 50 00:00 04:00 08:00 12:00 16:00 20:00 00:00 04:00 08:00 12:00 16:00 20:00 00:00 04:00 08:00 12:00 16:00 20:00 00:00 GMT 05-October-2002, 278/hh:mm from: t:\publpad, \$Name: pop3\_06-17-2002 \$, 24-Jun-2002,06:19:13.602 Vibratory Regime: Category: Vehicle

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**Control Moment Gyroscope** 

Source:

(CMG)

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Data Description		
Sensor	SAMS 121f04 10.0 sa/sec (1.00 Hz)	
Location	LAB1O2, ER1, Lower Z Panel	
Inc/Flight	Increment: 6, Flight: 11A	
Plot Type		

During the extravehicular activity (EVA) on GMT 08-April-2003, the Expedition 6 crew successfully freed the light stanchion of the S1 crew and equipment translation assembly (CETA) railcart. This stanchion had remained stuck after an aborted light installation during the first stage EVA and had to be removed by tapping it 11 times with a Russian hammer. Predictions indicated that these hammer blows might impart significant transient







Regime:	Vibratory
Category:	Crew
Source:	Hammer Taps During EVA

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#### Hand Posture Analyzer (HPA) Qualify



Data Description		
Sensor	SAMS 121f02 250.0 sa/sec (10.0 Hz)	
Location	LAB1O2, ER1, ER1 Drawer 1	
Inc/Flight	Increment: 7 Flight: 6S	
Plot Type	spectrogram	

#### Notes:

According to the on-orbit satus report for GMT 17-Sep-2003, "Ed Lu performed the Hand Posture Analyzer (HPA) experiment for the first time, using the posture acquisition glove (PGA). Since it has delicate sensors attached to the tops of the fingers, pressure should only be applied to the "palm side" while donning and doffing. The research objective of the ASI/Italy (Kayser Co.) designed HPA is to investigate the performance degradation of the human upper limb muscle-skeletal apparatus and its morphological-functional modifications during long term exposition to zero-G and to study the role of gravity in the planning and execution hierarchy of reaching, grasping, manipulating and transporting objects. The HPA facility consists of a Hand Grip Dynamometer (HGD), a Pinch Force Dynamometer (PFD), the instrumented PAG with 15 degrees of freedom, allowing the measurement of the bending angles on individual phalanxes, coupled to a Wrist Electronic Box (WEB) housing an inertial tracking system in order to acquire tri-axial acceleration and rotation of the forearm." No positive identification of these equipment manifest in the vibratory acceleration data collected in the US Lab has been made yet. This figure (particularly the inset), however, shows a distinct signal near the end of the scheduled time for these operations. The signal ramped from 7.8 to 9.5 Hz between 14:20 and 14:33 as annotated in this figure. The vertical red hash at 14:41 marks a relatively strong transient near the end of scheduled operations.

Regime:	Vibratory
Category:	Crew
Source:	Hand Posture Analyzer (HPA)

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### Advanced Thermoelectric Refrigerator/Freezer/Incubator (ARCTIC) Qualify



ARCTIC freezer installed in EXPRESS Rack 4 following arrival on STS-110 (photographed April 17, 2002).





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**Data Description** Sensor Location Inc/Flight Plot Type

#### Notes:

The Advanced Thermoelectric Refrigerator/Freezer/Incubator (ARCTIC) is used for storing biological samples in a thermallycontrolled environment on the International Space Station before they are returned to Earth for scientific analyses. The ARCTIC can also be used for storing perishable items and reagents. The ARCTIC freezer is a thermoelectric device that requires continuous and auxiliary power. It receives water and air cooling from the EXPRESS rack. ARCTIC 1 and 2 are scheduled to remain on Station and will only be powered up when needed. The crew will activate the freezers, insert and remove samples as needed, and perform weekly system health checks. Correspondence with hardware developers indicate that this thermoelectric device has no moving parts, so that nominal operation does not introduce any acceleration disturbance. Examination of SAMS data during activation and deactivation times for the ARCTIC support this assertion.

Regime:	Vibratory
Category:	Experiment Equipment
Source:	Advanced Thermoelectric Refrigerator/Freezer/Incubator (ARCTIC)



Research Center	

# Crew Pushoff/Landing Qualify



Data Description	
Sensor MAMS HiRAP 100.0 sa/sec (1000.00 Hz)	
Location	LAB1O2, ER1, Lockers 3,4
Inc/Flight	Increment: 7 Flight: 6S
Plot Type	

#### Notes:

In support of an experiment called Pore Formation and Mobility Investigation (PFMI), Ed Lu took about 7 minutes to perform several push/pulls at the MSG handrail along with pushoffs and landings near the Microgravity Science Glovebox (MSG). The objective was to ascertain the ability of the MAMS HiRAP sensor in ER1 (LAB1O2) to detect accelerations that might affect the PFMI and other experiments in the MSG. The handrail used for the push/pull test is just forward of the MSG location in LAB1S3, while the pushoffs and landings were primarily between deck and overhead racks near the MSG (between LAB1D2 and LAB1O2). The figure shown here is a screenshot of video obtained from the JSC that shows the complete test by Expedition 7 crew member, Ed Lu.



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Regime:	Vibratory
Category:	Crew
Source:	Pushoff/Landing

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Data Description	
Sensor	MAMS HiRAP 100.0 sa/sec (1000.00 Hz)
Location	LAB1O2, ER1, Lockers 3,4
Inc/Flight	Increment: 7 Flight: 6S
Plot Type	time series

#### Notes:

These tests performed by Ed Lu consisted of 20 push/pulls at the MSG handrail starting at about GMT 15-Aug-03, 227/09:03:11 (this time was MAMS recorded GMT, which was ahead of expected GMT by about 50 seconds). The peak acceleration vector magnitude was about 5 mg for the handrail push/pulls, while the set of 3 pushoff/landings that started at about GMT 15-Aug-03, 227/09:04:54 had a peak magnitude of just over 8 mg. This large transient came at GMT 15-Aug-03, 227/09:05:25. Close examination of the  $Z_A$ -axis data shows that pushoff/landing type of impacts tends to excite a structural mode at about 7.5 Hz. This resonance continues noticeably for a couple of seconds or so before subsiding. The PIMS team at the NASA GRC has archived a copy of the video that was shot for this test.

Regime:	Vibratory
Category:	Crew
Source:	Pushoff/Landing

#### Public Affairs Office (PAO) Event QUALIFY



Data Description	
Sensor	121f02 250.0 sa/sec (100.00 Hz)
Location	LAB1O2, ER1, Drawer 1
Inc/Flight	Increment: 5, Flight: UF2
Plot Type	spectrogram

#### Notes:

For a microgravity environment that mimics crew sleep, one can consider PAO events that occupy the entire crew (note that some PAO events occupy only part of the crew). These events typically last at least 10 minutes or so with the crew gathered in front of a video camera participating in an interview. During this time the crew is usually quite still, but there are times when they demonstrate various things that require them to push-off or otherwise apply a force to vehicle structure. The figure here shows the subtle contrast between nominal activity and all 3 crew participating in a PAO event from about 14:45 to about 15:00. Like crew sleep the difference lies primarily below about 6 Hz.

Regime:	Vibratory
Category:	Crew
Source:	Public Affairs Office (PAO) Event

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#### Public Affairs Office (PAO) Event QUANTIFY



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**Data Description** 

#### Crew Pushoff/Landing During Public Affairs Office (PAO) Event Qualify

Data Description	
Sensor	
Location	
Inc/Flight	Increment: 7 Flight: 6S
Plot Type	

#### Notes:

In support of public outreach, Ed Lu and Yuri Malenchenko performed a Public Affairs Office (PAO) interview with KCAU-TV in Sioux City, Iowa. Upon request as part of the interview, Malenchenko performed a reduced-gravity demonstration for students in the audience. The snapshots at the left were taken from video recorded during this demonstration. The PAO event took place from GMT 11-Sep-03, 254/14:11:23 to 14:29:06. The field of view for the video was looking aft in the US Lab. SAMS sensors located in overhead racks toward the front of the US Lab recorded the accelerations experienced at those locations during this crew pushoff event. The PIMS console log maintained during this event showed this entry for the event: "In response to request from school student, at GMT 11-Sep-03, 254/14:26:16, Yuri pushed off deck with both legs and landed on ceiling (just aft of MSG), then pushed off ceiling back to deck all within a second or so."



Leftmost frame shows that at GMT 11-Sep-03, 254/14:26:16, Yuri pushed off deck to start demonstration for students.





- NASA

1604	
Regime:	Vibratory
Category:	Crew
Source:	Pushoff/Landing

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#### Notes:

The table below shows the maximum acceleration magnitude around the time of this event for all 4 active SAMS sensors. All sensors exhibit the lag cited in the figure shown for 121f02.

SENSOR	LOCATION	MAX (mg)
121f02 (100 Hz)	LAB1O2, ER1, Drawer 1	4.29
121f03 (200 Hz)	LAB1O1, ER2, Lower Z Panel	11.90
121f04 (200 Hz)	LAB1O2, ER1, Lower Z Panel	12.87
121f05 <sup>*</sup> (100 Hz)	LAB1O1, ER2, Upper Z Panel	5.57

\* The 121f05 sensor had a transient at same time as other sensors as shown in table, but this was not it's max for the event. It registered 10.39 mg at about GMT 11-Sep-2003, 14:26:31.

Regime:	Vibratory
Category:	Crew
Source:	Pushoff/Landing

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14:25:28

14:25:40

14:25:52

14:26:04

1

0.5

0

14:25:16

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14:26:16

GMT 11-September-2003, 254/hh:mm:ss

14:26:28

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from: t:\pu

14:27:04

14:27:16

003.07:24:57.085

14:26:40

14:26:52

#### SAMS Filter Cleaning Qualify



Data Description	
Sensor	MAMS HiRAP 100.0 sa/sec (1000.00 Hz)
Location	LAB1O2, ER1, Lockers 3,4
Inc/Flight	Increment: 7 Flight: 6S
Plot Type	

Periodic SAMS drawer filter cleanings are required for maintenance and to help ensure ongoing vibratory acceleration measurement and data collection. During this activity, the normal course of events is as follows:

- ground command powers off all 3 drawers
- crew cleans filters on all 3 drawers during the same session by pulling each drawer out 5 or 8 inches and removing any debris with gray tape or the vacuum
- crew reinserts drawers and mates any cables that may have needed to be moved
- crew powers up interim control unit and laptop
- ground powers on RTS drawers

Since SAMS was powered off for this cleaning, the event had to be characterized by another accelerometer system. In this case, MAMS HiRAP was used.



Regime:	Transient
Category:	Crew
Source:	SAMS Filter Cleaning

#### SAMS Filter Cleaning Quantify

mams, hirap at LAB1O2, ER1, Lockers 3,4:[138.68 –16.18 142.35] 10.0000 sa/sec (100.00 Hz)

SAMS Filter Cleaning

Increment: 7, Flight: 6S SSAnalysis[ 0.0 0.0 0.0] Interval Minmax Size: 0.10, Step: 0.10 sec.



Data DescriptionSensorMAMS HiRAP<br/>100.0 sa/sec (1000.00 Hz)LocationLAB1O2, ER1, Lockers 3,4Inc/FlightIncrement: 7 Flight: 6SPlot Typeinterval min/max

In order to perform SAMS filter cleanings, the crew can potentially introduce large transients into the acceleration environment. These impulsive accelerations take place over about 10 minutes, which is the nominal span of time required to do this maintenance. The 0.1-second interval min/max figure shown here was computed from MAMS HiRAP measurements made in the same rack (ER1) as the drawers that contain the SAMS filters. As a result, the accelerations recorded there were expectedly high. In fact, the MAMS HiRAP sensor was saturated at 16 mg (per-axis) and therefore acceleration vector magnitude excursions were greater than 27 mg. The dynamic range of the HiRAP sensors prohibited detection of how much above 27 mg those impulses actually were. Maintenance such as this SAMS filter cleaning can be coordinated with payload planners in an effort to mitigate the impact on nearby investigations.

Regime:	Transient
Category:	Crew
Source:	SAMS Filter Cleaning

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#### **Periodic Fitness Evaluation (PFE) Ouantify**



Data Description		
Sensor	121f04 500.0 sa/sec (200.00 Hz)	
Location	LAB1O2, ER1, Lower Z Panel	
Inc/Flight	Increment: 6, Flight: 11A	
Plot Type	Interval RMS	

#### Notes:

sum

While the interval RMS plot for the 121f02 sensor (located inside drawer 1 of ER1) showed a prominent signature for PFE activity, this same analysis performed for the 121f04 sensor (located on the Z panel of the same rack, ER1) does not show any discernible shift up from the baseline RMS level. The same period that showed this upward shift in the 121f02 data is again marked by a red box here. The median RMS level calculated for the entire 8-hour period period shown in the interval RMS plot at the left was  $63.6 \,\mu g_{RMS}$ . Recall for the 121f02 sensor data, that the baseline was 13.5  $\mu$ g<sub>RMS</sub> when the PFE equipment was off, and 49.6  $\mu g_{RMS}$  when the equipment was on. This disturbance is effectively overwhelmed by the ambient environment and not readily detected at this Z panel location. We cannot say that it is not transmitted to this location, it's just that we cannot detect it against the background vibrations here.

Regime:	Vibratory
Category:	Crew
Source:	Periodic Fitness Evaluation (PFE)

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**Data Description** 121f02 Sensor 250.0 sa/sec (100.0 Hz) Location LAB102, ER1, Drawer 1 Increment: 7, Flight: 6S Inc/Flight Plot Type spectrogram Notes: For crew activity that involves the medical equipment computer (MEC), a narrowband signature similar to the start-up of signature observed for the Periodic Fitness Evaluation (PFE) activity is observable in vibratory data collected by

SAMS 121f02 and MAMS HiRAP sensors. The 121f02 spectrogram at the left has this brief signature surrounded by a black box. The specific example of this signature shown in this box lasts slightly less than 8 minutes and climbs from 59.5 to 70.4 Hz. This is brief example is representative of the MEC operations, although sometimes this narrowband disturbance persists for a long span, while presumably the crew is tending to other tasks.

Regime:	Vibratory
Category:	Equipment
Source:	Medical Equipment Computer (MEC)

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